

## Advances on affine vector fields

ARIANA PITEA and M. POSTOLACHE

### ABSTRACT.

Section 1 is introductory in nature [7], [8], while Section 2 contains our results. Section 1 presents certain results on affine mappings [7] and some notions about jet bundles [10]. All of these results are necessary to develop our theory in Section 2. Here we define the energy of a  $d$ -tensor field on the first order jet bundle and we prove that this energy is positively homogeneous of degree  $m - p$  with respect to the partial velocities. Then the total derivative is used to introduce affine vector fields. We prove that these fields are tangent to the spherical bundle. Our main result (Theorem 2.3) joins a symmetric tensor field, its associated energy and the affine vector fields into an original hyperbolic PDE.

### 1. INTRODUCTION

Let  $(M, g)$  and  $(\mathbb{R}^p, h)$  be Riemannian manifolds of dimensions  $n$  and  $p$ . The local coordinates on  $M$  and  $\mathbb{R}^p$  will be written  $x = (x^i)$ ,  $i = \overline{1, n}$ , and  $t = (t^\alpha)$ ,  $\alpha = \overline{1, p}$ , and the Christoffel symbols will be denoted by  $G_{jk}^i, H_{\beta\gamma}^\alpha$  respectively. To state our results, we need some background from [7], [9]:

**Definition 1.1.** A mapping  $\gamma: \mathbb{R}^p \rightarrow M$  is called affine if it moves the geodesics of the manifold  $(\mathbb{R}^p, h)$  into geodesics of the manifold  $(M, g)$ .

Let  $t^\alpha = t^\alpha(s)$ ,  $s \in I \subseteq \mathbb{R}$ ,  $0 \in I$ ,  $t^\alpha(0) = 0$ ,  $\alpha = \overline{1, p}$ , be a geodesic of  $\mathbb{R}^p$ , that is a solution of the differential system

$$\frac{d^2 t^\alpha}{ds^2} + H_{\beta\nu}^\alpha \frac{dt^\beta}{ds} \frac{dt^\nu}{ds} = 0, \quad \alpha = \overline{1, p}.$$

From  $x^i(s) = x^i(t^\alpha(s))$ , it follows  $\frac{dx^i}{ds} = \frac{\partial x^i}{\partial t^\alpha} \frac{dt^\alpha}{ds}$ ,  $i = \overline{1, n}$ . Differentiating once again, we obtain

$$\frac{d^2 x^i}{ds^2} = \frac{\partial^2 x^i}{\partial t^\alpha \partial t^\beta} \frac{dt^\alpha}{ds} \frac{dt^\beta}{ds} + \frac{\partial x^i}{\partial t^\alpha} \frac{d^2 t^\alpha}{ds^2} = \left( \frac{\partial^2 x^i}{\partial t^\beta \partial t^\nu} - H_{\beta\nu}^\alpha x_\alpha^i \right) \frac{dt^\beta}{ds} \frac{dt^\nu}{ds}, \quad i = \overline{1, n}.$$

Then

$$\frac{d^2 x^i}{ds^2} + G_{jk}^i \frac{dx^j}{ds} \frac{dx^k}{ds} = \left( \frac{\partial^2 x^i}{\partial t^\beta \partial t^\nu} - H_{\beta\nu}^\alpha x_\alpha^i + G_{jk}^i x_\beta^j x_\nu^k \right) \frac{dt^\beta}{ds} \frac{dt^\nu}{ds}, \quad i = \overline{1, n}.$$

Since  $x^i = x^i(s)$ ,  $i = \overline{1, n}$ , is a geodesic of  $M$ , we obtain

$$\frac{d^2 x^i}{ds^2} + G_{jk}^i \frac{dx^j}{ds} \frac{dx^k}{ds} = 0, \quad i = \overline{1, n},$$

hence we proved the following result.

**Proposition 1.1.** If the mapping  $\gamma: \mathbb{R}^p \rightarrow M$ ,  $\gamma(t) = (x^1(t), \dots, x^n(t))$  is affine, then it is solution of the hyperbolic PDEs system

$$\frac{\partial^2 x^i}{\partial t^\alpha \partial t^\beta} - H_{\alpha\beta}^\nu x_\nu^i + G_{jk}^i x_\alpha^j x_\beta^k = 0, \quad \alpha, \beta = \overline{1, p}, \quad i = \overline{1, n}.$$

**Theorem 1.1.** Suppose that the hyperbolic PDEs system

$$\frac{\partial^2 x^i}{\partial t^\alpha \partial t^\beta} - H_{\alpha\beta}^\nu x_\nu^i + G_{jk}^i x_\alpha^j x_\beta^k = 0, \quad \alpha, \beta = \overline{1, n}, \quad i = \overline{1, n},$$

has solutions of  $C^3$ -class, where  $H_{\beta\alpha\lambda}^\nu$  and  $G_{kjl}^i$  are the Riemann tensors of the manifolds  $(\mathbb{R}^p, h)$ ,  $(M, g)$  respectively. Then the complete integrability conditions are equivalent to

$$H_{\beta\alpha\lambda}^\nu x_\nu^i = G_{kjl}^i x_\lambda^k x_\alpha^j x_\beta^l, \quad \alpha, \beta, \lambda = \overline{1, p}, \quad i = \overline{1, n}.$$

For a proof, see [4], [5].

To end these preliminaries, let us point out some notions about jet bundles, [3], [10]. Let us consider the bundle  $(\mathbb{R}^p \times M, \pi_1, \mathbb{R}^p)$ , where  $\pi_1$  is the projection  $\pi_1: \mathbb{R}^p \times M \rightarrow \mathbb{R}^p$ .

**Definition 1.2.** A mapping  $\phi: I \subset \mathbb{R}^p \rightarrow \mathbb{R}^p \times M$  is called local section of  $(\mathbb{R}^p \times M, \pi_1, \mathbb{R}^p)$  if it satisfies the condition  $\pi_1 \circ \phi = id_I$ . If  $t \in \mathbb{R}^p$ , then the set of all local sections of  $\pi_1$ , whose domains contain the point  $t$ , will be denoted  $\Gamma_t(\pi_1)$ .

Received: 12.11.2008; In revised form: 17.06.2009; Accepted: 27.08.2009

2000 Mathematics Subject Classification. 53C65, 58J60.

Key words and phrases. Affine mapping, first order jet bundle, energy of a  $d$ -tensor field, hyperbolic PDE.

If  $\phi \in \Gamma_t(\pi_1)$  and  $(t^\alpha, x^i)$  are coordinate functions around  $\phi(t) \in \mathbb{R}^p \times M$ , then  $x^i(\phi(t)) = \phi^i(t)$ .

**Definition 1.3.** Two local sections  $\phi, \psi \in \Gamma_t(\pi_1)$  are called 1-equivalent at the point  $t$  if

$$\begin{aligned}\phi(t) &= \psi(t), \\ \frac{\partial \phi^i}{\partial t^\alpha}(t) &= \frac{\partial \psi^i}{\partial t^\alpha}(t), \quad i = \overline{1, n}, \alpha = \overline{1, p}.\end{aligned}$$

The equivalence class containing  $\phi$  is called the 1-jet of  $\phi$  at the point  $t$  and is denoted by  $j_t^1 \phi$ .

**Definition 1.4.** The set  $J^1(\mathbb{R}^p, M) = \{j_t^1 \phi \mid t \in \mathbb{R}^p, \phi \in \Gamma_t(\pi_1)\}$  is called first order jet bundle.

**Definition 1.5.** Let  $(U, (t^\alpha, x^i))$  be an adapted coordinate system on  $\mathbb{R}^p \times M$ . The induced coordinate system  $(U^1, u^1)$  on  $J^1(\mathbb{R}^p, M)$  is defined by

$$U^1 = \{j_t^1 \phi \mid \phi(t) \in U\}, \quad u^1 = (t^\alpha, x^i, x_\alpha^i),$$

where

$$\begin{aligned}t^\alpha(j_t^1 \phi) &= t^\alpha(t), \\ x^i(j_t^1 \phi) &= x^i(\phi(t)), \\ x_\alpha^i(j_t^1 \phi) &= \frac{\partial \phi^i}{\partial t^\alpha}(t).\end{aligned}$$

$x_\alpha^i : U^1 \rightarrow \mathbb{R}$  are called derivative coordinates on  $U^1$ .

Now we pass to the subject of our paper, formulating original results.

## 2. MAIN RESULTS

Here, we use an affine mapping

$$\gamma_{x, \xi_\mu} : \Omega \rightarrow M, \quad \Omega = \prod_{\alpha=1}^p [\tau_-^\alpha(x, \xi_\mu), \tau_+^\alpha(x, \xi_\mu)],$$

of  $C^\infty$ -class, determined by the initial conditions  $\gamma_{x, \xi_\mu}(0) = x$ ,  $(\gamma_{x, \xi_\mu})_\alpha^i(0) = \xi_\alpha^i$ ,  $\alpha = \overline{1, p}$ , whose image is fixed by a closed border  $\sigma$  of dimension  $p - 1$  included into  $\partial M$ .

Let  $(x; \xi_1, \dots, \xi_p)$ ,  $x \in M$ ,  $\xi_\alpha \in \mathbb{R}_x^p M$ ,  $\xi_\alpha \neq 0$ ,  $\alpha = \overline{1, p}$ . In a neighborhood  $\mathcal{U} \subset M$  of the point  $x \in M$  we consider a local coordinate system  $(x^1, \dots, x^n)$ . Then  $\xi_\alpha = \xi_\alpha^i \frac{\partial}{\partial x^i}(x)$ ,  $\alpha = \overline{1, p}$ .

Suppose  $\partial M$  is foliated by submanifolds of type  $\sigma$ .

**Definition 2.6.** The pair of metrics  $(h, g)$  is called simple if for any closed border  $\sigma$  of dimension  $p - 1$  included into  $\partial M$ , there is an unique affine mapping

$$x : \Omega \cup \partial\Omega \rightarrow M \cup \partial M, \quad x(\Omega \cup \partial\Omega) \cap \partial M = \sigma,$$

$\Omega$  hyperparallelepiped in  $\mathbb{R}^p$ ,  $x(\Omega \setminus \partial\Omega) \subset M$ , such that  $x$  depends smoothly on  $\sigma$ .

Suppose that  $(h, g)$  is a pair of simple metrics.

A tensor field  $F_{i_1 \dots i_m}^{\alpha_1 \dots \alpha_m}$  is called symmetric if it does not change under the permutation of any two indices of the same type [2].

**Definition 2.7.** Let  $F_{i_1 \dots i_m}^{\alpha_1 \dots \alpha_m}$  be a symmetric tensor field of  $C^\infty$ -class and  $\gamma = \gamma_{x(t), x_\mu(t)}$  be the affine mapping of  $C^\infty$ -class given above.

Let  $\tau_-(x, x_\mu) = (\tau_-^1(x, x_\mu), \dots, \tau_-^p(x, x_\mu))$  and  $0 = (0, \dots, 0)$ . If  $\Omega_{\tau_-(x, x_\mu), 0}$  is the hyperparallelepiped with the diagonal opposite points  $\tau_-(x, x_\mu)$  and  $0$ , the function

$$u(t, x, x_\mu) = \int_{\Omega_{\tau_-(x, x_\mu), 0}} F_{i_1 \dots i_m}^{\alpha_1 \dots \alpha_m}(\gamma_{x, x_\mu}(s)) (\gamma_{x, x_\mu})_{\alpha_1}^{i_1}(s) \cdots (\gamma_{x, x_\mu})_{\alpha_m}^{i_m}(s) ds^1 \dots ds^p$$

is called the energy of the tensor field  $F$  along the affine mapping  $\gamma$ .

**Proposition 2.2.** Let  $F_{i_1 \dots i_m}^{\alpha_1 \dots \alpha_m}$  be a symmetric tensor field of  $C^\infty$ -class. Then the function  $u$  is positively homogeneous of degree  $m - p$  with respect to partial velocities  $x_\mu^j$ , that is

$$u(t, x, \lambda x_\mu) = \lambda^{m-p} u(t^\alpha, x^i, x_\mu), \quad \lambda > 0.$$

*Proof.* We change the variable, by denoting  $s = \tilde{s}\lambda^{-1}$ .

The Jacobian of this transformation is  $J = \lambda^{-p}$ , while the conditions  $\tau_-^\alpha(x, \lambda x_\mu) \leq s^\alpha \leq 0$ ,  $\alpha = \overline{1, p}$ , become  $\tau_-^\alpha(x, x_\mu) \leq \tilde{s}^\alpha \leq 0$ ,  $\alpha = \overline{1, p}$ , that is  $\tilde{s} \in \Omega_{\tau_-(x, x_\mu), 0}$ .

Therefore, we obtain

$$u(t, x, \lambda x_\mu) = \int_{\Omega_{\tau_-(x, \lambda x_\mu), 0}} F_{i_1 \dots i_m}^{\alpha_1 \dots \alpha_m}(\gamma_{x, \lambda x_\mu}(s)) (\gamma_{x, \lambda x_\mu})_{\alpha_1}^{i_1}(s) \cdots (\gamma_{x, \lambda x_\mu})_{\alpha_m}^{i_m}(s) ds^1 \dots ds^p,$$

or

$$u(t, x, \lambda x_\mu) = \int_{\Omega_{\tau_-(x, x_\mu), 0}} F_{i_1 \dots i_m}^{\alpha_1 \dots \alpha_m}(\gamma_{x, x_\mu}(\tilde{s})) \lambda (\gamma_{x, x_\mu})_{\alpha_1}^{i_1}(\tilde{s}) \cdots \lambda (\gamma_{x, x_\mu})_{\alpha_m}^{i_m}(\tilde{s}) \lambda^{-p} d\tilde{s}^1 \dots d\tilde{s}^p,$$

that is

$$u(t, x, \lambda x_\mu) = \lambda^{m-p} u(t^\alpha, x^i, x_\mu).$$

□

The affine structure of the first order jet bundle involves the affine vector fields, the energy of tensor fields on affine mappings and an hyperbolic PDE. To introduce those tools, we start with the total derivative of the function  $u$  with respect to  $t^\beta$ ,  $\beta = \overline{1, p}$ , that is

$$\begin{aligned} D_\beta u &= \frac{\partial u}{\partial t^\beta} + \frac{\partial u}{\partial x^i} x_\beta^i + \frac{\partial u}{\partial x_\alpha^i} \frac{\partial^2 x^i}{\partial t^\alpha \partial t^\beta} = \frac{\partial u}{\partial t^\beta} + \frac{\partial u}{\partial x^i} x_\beta^i \\ &\quad + (H_{\alpha\beta}^\nu x_\nu^i - G_{jk}^i x_\alpha^j x_\beta^k) \frac{\partial u}{\partial x_\alpha^i}, \quad \beta = \overline{1, p}. \end{aligned}$$

Thus we obtain the vector fields

$$H_\beta = \frac{\partial}{\partial t^\beta} + x_\beta^i \frac{\partial}{\partial x^i} + (H_{\alpha\beta}^\nu x_\nu^i - G_{jk}^i x_\alpha^j x_\beta^k) \frac{\partial}{\partial x_\alpha^i}, \quad \beta = \overline{1, p},$$

which are called affine vector fields.

**Theorem 2.2.** *The affine vector fields  $H_\beta$ ,  $\beta = \overline{1, p}$ , are tangent to the spherical bundle*

$$SM: h^{\alpha\beta} g_{ij} x_\alpha^i x_\beta^j = 1.$$

*Proof.* The field  $N_{SM}$ , normal to  $SM$ , is

$$N_{SM} = \frac{\partial h^{\alpha\beta}}{\partial t^\nu} g_{ij} x_\alpha^i x_\beta^j dt^\nu + h^{\alpha\beta} \frac{\partial g_{ij}}{\partial x^k} x_\alpha^i x_\beta^j dx^k + 2h^{\nu\beta} g_{\ell j} x_\beta^j x_\nu^\ell.$$

It is to notice the orthogonality

$$\begin{aligned} \langle N_{SM}, H_\lambda \rangle &= \frac{\partial h^{\alpha\beta}}{\partial t^\nu} g_{ij} x_\alpha^i x_\beta^j \delta_\lambda^\nu + h^{\alpha\beta} \frac{\partial g_{ij}}{\partial x^k} x_\alpha^i x_\beta^j x_\lambda^k + 2h^{\nu\beta} g_{jk} x_\beta^j x_\nu^k H_{\nu\lambda}^\varepsilon \\ &\quad - 2h^{\nu\beta} g_{jk} x_\beta^j x_\nu^\ell x_\lambda^q G_{\ell q}^k = \left( \frac{\partial h^{\alpha\beta}}{\partial t^\lambda} + 2h^{\nu\beta} H_{\nu\lambda}^\alpha \right) g_{ij} x_\alpha^i x_\beta^j \\ &\quad + h^{\alpha\beta} \left( \frac{\partial g_{ij}}{\partial x^k} - 2g_{\ell j} G_{ik}^\ell \right) x_\alpha^i x_\beta^j x_\lambda^k = 0, \end{aligned}$$

due to the equalities

$$\begin{aligned} G_{ik}^\ell &= \frac{1}{2} g^{\ell j} \left( \frac{\partial g_{kj}}{\partial x^i} + \frac{\partial g_{ij}}{\partial x^k} - \frac{\partial g_{ik}}{\partial x^j} \right), \\ \frac{\partial h^{\alpha\beta}}{\partial t^\lambda} &= -h^{\alpha\nu} H_{\lambda\nu}^\beta - h^{\nu\beta} H_{\lambda\nu}^\alpha. \end{aligned}$$

□

**Theorem 2.3.** *The symmetric tensor field  $F_{i_1 \dots i_m}^{\alpha_1 \dots \alpha_m}$ , the energy  $u$  and the differential operators  $H_\beta$ ,  $\beta = \overline{1, p}$ , are connected by the hyperbolic PDE*

$$(H_1 \circ H_2 \circ \dots \circ H_p)(u) = F_{i_1 \dots i_m}^{\alpha_1 \dots \alpha_m}(x) x_{\alpha_1}^{i_1} \cdots x_{\alpha_m}^{i_m}.$$

*Proof.* Let  $\gamma = \gamma_{x(t), x_\mu(t)}$  be an affine mapping, determined by its initial conditions, as above. Because of the equality  $\gamma_{x(t+t_0), x_\mu(t+t_0)}(s) = \gamma(s+t_0)$ , the following relation holds

$$\begin{aligned} u(t+t_0, x(t+t_0), x_\mu(t+t_0)) &= \int_{\Omega_{\tau_-(x, x_\mu), t_0}} F_{i_1 \dots i_m}^{\alpha_1 \dots \alpha_m}(\gamma_{x, x_\mu}(s)) (\gamma_{x, x_\mu})_{\alpha_1}^{i_1}(s) \cdots \\ &\quad \cdots (\gamma_{x, x_\mu})_{\alpha_m}^{i_m}(s) ds^1 \dots ds^p, \end{aligned}$$

where  $\Omega_{\tau_-(x, x_\mu), t_0}$  is the hyperparallelepiped with the opposite diagonal points  $\tau_-(x, x_\mu)$  and  $t_0 = (t_0^1, \dots, t_0^p)$ .

Differentiating the previous equality with respect to  $t_0^p$  and then considering  $t_0^p = 0$ , we obtain

$$D_p|_{t_0^p=0} u = \int_{\tau_-^1(x, x_\mu)}^{t_0^1} \dots \int_{\tau_-^{p-1}(x, x_\mu)}^{t_0^{p-1}} F_{i_1 \dots i_m}^{\alpha_1 \dots \alpha_m}(\gamma_{x, x_\mu}(s^1, \dots, s^{p-1}, 0)) \\ (\gamma_{x, x_\mu})_{\alpha_1}^{i_1}(s^1, \dots, s^{p-1}, 0) \dots (\gamma_{x, x_\mu})_{\alpha_m}^{i_m}(s^1, \dots, s^{p-1}, 0) ds^1 \dots ds^{p-1}.$$

This relation is differentiated with respect to  $t_0^{p-1}$  and then  $t_0^{p-1}$  is considered equal to 0, and so on, obtaining

$$D_1|_{t_0^1=0} \left( D_2|_{t_0^2=0} \dots \left( D_p|_{t_0^p=0} u \right) \right) = F_{i_1 \dots i_m}^{\alpha_1 \dots \alpha_m}(\gamma_{x, x_\mu}(0)) (\gamma_{x, x_\mu})_{\alpha_1}^{i_1}(0) \dots (\gamma_{x, x_\mu})_{\alpha_m}^{i_m}(0).$$

Therefore, we may conclude that

$$(H_1 \circ H_2 \circ \dots \circ H_p)(u) = F_{i_1 \dots i_m}^{\alpha_1 \dots \alpha_m}(x) x_{\alpha_1}^{i_1} \dots x_{\alpha_m}^{i_m} \quad (*)$$

□

The relation (\*) is called *the hyperbolic PDE on the first order jet bundle*.

We remark that Theorem 2.3 extends a work of Prof. Sharafutdinov, [6].

Regarding related research works, we address the reader to [1], [11].

**Acknowledgement.** The authors would like to acknowledge the continued support and encouragements provided by Prof. Dr. Constantin Udriște while this work was in preparation.

## REFERENCES

- [1] Hall, G. S., Capocci, M. S. and Beig, R., *Zeros of conformal vector fields*, Class. Quantum Grav., **14** L49- L52 (1997), DOI: 10.1088/0264-9381/14/3/002
- [2] Mishchenko, A. and Fomenko, A., *A Course of Differential Geometry and Topology*, Mir Publishers, Moscow, 1988
- [3] Neagu, M., *Riemann-Lagrange Geometry on 1-Jet Spaces*, MatrixRom, Bucharest, 2005
- [4] Pitea, Ariana, *Energies of tensor fields along affine mappings*, Bull. Transilvania Univ. Braşov, **14**(49)s./2007, 263-269
- [5] Pitea, Ariana, *Integral Geometry and PDE Constrained Optimization Problems*, Ph. D. Thesis, "Politehnica" University of Bucharest, 2008
- [6] Sharafutdinov, A., *Integral Geometry of Tensor Fields*, VSPBV, Utrecht, 1994
- [7] Udrişte, C., *Convex Functions and Optimization Methods on Riemannian Manifolds*, Kluwer Academic Publishers, 1994
- [8] Udrişte, C., Ferrara, M. and Opreş, D., *Economic Geometric Dynamics*, Geometry Balkan Press, 2004
- [9] Udrişte, C., Pitea, Ariana and Mihăilă, Janina, *Kinetic PDEs on the first order jet bundle*, Proc. 4-th, Int. Coll. Math. Engng. & Num. Phys. (MENP-4), October 6-8, 2006, Bucharest, Romania, 195-208
- [10] Udrişte, C. and Postolache, M., *Atlas of Magnetic Geometric Dynamics*, Geometry Balkan Press, 2001
- [11] Vincze, Cs., *On geometric vector fields of Minkowski spaces and their applications*, Diff. Geom. Appl., **24** (2006), No. 1, 1-20

UNIVERSITY "POLITEHNICA" OF BUCHAREST  
 FACULTY OF APPLIED SCIENCES,  
 CHAIR OF MATHEMATICS AND INFORMATICS I  
 SPLAIUL INDEPENDENŢEI 313 RO-060042, BUCHAREST, ROMANIA  
 E-mail address: apitea@mathem.pub.ro and mihai@mathem.pub.ro