

## Positive solutions of nonlinear functional-integral equations

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ABSTRACT. In this paper we study the conditions are required for existence of at least one positive solution of the functional-integral equation

$$u(x) = g(x) + \int_0^h k(x, s) F(u)(s) ds, \quad x \in [0, h]$$

where  $F : C[0, h] \rightarrow C[0, h]$  is an operator. Our approach to the problem is based on the Krasnoselskii's compression-expansion fixed point theorem.

### 1. INTRODUCTION

In this paper, we consider the nonlinear integral equation

$$(1.1) \quad u(x) = g(x) + \int_0^h k(x, s) F(u)(s) ds, \quad x \in [0, h]$$

where  $F : C[0, h] \rightarrow C[0, h]$ ,  $g : [0, h] \rightarrow \mathbb{R}$  and  $k : [0, h] \times [0, h] \rightarrow \mathbb{R}$ . In particular case, when  $F$  is the Nemitskii's operator attached to the function  $f : [0, h] \times \mathbb{R} \rightarrow \mathbb{R}$ , i.e. for  $u \in C[0, h]$

$$F(u)(x) = N_f u(x) = f(x, u(x)), \quad x \in [0, h],$$

then equation (1.1) became

$$(1.2) \quad u(x) = g(x) + \int_0^h k(x, s) f(s, u(s)) ds, \quad x \in [0, h].$$

The existence of positive solutions for (1.2) was studied in several papers [1, 2, 5, 7, 8, 9] and reference therein. For example, in [5] are established existence results of positive solutions for (1.2) and their applications to the boundary-value problem with integral boundary conditions. In [1], the equation (1.2) is used to study the solutions for the two-point boundary value problem.

The idea of this paper was suggest in [7], where are presented existence results of multiple nonnegative continuous solutions of a nonlinear integral equation on both a compact interval and semi-infinite interval. Applications

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Received: 11.05.2003; In revised form: 08.02.2004

2000 *Mathematics Subject Classification.* 45G10, 45M20, 47G10.

Key words and phrases. *Krasnoselskii's fixed point theorem, Banach space, nonlinear Fredholm integral equations.*

of this result to localize solutions of some boundary valued problem are presented in [2, 4].

The main result is obtained by applying the well known fixed point theorem due to Krasnoselskii [6]. Let us recall this result:

**Theorem 1.1.** [Krasnoselskii's compression-expansion fixed point theorem] *Let  $X$  be a Banach space, and let  $K \subset X$  be a con in  $X$ . Assume that  $\Omega_1, \Omega_2$  are two open subsets of  $X$  such that  $0 \in \Omega_1$  and  $\bar{\Omega}_1 \subset \Omega_2$ . Consider the operator  $T : K \cap (\bar{\Omega}_2 \setminus \Omega_1) \rightarrow K$  be completely continuous and either*

$$\|T(x)\| \leq \|x\|, \quad x \in K \cap \Omega_1 \quad \text{and} \quad \|T(x)\| \geq \|x\|, \quad x \in K \cap \Omega_2$$

or

$$\|T(x)\| \geq \|x\|, \quad x \in K \cap \Omega_1 \quad \text{and} \quad \|T(x)\| \leq \|x\|, \quad x \in K \cap \Omega_2$$

is true. Then  $T$  has a fixed point in  $K \cap (\bar{\Omega}_2 \setminus \Omega_1)$ .

## 2. PRELIMINARY RESULTS

Consider that  $C[0, h]$  is the Banach space of all continuous functions  $u : [0, h] \rightarrow \mathbb{R}$ , endowed with the norm  $\|\cdot\|$ , where

$$(2.3) \quad \|u\| = \sup_{x \in [0, h]} |u(x)|, \quad u \in C[0, h].$$

Let us suppose that the following conditions are satisfied:

- ( $h_1$ )  $0 \leq k_x(s) = k(x, s) \in L^1[0, h]$  for  $x \in [0, h]$ ;
- ( $h_2$ ) the map  $x \mapsto k_x$  is continuous from  $[0, h]$  to  $L^1[0, h]$ ;
- ( $h_3$ ) there exists  $M \in (0, 1)$ ,  $\tilde{k} \in L^1[0, h]$  and an interval  $[a, b] \subset [0, h]$  such that  $k(x, s) \geq M\tilde{k}(s) \geq 0$ ,  $x \in [a, b]$ , a.e.  $s \in [0, h]$ ;
- ( $h_4$ )  $k(x, s) \leq \tilde{k}(s)$ ,  $x \in [0, h]$ , a. e.  $s \in [0, h]$ ;
- ( $h_5$ )  $g \in C[0, h]$  with  $g(x) \geq 0$ ,  $x \in [0, h]$  and  $\min_{a \leq x \leq b} g(x) \geq M \|g\|$ .

By considering some arguments from [5], we obtain the following sufficient conditions for ( $h_3$ ) and ( $h_4$ ), introduced by D. O'Regan and M. Meehan in [7].

**Lemma 2.1.** *Assume that*

(CC)  $k(\cdot, s) = \mathbf{k}$  is nonnegative, concave and nondecreasing a.e.  $s \in [0, h]$ , then ( $h_3$ ) and ( $h_4$ ) hold.

*Proof.* Let  $\eta \in (0, h)$ . Concavity of  $\mathbf{k}$  implies

$$\frac{\mathbf{k}(h) - \mathbf{k}(0)}{h} \geq \frac{\mathbf{k}(h) - \mathbf{k}(\eta)}{h - \eta}.$$

Hence

$$(2.4) \quad \mathbf{k}(\eta) \geq \frac{\eta}{h} \mathbf{k}(h) + \left(1 - \frac{\eta}{h}\right) \mathbf{k}(0).$$

Since  $\mathbf{k}$  is nonnegative, we may have  $\mathbf{k}(\eta) \geq M\mathbf{k}(h)$ . Therefore,

$$\frac{\eta}{h} k(h, s) \leq k(\eta, s) \leq k(x, s), x \in [\eta, h], \text{ a.e. } s \in [0, h].$$

Hence, the hypothesis  $(h_3)$  is satisfied for  $M = \frac{\eta}{h}$ ,  $[a, b] = [\eta, h]$  and  $\tilde{k}(s) = k(h, s)$  for any  $\eta \in (0, h)$ .  $\square$

**Lemma 2.2.** *If we assume that*

(CD)  $k(\cdot, s) = \mathbf{k}$  is nonnegative, concave and nonincreasing a.e.  $s \in [0, h]$ , then  $(h_3)$  and  $(h_4)$  hold.

*Proof.* Concavity of  $\mathbf{k}$  implies (2.4). Since  $\mathbf{k}$  is nonnegative, we can choose  $\mathbf{k}(\eta) \geq \left(1 - \frac{\eta}{h}\right) \mathbf{k}(0)$ . Because  $\mathbf{k}$  is nonincreasing, we get

$$\left(1 - \frac{\eta}{h}\right) k(0, s) \leq k(\eta, s) \leq k(x, s), x \in [0, \eta], \text{ a.e. } s \in [0, h].$$

Therefore, the hypothesis  $(h_3)$  is satisfied for  $M = 1 - \frac{\eta}{h}$ ,  $[a, b] = [0, \eta]$  and  $\tilde{k}(s) = k(0, s)$  for any  $\eta \in (0, h)$ .  $\square$

Let  $K : C[0, h] \rightarrow C[0, h]$  be an operator defined as follows

$$Kv(x) = g(x) + \int_0^h k(x, s) v(s) ds, \quad x \in [0, h].$$

Then equation (1.1) is equivalent to the fixed point problem

$$(2.5) \quad Tu = u,$$

where  $T : C[0, h] \rightarrow C[0, h]$  is given by  $T = KF$ .

Let  $[a, b]$  be the interval given by the hypothesis  $(h_3)$  and

$$C_K = \left\{ u \in C[0, h]; u(x) \geq 0, x \in [0, h] \text{ and } \min_{x \in [a, b]} u(x) \geq M \|u\| \right\}.$$

**Lemma 2.3.** *If hypotheses  $(h_1) - (h_5)$  are satisfied, then the operator  $K : C_K \rightarrow C[0, h]$  is well defined, continuous and completely continuous.*

*Proof.* By conditions  $(h_1)$ ,  $(h_2)$  and  $(h_5)$  results that  $K$  is completely continuous.

Let  $v \in C[0, h]$  be such that  $v(x) \geq 0$ ,  $x \in [0, h]$ . By  $(h_1)$ ,  $(h_2)$ ,  $(h_4)$  and  $(h_5)$  we have

$$(2.6) \quad \begin{aligned} \|Kv\| &= \sup_{x \in [0, h]} \left( g(x) + \int_0^h k(x, s) v(s) ds \right) \\ &\leq |g|_0 + \int_0^h \tilde{k}(s) v(s) ds. \end{aligned}$$

By  $(h_1)$ – $(h_3)$  and  $(h_5)$  we obtain

$$(2.7) \quad \begin{aligned} \min_{x \in [a, b]} K v(x) &= \min_{x \in [a, b]} \left( g(x) + \int_a^b k(x, s) v(s) ds \right) \\ &\geq M \left( \|g\| + \int_0^h \tilde{k}(s) v(s) \right) \end{aligned}$$

From (2.6) and (2.7) results  $\min_{x \in [a, b]} K v(x) \geq M \|K v\|$ . So,  $K v \in C_K$  for any  $v \in C_K$ .  $\square$

### 3. MAIN RESULT

**Theorem 3.2.** *Suppose that  $(h_1)$ – $(h_5)$  are satisfied and*

*$(H_1)$  the operator  $F : C[0, h] \rightarrow C[0, h]$  is continuous and increasing, i.e. for  $u, v \in C[0, h]$  with  $u < v$  implies  $F(u) < F(v)$ ;*

*$(H_2)$  there exists  $\alpha > 0$  such that  $\frac{\alpha}{\|g\| + K_1 F(\alpha)} > 1$ , where*

$$K_1 = \sup_{0 \leq x \leq h} \int_0^h k(x, s) ds > 0;$$

*$(H_3)$  there exist  $\beta > 0$ ,  $\alpha \neq \beta$  and  $x_0 \in [0, h]$  such that*

$$\frac{\beta}{g(x_0) + F(M\beta) \int_a^b k(x_0, s) ds} < 1;$$

*hold. Then, (1.1) has at least one nonnegative solution  $u \in C[0, h]$  and either*

*(A)  $0 < \alpha \leq \|u\| \leq \beta$  and  $u(x) \geq M\alpha$  for  $x \in [a, b]$  if  $\alpha < \beta$ ;*

*or*

*(B)  $0 < \beta \leq \|u\| \leq \alpha$  and  $u(x) \geq M\beta$  for  $x \in [a, b]$  if  $\alpha > \beta$ .*

*holds.*

*Proof.* Let  $\Omega_1$  and  $\Omega_2$  be a subsets in  $C[0, h]$  given by

$$\Omega_1 = \{u \in C[0, h]; \|u\| < \alpha\} \text{ and } \Omega_2 = \{u \in C[0, h]; \|u\| < \beta\}$$

Define the operator  $T : C_K \rightarrow C_K$  by

$$(3.8) \quad Tu(x) = KF(u)(x) = g(x) + \int_0^h k(x, s) F(u)(s) ds.$$

Since  $F$  is continuous and using Lemma 2.3, we have  $T$  completely continuous. In what it follows, we will apply the Krasnoselskii's fixed point theorem for  $T$ . Therefore, we prove that

$$(3.9) \quad \|Tu\| < \|u\|, u \in C_K \cap \partial\Omega_1,$$

and

$$(3.10) \quad \|Tu\| > \|u\|, u \in C_K \cap \partial\Omega_2.$$

Let  $u \in C_K \cap \partial\Omega_1$ , i.e.  $u(x) \geq 0$ ,  $x \in [0, h]$  and  $\|u\| = \alpha$ .

We have

$$(3.11) \quad \begin{aligned} \sup_{x \in [0, h]} |Tu(x)| &= \sup_{x \in [0, h]} \left( g(x) + \int_0^h k(x, s) F(u)(s) ds \right) \\ &\leq \sup_{x \in [0, h]} g(x) + F(\alpha) \sup_{x \in [0, h]} \int_0^h k(x, s) ds \\ &\leq \|g\| + K_1 F(\alpha) \\ &< \alpha = \|u\|. \end{aligned}$$

If  $u \in C_K \cap \partial\Omega_2$ , then  $u(x) \geq 0$ ,  $x \in [0, h]$ ,  $\|u\| = \beta$  and  $M\beta \leq u(x) \leq \beta$ ,  $x \in [a, b]$ . Then

$$(3.12) \quad \begin{aligned} T(u)(x_0) &= g(x_0) + \int_0^h k(x_0, s) F(u)(s) ds \\ &\geq g(x_0) + \int_a^b k(x_0, s) F(u)(s) ds \\ &\geq g(x_0) + F(M\beta) \int_a^b k(x_0, s) ds \\ &> \beta = \|u\|. \end{aligned}$$

Therefore, (3.11), (3.12) proves (3.9), (3.10) respectively.  $\square$

If we replace the hypothesis  $(h_3)$  and  $(h_4)$  with (CC) from Lemma 2.1 we get the following result

**Corollary 3.1.** *Suppose that  $(h_1)$ ,  $(h_2)$ , (CC),  $(h_5)$ ,  $(H_1)$  and*

*$(HC_1)$  there exists  $\alpha > 0$  such that  $\alpha > \|g\| + F(\alpha) \int_0^h k(h, s) ds$ ;*

*$(HC_2)$  there exists  $\beta > 0$ ,  $\beta \neq \alpha$  such that for  $\eta \in (0, h)$  we have*

$$\beta < \min_{x \in [0, h]} g(x) + F\left(\frac{\eta\beta}{h}\right) \int_{\eta}^h k(0, s) ds.$$

*Then, (1.1) has at least one nonnegative solution  $u \in C[0, h]$  and either*

*(AC)  $0 < \alpha \leq \|u\| \leq \beta$  and  $u(x) \geq \frac{\eta\alpha}{h}$  for  $x \in [\eta, h]$  if  $\alpha < \beta$ ;*

*or*

*(BC)  $0 < \beta \leq \|u\| \leq \alpha$  and  $u(x) \geq \frac{\eta\beta}{h}$  for  $x \in [\eta, h]$  if  $\alpha > \beta$ .*

*holds.*

Using Lemma 2.2 we get

**Corollary 3.2.** *Suppose that  $(h_1)$ ,  $(h_2)$ , (CD),  $(h_5)$ ,  $(H_1)$  and*

*$(HD_1)$  there exists  $\alpha > 0$  such that  $\alpha > \|g\| + F(\alpha) \int_0^h k(0, s) ds$ ;*

(HD<sub>2</sub>) there exists  $\beta > 0$ ,  $\beta \neq \alpha$  such that for  $\eta \in (0, h)$  we have

$$\beta < \min_{x \in [0, h]} g(x) + F \left( \frac{(h - \eta)\beta}{h} \right) \int_0^\eta k(h, s) ds.$$

Then, (1.1) has at least one nonnegative solution  $u \in C[0, h]$  and either

(AD)  $0 < \alpha \leq \|u\| \leq \beta$  and  $u(x) \geq \frac{(h-\eta)\alpha}{h}$  for  $x \in [0, \eta]$  if  $\alpha < \beta$ ;

or

(BD)  $0 < \beta \leq \|u\| \leq \alpha$  and  $u(x) \geq \frac{(h-\eta)\beta}{h}$  for  $x \in [0, \eta]$  if  $\alpha > \beta$ .

holds.

These two corollaries contain conditions which are similar with conditions required in [5] and are very easy to check in applications.

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