

*Dedicated to the 35<sup>th</sup> anniversary of the University of Baia Mare*

**The  $SO_q(N)$ -approach to the  $q$ -deformation  
of the free-particle description**

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**Abstract**

Proofs have been given that non-commutative geometry and differential calculus can be joined together by invoking an underlying quantum-group symmetry. Choosing the quantum group  $SO_q(N)$ , we then have to proceed by using the corresponding R-matrix solution to the parameter dependent Yang-Baxter equation. This results in a non-trivial  $q$ -deformation of the Laplacian acting on the  $N$ -dimensional non-commutative quantum Euclidian-space  $R_q^N$ . Surprisingly enough, the radial reduction of the covariant derivative implied in this manner reproduces the  $q$ -difference derivative presented long ago by Jackson. This opens the way to derive nontrivial  $q$ -deformations of the eigenvalues of the second-order Casimirs of  $SO_q(N)$ . The representation-dependence of  $q$ -deformed eigenvalues referred to above is also discussed in some more detail. The free particle can then be treated in terms of  $q$ -Jackson-Bessel functions.

**1. Introduction**

Parameter-dependent generalisations of the usual quantum-mechanical description have attracted much interest during the last decade [1]. The deformation parameter is denoted by  $q$ , such that the usual theory gets recovered as  $q \rightarrow 1$ . This notation is reminiscent to the  $q$ -difference formula

$$\partial_q f(x) = \partial_q^{(x)} f(x) = \frac{f(qx) - f(x)}{(q-1)x} \quad (1.1)$$

written down long ago by Jackson [2]. Several  $q$ -hypergeometric functions have been discussed even much earlier (see §3.1 in [3]). However, the most important step characterising this decade is the

synthesis between non-commutative geometry and the differential calculus, as presented in a clear manner by Wess and Zumino [4]. Such derivatives should then proceed covariantly with respect to certain quantum-group structures [5], like the one of the N-dimensional linear matrices  $GL_q(N)$ , or the one, say  $SO_q(N)$ , describing the rotations about the origin of the N-dimensional Euclidean space. These quantum-group symmetries are incorporated into  $\hat{R}$ -matrices having the size  $N^2 \times N^2$  and satisfying the

parameter independent Yang-Baxter equation  $\hat{R}_{12}\hat{R}_{23}\hat{R}_{12} = \hat{R}_{23}\hat{R}_{12}\hat{R}_{23}$  [6].

The conventional notation for matrices acting on tensor products of vectorial spaces is used. Then the quantum-group symmetry is exhibited by a further Yang-Baxter equation like  $T_1 T_2 \hat{R}_{12} = \hat{R}_{12} T_1 T_2$

[4,6], where the linear transformations of underlying non-commutative coordinates proceed as  $x^i = T_j^i x^j$ . The summation over

repeated covariant and contravariant indices is assumed, as usual. It should be mentioned that that the q-parameter is responsible for the non-commutative behavior of coordinates, such as given by the typical equations

$$\begin{aligned} x^1 x^2 &= q x^2 x^1 \\ x^2 x^3 &= q x^3 x^2 \\ x^1 x^3 - x^3 x^1 &= \frac{1-q}{\sqrt{q}} x^2 x^2 \end{aligned} \tag{1.2}$$

characterising  $SO_q(3)$ , such that hereafter  $q > 0$ . Using the q-dependent metric tensor  $C_{ij}$ , then gives the square length as [7]

$$\begin{aligned} r_q^2 &\equiv \ell^2 = C_{ij} x^j x^i \\ &= q^{-1/2} x^1 x^3 + x^2 x^2 + q^{1/2} x^3 x^1 \end{aligned} \tag{1.3}$$

for  $N=3$ , where  $x_i = C_{ij} x^j$  and  $[r_q^2, x^i] = 0$ . Starting from the basic covariant derivative formula [4]

$$\partial_i x^k = \delta_i^k + q \hat{R}_{1n}^{km} x^n \partial_m \quad (1.4)$$

opens the way to define the  $q$ -deformed Laplacian as [7-10]

$$\Delta_q = \partial^i \partial_i \quad (1.5)$$

where  $\partial^i = C^{ij} \partial_j$  and  $\partial_i = \partial / \partial x^i$ , so that  $[\Delta_q, \partial^i] = 0$ . Moreover, introducing algebraically the radial coordinate by virtue of the commutation relation  $[r_q, x^i] = 0$ , nothing prevents us from defining the radial derivative by virtue of the relationship [11]

$$\partial_r = \frac{x_i}{r} \partial^i \quad (1.6)$$

which proceeds in a close analogy with the classical description.

Proofs have also been given that the harmonic oscillator [7-9] and the Coulomb-problem [10-12] can be solved on the  $N$ -dimensional non-commutative Euclidean space referred to above. In addition,  $q$ -deformed radial Schrödinger-equations have been written down, as shown by (34)-(36) in [11]. These equations rely on (2.33) in [8], but further explanations and/or clarifications are still in order. This conjecture motivates us to present further details and relationships concerning the  $q$ -deformation of the radial Schrödinger-equation. In this context both Hermitian and non-Hermitian  $q$ -deformed Schrödinger-Hamiltonians will be discussed. The  $q$ -deformed free particle will also be treated in some more detail. Units for which  $\hbar = m_0 = c = 1$  are used, whereas the  $q$ -number reads

$$[[n]]_q = q^{\frac{n-1}{2}} [n]_{\sqrt{q}} = \frac{q^n - 1}{q - 1} \quad (1.7)$$

The paper is organised as follows. The Hermitian radial momentum operator is introduced in section 2 with the help of the radial  $q$ -deformed Heisenberg-algebra. Section 3 deals with an alternative derivation of Hermitian but parameter - and system dependent Hamiltonians. The free particle is then discussed in sections 5 and 6 in terms of  $q$ -Jackson-Bessel and  $q$ -exponential functions, respectively. Section 6 contains useful details concerning the angular part of the wavefunctions and the  $q$ -deformed Casimir-eigenvalues. We conclude with a brief summary of main results and with a succinct presentation of open perspectives.

## 2. The $q$ -deformed radial momentum operator

Using the concrete forms of  $C$ - and  $\hat{R}$ -matrices [6,7], it can be verified that the  $\partial$ -derivative proceeds as [11]

$$\partial = \partial_q^r = \frac{\mu}{q+1} \partial_q^{(r)} \quad (2.1)$$

in accord with (1.1) and (1.6), where  $\mu = 1 + q^{2-N}$ . This means that  $\partial_q^{(r)} = d_q/d_q r$  stands properly for the  $q$ -deformation of the usual radial derivative  $\partial = d/dr$ . For convenience we shall define, however, the  $q$ -deformed radial momentum-operator as

$$\beta = -i\partial \quad (2.2)$$

so that

$$\beta r - q r \beta = -i \frac{\mu}{q+1} \quad (2.3)$$

Performing the Hermitian-conjugation of (2.3) and using

$$\partial r^n = \frac{\mu}{q+1} [[n]]_q r^{n-1} + q^n r^n \partial \quad (2.4)$$

yields

$$\tilde{P}\tilde{\beta}^*-q\tilde{\beta}^*\tilde{P}=i\frac{\mu}{q+1} \quad (2.5)$$

where we have assumed quite reasonably that  $\tilde{P}^*=\tilde{P}$ . Then the Hermitian conjugated radial momentum-operator is given by

$$\tilde{P}^*=i\tilde{\partial}^*=-iq^{-N}\tilde{\partial}_{q'} \quad (2.6)$$

where now  $q'=1/q$ . This enables us to introduce the Hermitian  $q$ -deformed radial momentum-operator as follows

$$P_H=\frac{q}{\mu}(\tilde{\beta}+\tilde{\beta}^*) \quad (2.7)$$

which is invariant under  $q \rightarrow 1/q$ . Accordingly

$$P_H f(\tilde{r}) = -\frac{i}{\tilde{r}} \frac{f(q\tilde{r}) - f(q^{-1}\tilde{r})}{q - q^{-1}} \quad (2.8)$$

which corresponds e.g. to eq.(2.4b) in [13] and which provides a symmetrized version of the  $q$ -deformed radial derivative. Other symmetrizations have been done for the components of the vectorial momentum-operator [12,14], but this time one proceeds in conjunction with suitable star-conjugations.

We are now able to realise that the  $q$ -deformations of the three typical radial Schrödinger-equations written down before [11] exhibit inter-related Hamiltonians which are not Hermitian ones. Thus the  $q$ -deformed Hamiltonian characterising the former  $u$ -representation ( see (36) in [11]) reads

$$H_\Phi^{(q)} = F(q)\tilde{\partial}^2 + \frac{\lambda_\Phi^{(q)}}{r^2} + V(r) \quad (2.9)$$

where

$$F(q) = -\frac{q}{(q+1)^2}(q^{-L/2} + q^{L/2})^2 \quad (2.10)$$

and

$$\lambda_{\Phi}^{(q)} = -\frac{\mu^2 q^2}{(q+1)^4} [[-2l-N+1]]_q [[2l+N-3]]_q. \quad (2.11)$$

One has  $L=1+(N-2)/2$ , whereas  $l=0,1,2,\dots$ , as usual. Further one obtains

$$H_{\Phi}^{(q)} - H_{\Phi}^{(q)*} = F(q) (\partial_q^{(z)^2} - q^{-2N} \partial_q^{(r)^2}) \quad (2.12)$$

by virtue of (2.6). Applying this difference to a monomial yields

$$\begin{aligned} (H_{\Phi}^{(q)} - H_{\Phi}^{(q)*}) r^n &= G_n(q) r^{n-2} = \\ &= \frac{\mu^2}{(q+1)^2} [[n]]_q [[n-1]]_q (1 - q^{1-2n}) r^{n-2} \end{aligned} \quad (2.13)$$

so that  $G_n(1)=0$ , as one might expect. This means that the classical limit of (2.9), i.e.

$$H_{\Phi}^{(1)} = -\partial^2 + \left(L^2 - \frac{1}{4}\right) \frac{1}{r^2} + V(r) \quad (2.14)$$

is Hermitian. However, if  $q \neq 1$ , one has  $G_n(q) \neq 0$  if  $n=0, 1/2$  and  $1$  only. This indicates that  $H_{\Phi}^{(q)}$  ceases to be Hermitian, in

contradistinction to  $H_{\Phi}^{(1)}$ .

Such  $q$ -deformed Hamiltonians are, however, meaningful as they play the role of well defined  $q$ -parameter dependent generalisations of Hermitian classical counterparts [7,8,10]. Moreover, it has been found that they work safely in concrete applications, like the  $q$ -deformation of classical duality transformations [15]. It should also be stressed that such developments serve as a theoretical basis to the derivation of more general  $q$ -difference and/or discrete equations. In this respect we have to mention, that quantum mechanics on a lattice can be viewed as a nontrivial  $q$ -deformation [16], too. Moreover, there are reasons to consider that the flexibility of the usual quantum-mechanical description gets

enhanced by accounting for appropriate non-Hermitian generalisations [17].

### 3. The q-deformed free particle description

After having been arrived at this stage, we are ready to analyse in some more details the q-deformed free particle description. Usual results have then to be reproduced as  $q \rightarrow 1$ . For this purpose, let us consider the q-deformed radial Schrödinger-equation [8,11,18]

$$H_f^{(q)} f_q^{(l)}(\tilde{r}) = (-\Delta_q^{(l,M)} + V(r)) f_q^{(l)}(\tilde{r}) = E_q f_q^{(l)}(\tilde{r}) \quad (3.1)$$

where now

$$\Delta_q^{(l,M)} = q^{2l+N-1} \partial^2 + \frac{\mu}{q+1} [[2l+N-1]]_q \frac{1}{\tilde{r}} \partial \quad (3.2)$$

which relies on (2.9) and which works in the f-representation discussed before [11]. Putting  $V(r)=0$ , we are then faced with the q-deformed eigenvalue equation

$$-\Delta_q^{(l,M)} f_q^{(\pm l)}(\tilde{r}, k) = E_q f_q^{(\pm l)}(\tilde{r}, k) \quad (3.3)$$

The eigenvalue and the eigenfunctions are then given by

$$E_q = \frac{1}{4} \mu^2 k^2 \quad (3.4)$$

where k denotes the continuous and positive momentum parameter and

$$f_q^{(\pm l)}(\tilde{r}, k) = \tilde{r}^{-l} J_{\pm l}^{(1)}(k\tilde{r}; q^2) \quad (3.5)$$

respectively [18]. One has

$$J_\nu^{(1)}(x; q) = \sum_{n=0}^{\infty} \frac{(-1)^n (x/2)^{2n+\nu}}{[[n]]_q! \Gamma_q(n+1+\nu)} \quad (3.6)$$

where  $0 < q < 1$ , which relies on the well known q-Jackson-Bessel functions [19-24]. We have to note, however, that (3.6) corresponds

to  $J_\nu^{(1)}((1-q)x; q)$ , as used in the mathematical literature [24].

In addition, the q-Gamma-function quoted above fulfils the typical property ( see e.g. [25])

$$\Gamma_q(n+1+v) = [[n+v]]_q \Gamma_q(n+v) \quad (3.7)$$

We then have to recognize that eqs. (3.3) - (3.6) express a meaningful  $q$ -deformation of the usual free particle description. Accordingly, the usual results get reproduced safely as soon as  $q \rightarrow 1$ .

Further clarifications are still in order. Indeed, accounting for (1.1), we have to realise that the inverse operation is given quite consistently by the  $q$ -integral [26]

$$\int_0^\infty f(\tilde{r}) d_q \tilde{r} = (1-q) \sum_{j=-\infty}^{j=\infty} q^j f(q^j) \quad (3.8)$$

where  $0 < q < 1$ . Relatedly, let us consider the  $q$ -deformed sine-function

$$\sin_q x = \sum_{n=0}^{\infty} \frac{(-1)^n x^{2n+1}}{[[2n+1]]_q!} \frac{\pi^{1/2}}{\Gamma_q(1/2)} \left(\frac{q+1}{2}\right)^{2n+1} \quad (3.9)$$

We then have to realise that

$$\int_0^\infty \sin_q(k'\tilde{r}) \sin_q(k\tilde{r}) d_q \tilde{r} = \frac{\pi}{2} \delta_q(k'-k) \quad (3.10)$$

stands for a nontrivial  $q$ -deformation of the usual Dirac-function

$$\int_0^\infty \sin(k'r) \sin(kr) dr = \frac{\pi}{2} \delta(k'-k) \quad (3.11)$$

On the other hand there is ( see also (3.17) in [25])

$$\sin_q(x) = \left(\frac{1}{2}x\right)^{1/2} J_{1/2}^{(1)}(x; q^2) \quad (3.12)$$

so that the scalar product (3.10) becomes

$$\langle k'|k \rangle^{1/2} \langle k', 1/2 | k, 1/2 \rangle_q = \delta_q(k'-k) \quad (3.13)$$

where  $|k, 1/2 \rangle_q$  stands for  $f_q^{(1/2)}(\tilde{r}, k)$ . Therefore,  $f_q^{(1/2)}(\tilde{r}, k)$

exhibits definitely a well defined  $q$ -deformed version of the orthogonality condition characterising the classical solution



$f_1^{(1/2)}(r, k)$ . Thus there are valuable reasons to consider that the spectrum characterising the  $q$ -deformed free particle presented above is definitely continuous, which agrees with the very form of the  $q$ -energy exhibited by (3.4). Such results are in accord with the eigenvalue-equations done recently in terms of a star symmetrized free-particle Hamiltonian (see (15)-(16) in [12]). The same remains valid with the free particle description [27] based on homogeneous spaces [28] of the Euclidean quantum group  $E_q(2)$ .

Nevertheless, a discrete free-particle spectrum has been derived by looking from the very beginning for normalizable power-series expansions without negative powers in the radial coordinate [29]. The point is that the discrete energy derived in this manner behaves like  $1/(1-q^2)^2$ , so that it does not express, as a matter of fact, an actual  $q$ -deformation of the classical result. Such results should then be viewed as exclusive manifestations implied by the quantum-group description, so that they deserve further attention.

#### 4. The $q$ -deformed centrifugal barriers

Now we would like to use this opportunity to clarify several aspects concerning the  $q$ -deformed centrifugal barriers as well as the angular-dependence of total wavefunctions. First we have to recall that the radial unrenormalized wavefunctions characterising (34)-(36) in [11] are inter-related as

$$\Psi_q^{(1)}(\tilde{r}) = \tilde{r}^{-2} f_q^{(2)}(\tilde{r}) = \tilde{r}^{1-a} \phi_q^{(2)}(\tilde{r}) \quad (4.1)$$

where

$$q^a = \frac{q^{-2L+1}}{q+1} \quad (4.2)$$

and where  $\Psi_q^{(1)}(\tilde{r})$  and  $\phi_q^{(2)}(\tilde{r})$  stand for the former  $g(r)$  and  $f(r)$ , respectively. Starting from  $f_q^{(1)}(\tilde{r})$ , we can then say that the

total q-deformed wavefunction factorizes as

$$\Psi_q^{(1)}(\vec{x}) = S_I^{(1)}(x^i) f_q^{(1)}(\vec{r}) \quad (4.3)$$

where  $S_I^{(1)}(x^i)$  is a suitably symmetrized sum of monomials of the same degrees in the non-commutative  $x^i$ -coordinates ( see (2.23) in [8] ). On the other hand (4.3) can be rewritten equivalently as

$$\Psi_q^{(1)}(\vec{x}) = Y_q^{(1)}(\xi^i) \psi_q^{(1)}(\vec{r}) \quad (4.4)$$

where  $\xi^i = x^i/\vec{r}$  and where

$$Y_q^{(1)}(\xi^i) = \frac{1}{\vec{r}^1} S_I^{(1)}(x^i) \quad (4.5)$$

is the q-deformed counterpart of N-dimensional spherical harmonics, i.e. of Gegenbauer-polynomials. Furthermore one has

$$\begin{aligned} \Delta_q(S_I^{(1)}(x^i) f_q^{(1)}(\vec{r})) &= S_I^{(1)}(x^i) \Delta_q^{(1,M)} f_q^{(1)}(\vec{r}) = \\ &= S_I^{(1)}(x^i) \left( q^{2I} \Delta_q + \frac{\mu}{q+1} [[21]]_q C_{ij} x^i \partial^j \right) f_q^{(1)}(\vec{r}) \end{aligned} \quad (4.6)$$

which leads to the q-deformed eigenvalue-equation

$$-\Delta_q Y_q^{(1)}(\xi^i) = \lambda_\psi^{(q)} Y_q^{(1)}(\xi^i) \quad (4.7)$$

via  $f_q^{(1)}(\vec{r}) = \vec{r}^{-1}$ . We have to remark that

$$\lambda_\psi^{(q)} = \frac{\mu^2}{(q+1)^2} q^{-I} [[I]]_q [[I+N-2]]_q \quad (4.8)$$

reproduces precisely the amplitude of the q-deformed centrifugal barrier in (35) in [11], as one might expect. Of course, (4.8) stands for the q-deformed eigenvalue of the square angular momentum in the  $\psi$ -representation. Concrete form of such q-deformed

spherical harmonics have already been written down for  $l=0,1$  and 2 [10,12]. Moreover, certain  $q$ -generalisations of Gegenbauer polynomials have also been discussed [30]. It should be mentioned that in order to treat (4.6) we have to resort basically to (1.4), but further equations like

$$\partial^i x^j = C^{ij} + q(\hat{R}^{-1})_{ij} x^m \partial^i \quad (4.9)$$

and

$$\partial_i x_j = C_{ji} + q(\hat{R}^{-1})_{ji} x_k \partial_k \quad (4.10)$$

are useful.

Proceeding similarly and putting  $f_q^{(l)}(\vec{r}) = \vec{r}^a$  yields the  $q$ -deformed eigenvalue (2.11). It should also be mentioned that (2.11) and (4.8) correspond to the  $q$ -deformed Casimir-eigenvalues presented before for  $N=3$  [12,31] and for arbitrary  $N$  [29], respectively. Thus we succeeded to clarify the representation background of the two different  $q$ -deformed Casimir-eigenvalues discussed separately before.

## 5. Conclusions

In this paper we have discussed further aspects concerning the  $q$ -deformation of the radial Schrödinger-equation. So the Hermitian radial momentum operator (2.6) has been derived in a quite transparent manner with the help of the radial  $q$ -deformed Heisenberg-algebra (2.3). Closed free-particle solutions to the  $q$ -deformed radial Schrödinger-equation (3.1) have been written down. We have also succeeded in clarifying several details concerning the angular part of the  $q$ -deformed wavefunctions as well as the influence of the representation on the  $q$ -deformed Casimir-eigenvalues. In general,  $q$ -deformed radial Schrödinger-equations mentioned above are not easily solvable, but useful approximations can be derived by applying  $q$ -deformed  $1/N$ -formulae [11,15,32]. Besides (2.3), other generalisations of the Heisenberg-algebra have also been discussed [33].

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