

(6)

Dedicated to Costică MUSTĂTA on his 60<sup>th</sup> anniversary

### SCHWARZSCHILD'S METRIC GENERATED BY A BODY WITH MASS

$m_1$  PERTURBED BY A BODY WITH MASS  $m_2$  FROM A FIXED DISTANCE

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(7)  $\sqrt{g_{00}} \left( \frac{m_1}{r} + \frac{m_2}{r^2} \right) = \sqrt{1 - \frac{2m_1}{r}} + \sqrt{1 - \frac{2m_2}{r^2}} = \sqrt{g_{00}}$

Abstract. This paper approaches the modification a relativity metrics of spherical symmetry generated by a body of mass  $m_1$  due to a for off spherical deals with the translation

of the reference frame  $O'x'y'z'$  with the origin in  $m_2$  is done in the reference frame  $Oxyz$  with the origin in  $m_1$ .

The straight line  $OO'$  being the support of the axes  $O'x'$  and  $Ox$ . In the present case, distance  $OO' = a$  is considered constant in time.

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#### The translation of the axes of coordinates

Let us consider two spherical bodies of mass  $m_1$  and  $m_2$  situated at a fixed distance  $a$  much bigger than their radii.

In this case a reference frame can be chosen for both bodies, so that mass  $m_1$  should be located in the origin  $O$  of the system of axes  $Oxyz$ , and mass  $m_2$  should be in the origin  $O'$  of the system of axes  $O'x'y'z'$ .

A spherical body of mass  $m_1$  situated in the origin of the reference frame  $Oxyz$  determines a Schwarzschild metrics in its exterior [1].

$$ds_1^2 = g_{ij} dx^i dx^j = \left(1 - \frac{2m_1}{r}\right) dt^2 - \left(1 - \frac{2m_1}{r}\right)^{-1} dr^2 - r^2 d\theta^2 - r^2 \sin^2 \theta d\phi^2 \quad (1)$$

where

$$\begin{aligned} x^0 &= t = ct_{ph}; & x^1 &= r = r_{ph}; & x^2 &= \theta = \theta_{ph}; & x^3 &= \phi = \phi_{ph} \\ \left. \begin{aligned} \theta &= \pi/2 \\ \theta &= 0 \end{aligned} \right\} & & \left. \begin{aligned} \theta &= \pi/2 \\ \theta &= 0 \end{aligned} \right\} & & \left. \begin{aligned} \theta &= \pi/2 \\ \theta &= 0 \end{aligned} \right\} & & \left. \begin{aligned} \theta &= \pi/2 \\ \theta &= 0 \end{aligned} \right\} \end{aligned} \quad (2)$$

are the geometrized generalized spherical coordinates. The geometrized time and mass have length dimensions (in meters). ~~(DE GRUYTER AND JOURNAL FOR APPLIED MATHEMATICS)~~

$$m = \frac{G M_{pk}}{c^2} \quad (3)$$

where index  $ph$  shows us that the respective magnitude is measured in physical units while  $c$  and  $G$  represents the speed of the light and the universal constant of gravity, respectively.

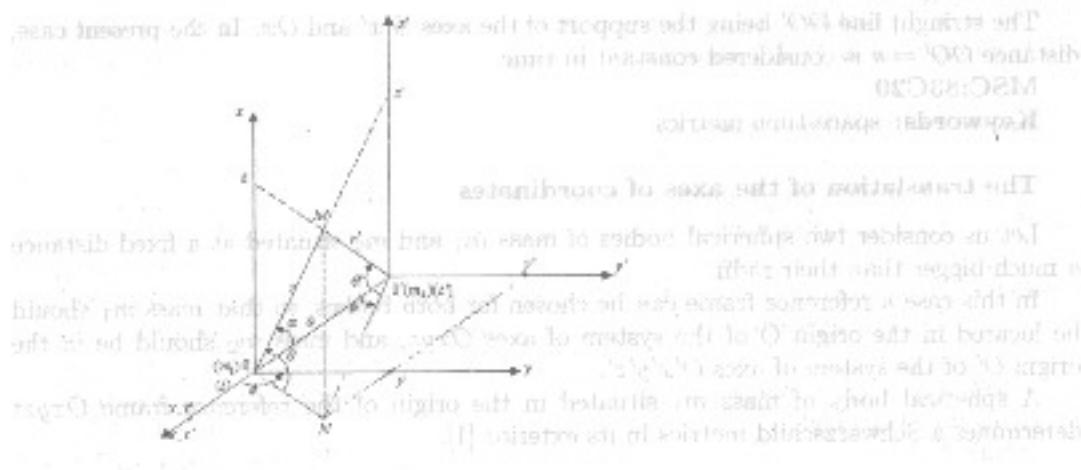
The body of mass  $m_2$  with the mass center situated in the origin of the reference point  $Ox_2'y_2'z_2'$  determines the metrics

$$ds_2^2 = \left(1 - \frac{2m_2}{r'}\right) dt'^2 - \left(1 - \frac{2m_2}{r'}\right)^{-1} dr'^2 - r'^2 d\theta'^2 - r'^2 \sin^2 \theta' d\phi'^2 \quad (4)$$

The length unit in both cases is the meter measured by a for all observer.

A point M from the space-time Universe has the Cartesian coordinates  $(t, x, y, z)$  measured from O and  $(t', x', y', z')$  from  $O' \cap 2$ . We have noted the radial distances by

In order to obtain a better fit we perform a stepwise regression analysis (see Fig. 5) to determine which variables are significant in explaining the variation in the distance between the centers of mass of the two objects. The results of this analysis are shown in Table 1.



Between the spherical coordinates and the Cartesian coordinates of the two reference point there is the relationship:

$$\left\{ \begin{array}{l} x = r \cos \theta \cos \phi \\ y = r \cos \theta \sin \phi \\ z = r \sin \theta \end{array} \right. \quad \left\{ \begin{array}{l} x' = r' \cos \theta' \cos \phi' \\ y' = r' \cos \theta' \sin \phi' \\ z' = r' \sin \theta' \end{array} \right. \quad (6)$$

It is to be notice that:

(7)

$$\left\{ \begin{array}{l} x' = a + x \\ y' = y \\ z' = z \end{array} \right.$$

By applying Pythagoras' generalized theorem under the trigonometrical form in the triangle  $MOO'$ , we have

(8)

$$r'^2 = a^2 + r^2 + 2ar \cos \alpha$$

is results

$$r' = E = \sqrt{a^2 + r^2 + 2ar \cos \theta \cos \phi} \quad (9)$$

An event occurring in the point  $M$  at the moment  $t_{M,\alpha}$  measured after the clock in  $M$ , will be seen in  $O$  after the arrival of the luminous signal coming with the speed of light  $c$  at the moment  $t_{ph} + \frac{r}{c}$ , and in  $O'$  at the moment  $t'_{ph} + \frac{r'}{c}$ . In geometrized units

(10)

$$t_M = t + r = t' + r' + \Delta t_{ph} - \Delta t_{M,O}$$

of which  $\Delta t$  is geodetic time interval between the events in  $O$  without the interval between the events in  $O'$  and  $M$  (see Fig. 11)

(11)

$$t' = t + r - E$$

As  $z = z'$  from (6) and (9) results

(12)

$$\sin \theta' = \frac{r \sin \theta}{E} \quad \text{and} \quad \cos \theta' = \frac{F}{E} \left( \frac{\cos \lambda}{\lambda} - 1 \right) \frac{1}{\sqrt{1 - \frac{v^2}{c^2}}}$$

where

(13)

$$F = \sqrt{a^2 + r^2 \cos^2 \theta + 2ar \cos \theta \cos \phi}$$

In the same way, from  $y' = y$  and (6) and (13) we have

(14)

$$\sin \phi' = \frac{r \cos \theta \sin \phi}{F} \quad \text{and} \quad \cos \phi' = \frac{a + r \cos \theta \cos \phi}{F} \left( \frac{1}{\sqrt{1 - \frac{v^2}{c^2}}} \right)$$

(15)

$$\left\{ \begin{array}{l} \sin \theta' = \frac{r \sin \theta}{E} \quad \text{and} \quad \cos \theta' = \frac{F}{E} \left( \frac{\cos \lambda}{\lambda} - 1 \right) \frac{1}{\sqrt{1 - \frac{v^2}{c^2}}} \\ \sin \phi' = \frac{r \cos \theta \sin \phi}{F} \quad \text{and} \quad \cos \phi' = \frac{a + r \cos \theta \cos \phi}{F} \left( \frac{1}{\sqrt{1 - \frac{v^2}{c^2}}} \right) \end{array} \right.$$

The passing of Schwarzschild's metrics associated with mass  $m_2$  to the coordinates associated with the reference point with the origin in  $m_1$

Let us suppose, for the simplification of the calculations, that  $a = OO' = \text{constant}$  in time. Therefore

$$(8) \quad \frac{da}{dt} = 0 \quad (15)$$

Differentiating the linking relations (9), (11), (12), (13), (14) and replacing the magnitudes by prime ('), in metrics (4) we get the metric  $ds_2^2$ .

The results obtained in this way we unified in the following theorem.

**Theorem.** *The Schwarzschild's metrics generated by a body with mass  $m_1$  is perturbed by a body with mass  $m_2$  situated at a fixed distance  $a$ , with the supplementary metric:*

$$(16) \quad \begin{aligned} ds_2^2 = & h_{00} dx^1 dx^1 + h_{11} dr^2 + h_{22} d\theta^2 + h_{33} d\phi^2 + \\ & + 2h_{01} dt dr + 2h_{02} dt d\phi + 2h_{03} dt d\phi + \\ & + 2h_{12} dr d\theta + 2h_{13} dr d\phi + 2h_{23} d\theta d\phi \end{aligned}$$

where the metrics  $ds_2^2$  are expressed in the coordinates corresponding to the reference system  $O_{txyz}$ , where  $h_{ij}$  are expressed as follows:

$$(17) \quad h_{00} = 1 - \frac{2m_2}{E}$$

$$(18) \quad \begin{aligned} h_{11} = & \frac{1}{E^2} \left[ \left( 1 - \frac{2m_2}{E} \right)^{-1} (E - r - a \cos \theta \cos \phi) - \left( 1 - \frac{2m_2}{E} \right)^{-1} (r + a \cos \theta \cos \phi)^2 \right] - \\ & - \frac{a^2}{F^2} \sin^2 \theta \left[ \frac{(a + r \cos \theta \cos \phi)^2 + r^2 \cos^2 \theta \sin^2 \phi}{E^2} + \frac{r^2 \cos^2 \theta \sin^2 \phi}{F^2} \right] \end{aligned}$$

$$(19) \quad \begin{aligned} h_{22} = & \frac{1}{E^2} a^2 r^2 \sin^2 \theta \cos^2 \phi \left[ \left( 1 - \frac{2m_2}{E} \right)^{-1} - \left( 1 - \frac{2m_2}{E} \right)^{-1} \right] - \\ & - \frac{r^2}{F^2} \left\{ \frac{1}{E^2} [(a^2 + r^2) \cos \theta + ar \cos \phi (1 - \cos^2 \theta)]^2 + \right. \\ & \left. + \frac{r^2 \sin^4 \theta \sin^2 \phi}{F^2 (a + r \cos \theta \cos \phi)^2} [a^2 + r^2 \cos^2 \theta + r(a - r) \cos \theta \cos \phi]^2 \right\} \end{aligned}$$

$$h_{33} = \frac{1}{E^2} a^2 r^2 \cos^2 \theta \sin^2 \phi \left[ \left( 1 - \frac{2m_2}{E} \right) - \left( 1 - \frac{2m_2}{E} \right)^{-1} \right] -$$

$$- \left[ \left( \frac{r^4}{E^2} \sin^2 \theta \cos^2 \theta \left\{ \frac{a^2 \sin^2 \phi}{E^2} + \frac{1}{F^2(a+r \cos \theta \cos \phi)^2} \right. \right. \right.$$

$$\left. \left. \left. + [ar \cos \theta (1 + \cos^2 \phi) + (a^2 + r^2 \cos^2 \theta) \cos \phi]^2 \right\} \right] \quad (20)$$

$$h_{01} = \left( 1 - \frac{r + a \cos \theta \cos \phi}{E} \right) \left( 1 - \frac{2m_2}{E} \right) \quad (21)$$

$$h_{02} = \frac{1}{E} ar \sin \theta \cos \phi \left( 1 - \frac{2m_2}{E} \right) \quad (22)$$

$$h_{03} = \frac{1}{E} ar \cos \theta \sin \phi \left( 1 - \frac{2m_2}{E} \right) \quad (23)$$

## REFERENCES

1.  $h_{12} = \frac{1}{E^2} ar \sin \theta \cos \phi$  — [\[1\]](#)  
 $\cdot \left[ \left( 1 - \frac{2m_2}{E} \right) (E - r - a \cos \theta \cos \phi) + \left( 1 - \frac{2m_2}{E} \right)^{-1} (r + a \cos \theta \cos \phi) \right] -$   
 $\cdot \frac{ar}{F^2} \sin \theta (a + r \cos \theta \cos \phi) \left\{ \frac{1}{E^2} [(a^2 + r^2) \cos \theta + ar \cos \phi (1 + \cos^2 \theta)] - \right.$   
 $\left. - \frac{r^2 \sin^2 \theta \cos \theta \sin^2 \phi}{F^2(a + r \cos \theta \cos \phi)^2} [a^2 + r^2 \cos^2 \theta + r(a - r) \cos \theta \cos \phi] \right\} \quad (24)$

$$h_{13} = \frac{1}{E^2} ar \cos \theta \sin \phi$$

$$\cdot \left[ \left( 1 - \frac{2m_2}{E} \right) (E - r - a \cos \theta \cos \phi) + \left( 1 - \frac{2m_2}{E} \right)^{-1} (r + a \cos \theta \cos \phi) \right] -$$

$$- \frac{ar^2}{F^2} \sin^2 \theta \cos \theta \sin \phi \left\{ \frac{a(a + r \cos \theta \cos \phi)}{E^2} + \frac{r \cos \theta}{F(a + r \cos \theta \cos \phi)} \right.$$

$$\left. \cdot [ar \cos \theta (1 + \cos^2 \phi) + (a^2 + r^2 \cos^2 \theta) \cos \phi] \right\} \quad (25)$$

$$\begin{aligned}
 h_{23} &= \frac{1}{E^2} a^2 r^2 \sin \theta \cos \theta \sin \phi \cos \phi \left[ \left( 1 - \frac{2m_2}{E} \right) - \left( 1 - \frac{2m_2}{E} \right)^{-1} \right] - \\
 &\quad - \frac{r^3}{F^2} \sin \theta \cos \theta \sin \phi \left\{ \frac{a}{E^2} [(a^2 + r^2) \cos \theta + ar \cos \phi (1 + \cos^2 \theta)] - \right. \\
 &\quad \left. - \frac{ar^3 \sin \theta \cos \theta \sin \phi}{F^2} \left\{ \frac{1}{E^2} [(a^2 + r^2) \cos \theta + ar(1 + \cos^2 \theta) \cos \phi] - \right. \right. \\
 &\quad \left. \left. - \frac{\tau \sin^2 \theta}{F^2(a + r \cos \theta \cos \phi)} [(a^2 + r^2 \cos^2 \theta) \cos \phi + ar \cos \theta (1 + \cos^2 \phi)] \right\} \right\} \quad (26) \\
 &\quad - \left( \frac{1 + \frac{2m_2}{E}}{\frac{3}{2}} - 1 \right) \sin \theta \cos \theta \tan \frac{1}{2} = \text{constant} \quad \square
 \end{aligned}$$

## REFERENCES

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