

New stable semi-explicit Runge-Kutta methods

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ABSTRACT. Semi-explicit Runge-Kutta methods of order 3 with four stages and order 4 with five stages are discussed, from stability point of view. Some A -stable and L -stable subclasses of such methods are highlighted.

1. INTRODUCTION

For initial value problem

$$(1.1) \quad y'(x) = f(x, y(x)), \quad y(x_0) = y_0,$$

where $f : [a, b] \times \mathbb{R}^m \rightarrow \mathbb{R}^m$, $x_0 = a$, $y_0, y \in \mathbb{R}^m$, we consider the numerical solution obtained by special implicit Runge-Kutta methods, called semi-explicit or diagonally-implicit (see [2], [3]).

Many authors have investigated such methods: J.C. Butcher [2], [3], E. Hairer, C. Lubich, G. Wanner [7], [8], P.J. Houwen van der and B.P. Sommeijer [9], K. Burrage [1] etc.

In this paper we will construct some subclasses of semi-explicit Runge-Kutta schemes of order 3 with four stages and order 4 with five stages for problem (1.1). These methods will be A -stable or L -stable thus they are suitable for solving stiff problems.

Without loss of generality, the analysis will be performed when (1.1) is a scalar problem.

2. PRELIMINARIES

Let x_n , $n = 0, 1, 2, \dots, N$ be, equal spaced points from interval $[a, b]$, with $x_0 = a$, $x_n - x_{n-1} = h$, $n = 0, 1, 2, \dots$, $x_N = x_0 + Nh = b$, and let y_n be, the approximate value of exact solution $y(x)$ of (1.1) at the point x_n , $n = 0, 1, 2, \dots, N$.

Received: 15.05.2003; In revised form: 23.01.2004

2000 *Mathematics Subject Classification.* 65L06, 65L20.

Key words and phrases. *Semi-explicit or diagonally-implicit Runge-Kutta methods, stability function, A-stability, L-stability.*

Definition 2.1. A semi-explicit or diagonally-implicit Runge-Kutta method with s stages for numerical solution of the problem (1.1) is defined by the relations

$$(2.1) \quad k_{i,n} = hf \left(x_n^i, y_n + \sum_{j=1}^s a_{ij} k_{j,n} \right), \quad i = 1, 2, \dots, s$$

$$(2.2) \quad y_{n+1} = y_n + \sum_{i=1}^s b_i k_{i,n}; \quad n = 0, 1, 2, \dots,$$

where $x_n^i = x_n + c_i h$, and $b_i, a_{ij}, c_i, i, j = 1, 2, \dots, s$ are real parameters such that

$$a_{ij} = 0, \quad \text{for } j > i \quad \text{and} \quad a_{ii} = \lambda, \quad \text{for all } i, j = 1, 2, \dots, s.$$

A semi-explicit Runge-Kutta method is usually displayed in the Butcher's array

$$(2.3) \quad \begin{array}{c|c} c & A \\ \hline & b^T \end{array}$$

$$\text{where } c = (c_1, c_2, \dots, c_s)^T, \quad b^T = (b_1, b_2, \dots, b_s),$$

$$(2.4) \quad A = \begin{pmatrix} \lambda & 0 & 0 & \cdots & 0 \\ a_{21} & \lambda & 0 & \cdots & 0 \\ a_{31} & a_{32} & \lambda & \cdots & 0 \\ \cdots & \cdots & \cdots & \cdots & \cdots \\ a_{s1} & a_{s2} & a_{s3} & \cdots & \lambda \end{pmatrix},$$

should satisfy

$$(2.5) \quad c = A \cdot e,$$

with $e = (1, 1, \dots, 1)^T \in \mathbb{R}^s$.

We will focus our attention only to methods with $s = 4$ stages and $s = 5$ stages. For $s = 4$ and $s = 5$ stages the Runge-Kutta methods are generated respectively by the arrays

$$(2.6) \quad \begin{array}{c|cccc} c_1 & \lambda & 0 & 0 & 0 \\ c_2 & a_{21} & \lambda & 0 & 0 \\ c_3 & a_{31} & a_{32} & \lambda & 0 \\ c_4 & a_{41} & a_{42} & a_{43} & \lambda \\ \hline & b_1 & b_2 & b_3 & b_4 \end{array} \quad \text{and} \quad \begin{array}{c|ccccc} c_1 & \lambda & 0 & 0 & 0 & 0 \\ c_2 & a_{21} & \lambda & 0 & 0 & 0 \\ c_3 & a_{31} & a_{32} & \lambda & 0 & 0 \\ c_4 & a_{41} & a_{42} & a_{43} & \lambda & 0 \\ c_5 & a_{51} & a_{52} & a_{53} & a_{54} & \lambda \\ \hline & b_1 & b_2 & b_3 & b_4 & b_5 \end{array}$$

The stability function for such methods, depends only on parameter λ (see [9]) and it is given by

$$(2.7) \quad R(z, \lambda) = \frac{P(z, \lambda)}{Q(z, \lambda)}, \quad z \text{ complex,}$$

where

$$(2.8) \quad \begin{aligned} P(z, \lambda) = & 1 + (1 - 4\lambda)z + \left(\frac{1}{2} - 4\lambda + 6\lambda^2\right)z^2 + \\ & + \left(\frac{1}{6} - 2\lambda + 6\lambda^2 - 4\lambda^3\right)z^3 + \left(\frac{1}{24} - \frac{2}{3}\lambda + 3\lambda^2 - 4\lambda^3 + \lambda^4\right)z^4, \end{aligned}$$

$$(2.9) \quad Q(z, \lambda) = (1 - \lambda z)^4,$$

for $s = 4$, and

$$(2.10) \quad \begin{aligned} P(z, \lambda) = & 1 + (1 - 5\lambda)z + \left(\frac{1}{2} - 5\lambda + 10\lambda^2\right)z^2 + \\ & + \left(\frac{1}{6} - \frac{5}{2}\lambda + 10\lambda^2 - 10\lambda^3\right)z^3 + \left(\frac{1}{24} - \frac{5}{6}\lambda + 5\lambda^2 - 10\lambda^3 + 5\lambda^4\right)z^4 + \\ & + \left(\frac{1}{120} - \frac{5}{24}\lambda + \frac{5}{3}\lambda^2 - 5\lambda^3 + 5\lambda^4 - \lambda^5\right)z^5, \end{aligned}$$

$$(2.11) \quad Q(z, \lambda) = (1 - \lambda z)^5,$$

if the methods have $s = 5$ stages.

A -stability of the semi-explicit Runge-Kutta methods generated by the arrays (2.6) is equivalent (see [4]) to requirements that the polynomial Q should have no zeros in the left half-plane, that is $\lambda > 0$, and E -polynomial of Nørsett, [10],

$$(2.12) \quad E(y^2, \lambda) := |Q(iy, \lambda)|^2 - |P(iy, \lambda)|^2,$$

should satisfy

$$(2.13) \quad E(y^2, \lambda) \geq 0, \quad \forall y \in \mathbb{R},$$

for some $\lambda > 0$.

For L -stability, the stability function should satisfy the A -stability, requirements and more

$$(2.14) \quad \lim_{|z| \rightarrow +\infty} R(z, \lambda) = 0.$$

3. THE CONSTRUCTION OF A -STABLE AND L -STABLE METHODS OF ORDER 3

To obtain semi-explicit methods of order 3 with $s = 4$ stages, we impose the order conditions (see [2]), together with (2.5), which, in case of semi-explicit methods, become

$$(3.1) \quad b_1 + b_2 + b_3 + b_4 = 1,$$

$$(3.2) \quad b_1 c_1 + b_2 c_2 + b_3 c_3 + b_4 c_4 = \frac{1}{2},$$

$$(3.3) \quad b_1 c_1^2 + b_2 c_2^2 + b_3 c_3^2 + b_4 c_4^2 = \frac{1}{3},$$

$$(3.4) \quad b_2 a_{21} c_1 + b_3 (a_{31} c_1 + a_{32} c_2) + b_4 (a_{41} c_1 + a_{42} c_2 + a_{43} c_3) = \frac{1}{6} - \frac{\lambda}{2},$$

$$(3.5) \quad c_1 = \lambda, \quad c_2 = a_{21} + \lambda, \quad c_3 = a_{31} + a_{32} + \lambda,$$

$$(3.6) \quad c_4 = a_{41} + a_{42} + a_{43} + \lambda.$$

So, we are seeking values of parameters from the tableaux (2.6), usually $0 < c_i \leq 1$, $i = 1, 2, 3, 4$, that is $0 < \lambda \leq 1$, such that the equations (3.1) - (3.6) be satisfied and also (2.13) or (2.13) and (2.14).

We can state

Lemma 3.1. *The solutions of the system (3.1) – (3.6) are depending on the free parameters $\lambda, c_2, c_3, c_4 \in (0, 1]$, pairwise distinct and on the free parameters $b_1, a_{31}, a_{41}, a_{42}$, arbitrary real numbers.*

The solutions are given by

$$(3.7) \quad \begin{aligned} b_2 &= A_2/6(c_3 - c_2)(c_4 - c_2), \\ b_3 &= -A_3/6(c_3 - c_2)(c_4 - c_3), \\ b_4 &= A_4/6(c_4 - c_2)(c_4 - c_3), \\ a_{43} &= c_4 - a_{41} - a_{42} - \lambda, \\ a_{32} &= c_3 - a_{31} - \lambda, \quad a_{21} = c_2 - \lambda, \quad c_1 = \lambda, \end{aligned}$$

where

$$(3.8) \quad A_2 = 2 - 3(c_3 + c_4) + 6c_3c_4 - 6b_1 [\lambda^2 - \lambda(c_3 + c_4) + c_3c_4],$$

$$(3.9) \quad A_3 = 2 - 3(c_2 + c_4) + 6c_2c_4 - 6b_1 [\lambda^2 - \lambda(c_2 + c_4) + c_2c_4],$$

$$(3.10) \quad A_4 = 2 - 3(c_2 + c_3) + 6c_2c_3 - 6b_1 [\lambda^2 - \lambda(c_2 + c_3) + c_2c_3]$$

and the free parameters $\lambda, c_2, c_3, c_4, b_1, a_{31}, a_{41}, a_{42}$ should satisfy

$$\begin{aligned}
 & A_2\lambda(c_2 - \lambda)(c_4 - c_3) - A_3 [a_{31}\lambda + c_2(c_3 - a_{31} - \lambda)](c_4 - c_2) + \\
 & + A_4 [a_{41}\lambda + a_{42}c_2 + c_3(c_4 - a_{41} - a_{42} - \lambda)](c_3 - c_2) = \\
 (3.11) \quad & = (1 - 3\lambda)(c_3 - c_2)(c_4 - c_2)(c_4 - c_3).
 \end{aligned}$$

Proof. By solving the equations (3.1), (3.2) and (3.3) as a linear system with respect to b_2, b_3, b_4 and replacing the expressions of b_2, b_3, b_4 into the equation (3.4), and taking into account (3.5) and (3.6), after a long computation, we obtain the conclusions (3.7) and (3.11). \square

Remark 3.2. The formulas (3.7) provide the class of all semi-explicit Runge-Kutta methods of order 3, with four stages, depending on 8 free parameters $\lambda, c_2, c_3, c_4 \in (0, 1]$ distinct each other and $b_1, a_{31}, a_{41}, a_{42} \in \mathbb{R}$.

Example 3.3. We can check that the array

$$(3.12) \quad \begin{array}{c|cccc}
 \lambda & \lambda & 0 & 0 & 0 \\
 \frac{2}{5} & \frac{2}{5} - \lambda & \lambda & 0 & 0 \\
 \frac{3}{5} & \frac{8}{3} \left(\frac{3}{5} - \lambda \right) & \frac{5}{3} \left(\lambda - \frac{3}{5} \right) & \lambda & 0 \\
 1 & 0 & 3(1 - \lambda) & 2(\lambda - 1) & \lambda \\
 \hline
 & 0 & \frac{10}{9} & -\frac{5}{12} & \frac{11}{36}
 \end{array}$$

represents a family of semi-explicit methods of order 3 with four stages depending on one free parameter $\lambda \in (0, 1]$, belonging to the class specified in the Remark 3.2.

Now we will delimit two subsets of the class of semi-explicit Runge-Kutta methods of order 3 with four stages, namely the subclass of A -stable methods, and the subclass of L -stable methods.

We have

Theorem 3.4. For every $\lambda \in [\alpha, 1], c_2, c_3, c_4 \in (0, 1]$, distinct each other and every $b_1, a_{31}, a_{41}, a_{42}$ arbitrary real numbers, where $\alpha = \frac{3 + \sqrt{3}}{12} = 0.3943375673\dots$, the solutions (3.7) provide a subclass of A -stable semi-explicit Runge-Kutta methods of order 3 with four stages. Moreover, for the value $\lambda = \lambda^* = 0.5728160625\dots$, and the rest of free parameters as above, the solutions (3.7) provide a subclass of L -stable semi-explicit Runge-Kutta methods of order 3 with $s = 4$ stages.

Proof. We seek values for λ such that the inequality (2.13) be satisfied. If we write the polynomial E in the form

$$(3.13) \quad E(y^2, \lambda) = A(\lambda)y^6 + B(\lambda)y^8,$$

where A and B are the polynomials in λ

$$(3.14) \quad A(\lambda) = \frac{1}{72} - \frac{1}{3}\lambda + \frac{17}{6}\lambda^2 - \frac{32}{3}\lambda^3 + 17\lambda^4 - 8\lambda^5,$$

$$(3.15) \quad B(\lambda) = -\frac{1}{576} + \frac{1}{18}\lambda - \frac{25}{36}\lambda^2 + \frac{13}{3}\lambda^3 - \frac{173}{12}\lambda^4 + \frac{76}{3}\lambda^5 - 22\lambda^6 + 8\lambda^7,$$

and then, solve numerically the equations $A(\lambda) = 0$ and $B(\lambda) = 0$, we obtain the real roots. $A(\lambda)$ has the real roots

$$\lambda_1 = 0.0939962451\dots; \lambda_2 = 0.3486234981\dots, \lambda_3 = 1.2805797610\dots,$$

and $B(\lambda)$ has the real roots:

$$\lambda'_1 = 0.1056624327\dots, \lambda'_2 = 0.1072789060\dots, \lambda'_3 = 0.2038425244\dots,$$

$$\lambda'_4 = \frac{1}{4}; \lambda'_5 = 0.3943375673\dots$$

The polynomials A and B take the factorized forms

$$(3.16) \quad A(\lambda) = -8(\lambda - \lambda_1)(\lambda - \lambda_2)(\lambda - \lambda_3)(\lambda^2 - a\lambda + b),$$

$$(3.17) \quad B(\lambda) = 8(\lambda - \lambda'_1)(\lambda - \lambda'_2)(\lambda - \lambda'_3)(\lambda - \lambda'_4)(\lambda - \lambda'_5)(\lambda^2 - a'\lambda + b'),$$

where $\lambda^2 - a\lambda + b$ and $\lambda^2 - a'\lambda + b'$ have no real roots, that is, they take only positive values.

We can now solve the system of inequalities

$$(3.18) \quad A(\lambda) \geq 0, \quad B(\lambda) \geq 0, \quad 0 < \lambda \leq 1,$$

by studying the sign of $A(\lambda)$ and $B(\lambda)$.

We obtain that (3.18) are satisfied if and only if $\lambda \in [\lambda'_5, 1]$.

Putting $\lambda'_5 = \alpha = 0.3943375673\dots$ it follows the first conclusion of the theorem. If we take for λ the value $\lambda = \lambda^* = 0.5728160625\dots$, we see that the coefficient of z^4 in the numerator P of stability function (2.7), vanishes, so the degree of P is less than the degree of Q and then we have (2.14). Because $\lambda^* \in [\alpha, 1]$ we can say that the subclass of semi-explicit methods with $\lambda = \lambda^*$ are L -stable.

We have used the Maple 6 and Mathematica 5 packages for numerical solving of equations $A(\lambda) = 0$ and $B(\lambda) = 0$. \square

Example 3.5. We present five example of semi-explicit Runge-Kutta methods of order 3 with four stages, the first four methods are A -stable and the last, L -stable.

$$(3.19) \quad \begin{array}{c|cccc} \frac{1}{2} & \frac{1}{2} & 0 & 0 & 0 \\ \frac{1}{5} & -\frac{3}{10} & \frac{1}{2} & 0 & 0 \\ \frac{2}{3} & -\frac{1}{9} & \frac{5}{18} & \frac{1}{2} & 0 \\ 1 & -\frac{4}{5} & 1 & \frac{3}{10} & \frac{1}{2} \\ \hline & \frac{22}{45} & \frac{5}{9} & \frac{9}{10} & \frac{1}{30} \end{array}$$

$$(3.20) \quad \begin{array}{c|cccc} \frac{3}{5} & \frac{3}{5} & 0 & 0 & 0 \\ \frac{2}{5} & -\frac{1}{5} & \frac{3}{5} & 0 & 0 \\ \frac{1}{5} & -\frac{4}{5} & \frac{2}{5} & \frac{3}{5} & 0 \\ \frac{1}{5} & -\frac{1}{5} & \frac{2}{5} & \frac{4}{5} & \frac{3}{5} \\ 1 & 0 & -\frac{2}{5} & \frac{4}{5} & \frac{3}{5} \\ \hline & \frac{5}{12} & 0 & \frac{5}{12} & \frac{1}{6} \end{array}$$

$$(3.21) \quad \begin{array}{c|cccc} \frac{3}{4} & \frac{3}{4} & 0 & 0 & 0 \\ \frac{1}{2} & -\frac{1}{4} & \frac{3}{4} & 0 & 0 \\ \frac{2}{2} & \frac{7}{7} & \frac{21}{21} & \frac{3}{3} & 0 \\ \frac{5}{2} & \frac{10}{10} & -\frac{20}{20} & \frac{4}{5} & \frac{3}{5} \\ \frac{2}{3} & 0 & \frac{1}{3} & -\frac{12}{12} & \frac{4}{4} \\ \hline & \frac{184}{63} & \frac{10}{9} & \frac{425}{504} & -\frac{31}{8} \end{array}$$

$$(3.22) \quad \begin{array}{c|cccc} \frac{3}{5} & \frac{3}{5} & 0 & 0 & 0 \\ \frac{1}{5} & \frac{2}{5} & \frac{3}{5} & 0 & 0 \\ \frac{2}{5} & \frac{1}{5} & \frac{3}{5} & \frac{3}{5} & 0 \\ \frac{4}{5} & \frac{1}{10} & -\frac{3}{10} & \frac{3}{5} & 0 \\ \frac{4}{5} & \frac{1}{5} & \frac{3}{5} & -\frac{3}{5} & \frac{3}{5} \\ \hline & \frac{1}{3} & \frac{5}{9} & -\frac{1}{4} & \frac{13}{36} \end{array}$$

$$(3.23) \quad \begin{array}{c|ccccc} 0.573 & 0.573 & & & \\ 0.400 & -0.173 & 0.573 & & \\ 0.600 & 0.072 & -0.045 & 0.573 & \\ 1.000 & 0 & 1.281 & -0.854 & 0.573 \\ \hline & 0 & \frac{10}{9} & -\frac{5}{12} & \frac{11}{36} \end{array}$$

4. THE CONSTRUCTION OF A -STABLE AND L -STABLE METHODS OF ORDER 4

Now, we are focusing on semi-explicit Runge-Kutta methods, generated by the second tableau of (2.6), having order $p = 4$ and $s = 5$ stages. The order conditions become, in this case (see [2, p.170])

$$(4.1) \quad \sum_{i=1}^5 b_i c_i^{k-1} = \frac{1}{k}, \quad k = 1, 2, 3, 4$$

$$(4.2) \quad \sum_{i=2}^5 b_i \sum_{j=1}^{i-1} a_{ij} c_j = \frac{1}{6} - \frac{\lambda}{2},$$

$$(4.3) \quad \sum_{i=2}^5 b_i c_i \sum_{j=1}^{i-1} a_{ij} c_j = \frac{1}{8} - \frac{\lambda}{3},$$

$$(4.4) \quad \sum_{i=2}^5 b_i \sum_{j=1}^{i-1} a_{ij} c_j^2 = \frac{1}{12} - \frac{\lambda}{4},$$

$$(4.5) \quad \sum_{i=3}^5 b_i \sum_{j=2}^{i-1} a_{ij} \sum_{k=1}^{j-1} a_{jk} c_k = \frac{1}{24} - \frac{\lambda}{3} + \frac{\lambda^2}{2},$$

with additional conditions (2.5), that is

$$(4.6) \quad c_1 = \lambda, \quad c_2 = a_{21} + \lambda, \quad c_3 = a_{31} + a_{32} + \lambda,$$

$$(4.7) \quad c_4 = a_{41} + a_{42} + a_{43} + \lambda,$$

$$(4.8) \quad c_5 = a_{51} + a_{52} + a_{53} + a_{54} + \lambda.$$

We are seeking for values of parameters $b_i, c_i, a_{ij}, \lambda$, usually $0 < c_i \leq 1$ $i = 1, 2, 3, 4, 5$, so $0 < \lambda \leq 1$, distinct, such that the equations (4.1)-(4.8) be satisfied and also the conditions (2.13) for A -stability or (2.13) and (2.14) for L -stability satisfied.

The complete solutions of the nonlinear algebraic system (4.1)-(4.8) is not an easy problem, but every solution of this system, provides one semi-explicit (diagonally implicit) Runge-Kutta method of order 4 with $s = 5$ stages.

We will not give the complete solutions of the system (4.1)-(4.8) because it has a very complicated form.

We can state

Theorem 4.1. *The solution of the system (4.1)-(4.8) provide A -stable Runge-Kutta methods of order 4 with five stages if and only if*

$$\lambda \in [\alpha, \beta] \cup [\gamma, \delta],$$

where

$$\begin{aligned} \alpha &= 0.0701257\dots, & \beta &= 0.0726521\dots, \\ \gamma &= 0.2402928\dots, & \delta &= 0.4732683\dots \end{aligned}$$

Moreover for $\lambda = \lambda_1 = 0.07075122\dots$ or $\lambda = \lambda_2 = 0.2780538\dots$, the corresponding solutions of the system (4.1)-(4.8) provide two subclasses of L -stable Runge-Kutta methods of order 4 with five stages.

Proof. The E -polynomial (2.12) for methods with $s = 5$ stages can be written, using (2.10) and (2.11), as

$$(4.9) \quad E(y^2, \lambda) = A_1(\lambda)y^6 + A_2(\lambda)y^8 + A_3(\lambda)y^{10},$$

where

$$(4.10) \quad A_1(\lambda) = -\frac{1}{360} + \frac{1}{12}\lambda - \frac{5}{6}\lambda^2 + \frac{10}{3}\lambda^3 - 5\lambda^4 + 2\lambda^5,$$

$$(4.11) \quad \begin{aligned} A_2(\lambda) &= \frac{1}{960} - \frac{1}{24} \lambda + \frac{47}{72} \lambda^2 - \frac{31}{6} \lambda^3 + \\ &+ \frac{265}{12} \lambda^4 - \frac{151}{3} \lambda^5 + 55\lambda^6 - 20\lambda^7, \end{aligned}$$

$$(4.12) \quad \begin{aligned} A_3(\lambda) &= -\frac{1}{14400} + \frac{1}{288} \lambda - \frac{41}{576} \lambda^2 + \frac{56}{9} \lambda^3 - \frac{89}{18} \lambda^4 + \\ &+ \frac{563}{30} \lambda^5 - \frac{505}{12} \lambda^6 + \frac{160}{3} \lambda^7 - 35\lambda^8 + 10\lambda^9. \end{aligned}$$

If we find numerically the real roots of the polynomials $A_1(\lambda)$, $A_2(\lambda)$, $A_3(\lambda)$, then we can solve the inequalities

$$(4.13) \quad A_1(\lambda) \geq 0, \quad A_2(\lambda) \geq 0, \quad A_3(\lambda) \geq 0, \quad 0 < \lambda \leq 1,$$

by studying the sign of $A_1(\lambda)$, $A_2(\lambda)$, $A_3(\lambda)$.

We obtain that (4.13) hold for $\lambda \in [\alpha, \beta] \cup [\gamma, \delta]$, where $\alpha = 0.0701257\dots$, $\beta = 0.072652\dots$, $\gamma = 0.2402928404\dots$, and $\delta = 0.4732683912\dots$, and then with (4.9)

$$(4.14) \quad E(y^2, \lambda) \geq 0, \quad y \in \mathbb{R}, \quad \lambda \in [\alpha, \beta] \cup [\gamma, \delta].$$

The last condition is sufficient for A -stability of every method, solution of the system (4.1)-(4.8), which ensures the order $p = 4$ of the method.

If we take $\lambda = \lambda_1 = 0.075122\dots \in [\alpha, \beta]$ and $\lambda = \lambda_2 = 0.2780538411 \in [\gamma, \delta]$, then we can check that the coefficient of z^5 of the polynomial $P(z, \lambda)$ from (2.10), vanishes. In this case the condition (2.14) is fulfilled, so every solution of the system (4.1)-(4.8) with $\lambda = \lambda_1$ or $\lambda = \lambda_2$ provides one L -stable semi-explicit Runge-Kutta method of order $p = 4$ with $s = 5$ stages.

Again, we mention that we used the Maple 6 and Mathematica 5 packages for numerical root finding for polynomials (4.10), (4.11), (4.12).

In the next we will give only two particular solutions of the system (4.1)-(4.8), i.e. two particular A -stable or L -stable methods. \square

Example 4.2. We present two semi-explicit Runge-Kutta methods of order 4 with five stages i.e. two solutions of the system (4.1)-(4.8), the first method (4.15) is A -stable and the last, (4.16), L -stable.

It is clearly that the coefficients of the Runge-Kutta methods (3.23) and (4.16) can be given with arbitrary accuracy.

$$(4.15) \quad \begin{array}{c|cccccc} 2 & 2 & & & & & \\ \hline 5 & 5 & & & & & \\ 3 & 1 & 2 & & & & \\ \hline 5 & 5 & 5 & & & & \\ 4 & 1 & 1 & 2 & & & \\ \hline 5 & 5 & 5 & 5 & & & \\ 1 & 1 & 8 & 16 & 2 & & \\ \hline 5 & \frac{19}{5} & -\frac{19}{5} & \frac{95}{5} & \frac{2}{5} & & \\ 1 & \frac{1337}{435} & -\frac{1934}{435} & \frac{454}{261} & \frac{304}{1305} & \frac{2}{5} & \\ \hline & \frac{55}{72} & \frac{5}{4} & -\frac{25}{72} & \frac{95}{144} & \frac{29}{144} & \end{array}$$

$$(4.16) \quad \begin{array}{c|cccccc} 0.278053 & 0.278053 & & & & & \\ 0.200000 & -0.078053 & 0.278053 & & & & \\ 0.600000 & -0.340512 & 0.667068 & 0.278053 & & & \\ 0.800000 & 0.905887 & 0 & -0.383939 & 0.278053 & & \\ 1.000000 & 20.823214 & -13.830951 & -9.962345 & 3.692028 & 0.278053 & \\ \hline & -4.221747 & 3.262906 & 4.168667 & -2.926083 & 0.916683 & \end{array}$$

Acknowledgment.

The author would like to thank the professor Damian Trif from Babeş-Bolyai University Cluj-Napoca for their observations and suggestions regarding the concrete examples given in the first version of this paper.

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