

# An intermixed algorithm for solving fixed point problems of proximal operators in Hilbert Spaces

WONGVISARUT KHUANGSATUNG<sup>1</sup> and ATID KANGTUNYAKARN<sup>2</sup>

**ABSTRACT.** The aim of this paper is to modify proximal operators in Hilbert spaces. We introduce an intermixed algorithm with viscosity technique to find the solution of fixed point problem of two proximal operators in a real Hilbert space, utilizing the modified proximal operators. Under some mild conditions, a strong convergence theorem is established for the proposed algorithm. We also apply our main result to the split feasibility problem. Finally we provide numerical examples for supporting the main result.

## 1. INTRODUCTION

Let  $H$  be a real Hilbert space with an inner product  $\langle \cdot, \cdot \rangle$  and an induced norm  $\| \cdot \|$  and let  $\Gamma_0(H)$  be a class of convex, lower semicontinuous, and proper functions from a Hilbert space  $H$  to  $(-\infty, +\infty]$ . Let  $C$  be closed convex subset of  $H$ . Let  $S : C \rightarrow C$  be a nonlinear mapping, a point  $x \in C$  is called a fixed point of  $S$  if  $Sx = x$ . We denote by  $Fix(S)$ , the set of all fixed points of  $S$ , i.e.  $Fix(S) = \{x \in C : S(x) = x\}$ . Consider the following convex minimization problem

$$(1.1) \quad \min_{x \in H} (f(x) + g(x)),$$

where  $f \in \Gamma_0(H)$ ,  $g : H \rightarrow \mathbb{R}$  is convex and differentiable with the Lipschitz continuous gradient denoted by  $\nabla g$ . The solution set of (1.1) will be denoted by  $\text{Argmin}(f + g)$ . In 2014, Xu [29] presented an important mathematical tool to demonstrate that the solution set of (1.1) is equivalent to the fixed point equation as follows:

$$(1.2) \quad \tilde{x} = \text{Prox}_{\gamma f}(\tilde{x} - \gamma \nabla g(\tilde{x})),$$

where  $\gamma > 0$  and  $\text{Prox}_{\gamma f} x := \text{argmin}_{u \in H} \{f(u) + \frac{1}{2\gamma} \|u - x\|^2\}$  is the proximal mapping of  $f$  (see [2] for more informations on the proximal mapping). The most widely used algorithm for solving the convex minimization problem (1.1) is the so-called proximal-gradient algorithm. This proximal-gradient algorithm is given by:  $x_1 \in H$  and

$$(1.3) \quad x_{n+1} = \text{Prox}_{\gamma f}(I - \gamma \nabla g)(x_n), \quad \forall n \geq 1.$$

where  $\text{Prox}_f$  is the proximal operator of  $f$ ,  $\gamma \in (0, 2/L)$  and  $L$  is the Lipschitz constant of  $\nabla g$ , then the sequence  $\{x_n\}$  generated by algorithm (1.3) converges weakly to an element of  $\text{Argmin}(f + g)$  [ see [2], Corollary 28.9]. This method is sometimes called the forward-backward algorithm. The proximal-gradient algorithm can be used in real-world applications, for example, in signal recovery, in image deblurring, and in machine learning (regression on highdimensional datasets) (see, [4], [20], [14], [22]). Recently there are extensive works in studying proximal gradient algorithm, see [19], [13], [28], [27], [10], [1], [25] and the references therein. For a set  $C$ , we denote by  $\delta_C$  the indicator function of the set, that is,  $\delta_C(x) = 0$  if  $x \in C$  and  $\infty$  otherwise. We denote the metric projection

---

Received: 01.09.2023. In revised form: 18.03.2024. Accepted: 25.03.2024

2010 *Mathematics Subject Classification.* 47H10, 90C25.

Key words and phrases. *proximal operators, intermixed algorithm, strong convergence theorem.*

Corresponding author: Atid Kangtunyakarn; beawrock@hotmail.com

onto  $C$  as  $P_C$ . Clearly, by definition,  $P_Cx = \text{Prox}_{\delta_C} x$ . When  $f = \delta_C$ , the algorithm (1.3) becomes the popular gradient projection algorithm, which is defined as follows. For an initial guess  $x_1 \in H$ ,

$$(1.4) \quad x_{n+1} = P_C(I - \gamma \nabla g)(x_n), \quad \forall n \geq 1.$$

Recently, Guo and Cui [8] modified the proximal-gradient algorithm with viscosity technique as follows: For arbitrarily given  $x_1 \in H$ , let the sequences  $\{x_n\}$  be generated iteratively by

$$(1.5) \quad x_{n+1} = \alpha_n h(x_n) + (1 - \alpha_n) \text{Prox}_{\mu_n f}(I - \mu_n \nabla g)(x_n) + e(x_n), \quad \forall n \geq 1,$$

where  $\{\alpha_n\}$  is a real number sequence in  $[0, 1]$ ,  $0 < a = \inf_n \mu_n \leq \mu_n < \frac{2}{L}$ ,  $h : H \rightarrow H$  a  $\rho$ -contractive operator with  $\rho \in (0, 1)$ , and  $e : H \rightarrow H$  represents a perturbation operator and satisfies  $\sum_{n=1}^{\infty} \|e(x_n)\| < +\infty$ . Under some appropriate conditions, they proved that the algorithm (1.5) converges strongly to a solution of (1.1) in a real Hilbert space.

Currently, one of the best methods for solving the fixed point problem of nonlinear mapping is to use the intermixed algorithm, proposed by Yao et al.[32]. This algorithm has the following features: the definition of the sequence  $\{x_n\}$  is involved in the sequence  $\{y_n\}$  and the definition of the sequence  $\{y_n\}$  is also involved in the sequence  $\{x_n\}$ . In recent years, the intermixed algorithm has attracted a significant amount of interest from authors, who improved it in various ways (see, e.g., [26], [23], [11]). In particular, Yao et al.[32] introduced the intermixed algorithm for two strict pseudo-contractions as follows: For arbitrarily given  $x_1 \in C, y_1 \in C$ , let the sequences  $\{x_n\}$  and  $\{y_n\}$  be generated iteratively by

$$(1.6) \quad \begin{cases} x_{n+1} = (1 - \delta_n)x_n + \delta_n P_C[\alpha_n h_1(y_n) + (1 - k - \alpha_n)x_n + kTx_n], & \forall n \geq 1, \\ y_{n+1} = (1 - \delta_n)y_n + \delta_n P_C[\alpha_n h_2(x_n) + (1 - k - \alpha_n)y_n + kSy_n], & \forall n \geq 1, \end{cases}$$

where  $\{\alpha_n\}, \{\delta_n\}$  are two real number sequences in  $(0, 1)$ ,  $S, T : C \rightarrow C$  are  $\lambda$ -strictly pseudo-contractions with  $k \in (0, 1 - \lambda)$ , and  $h_1, h_2 : C \rightarrow H$  are  $\rho_1, \rho_2$ -contractions, respectively. Moreover, Yao et al. also proved in [32] that the sequence  $\{x_n\}$  generated by (1.6) weakly converges to a fixed point of two strict pseudo-contractions under some appropriate conditions.

The Krasnoselskii-Mann algorithm (see, [15], [16], [21]) is one of the most well-known fixed point algorithms. In recent years, several researchers have increasingly investigated the Krasnoselskii-Mann algorithm in various directions, for example [24], [7], [33], [9] and the references therein. In particular, Kanzow and Shehu [12] proposed the following inexact Krasnoselskii-Mann algorithm for finding a fixed point of a nonexpansive mapping  $T$  in a real Hilbert space: For arbitrarily given  $x_1 \in H$ , let  $\{x_n\}$  be a sequence generated iteratively by

$$(1.7) \quad x_{n+1} = \alpha_n x_n + \beta_n T x_n + r_n, \quad \forall n \geq 1,$$

where  $T : H \rightarrow C$  is a nonexpansive mapping,  $r_n$  denotes the residual vector and  $\{\alpha_n\}, \{\beta_n\}$  are two real number sequences in  $[0, 1]$  such that  $\alpha_n + \beta_n \leq 1$ . They proved that if  $\sum_{n=1}^{\infty} \alpha_n \beta_n = \infty, \sum_{n=1}^{\infty} \|r_n\| < \infty$ , and  $\sum_{n=1}^{\infty} (1 - \alpha_n - \beta_n) < \infty$ , then the sequence  $\{x_n\}$  generated by (1.7) converges weakly to a fixed point of  $T$ .

In this paper, based on the problems (1.1) and (1.2), we modify a proximal operator and introduce a new mathematical tool relevant to the modified proximal operator in Hilbert spaces. Inspired and motivated by previous works, we introduce an intermixed algorithm with viscosity technique to find the solution of fixed point problem of two proximal operators in a real Hilbert space. Using the mathematical tool above, a strong convergence

theorem for the proposed algorithm is established under some mild conditions. Applications to the split feasibility problems are also considered. Finally, we provide some numerical experiments to verify the theoretical results of this paper. In summary,

- Applying the convex minimization problem (1.1) and the fixed point equation (1.2), we propose a new mathematical tool related to two proximal operators;
- We propose an intermixed algorithm to find the solution of fixed point problem of two proximal operators in a real Hilbert space and prove a strong convergence theorem for the proposed algorithm under some mild conditions;
- Our algorithm combine the proximal-gradient algorithm with viscosity technique in Guo and Cui [8], the intermixed algorithm in Yao et al.[32] and the Krasnosel'skiĭ–Mann algorithm in Kanzow and Shehu [12].

The organization of our paper is as follows: In section 2, we first recall some basic definitions and lemmas. We also give a new lemma related to two proximal operators (see Lemma 2.4 below). In section 3, we prove the strong convergence theorem of our proposed algorithm under some mild conditions. In section 4, we consider the application of our main result to solve the split feasibility problems. In section 5, we provide numerical examples to support the main result.

## 2. PRELIMINARY

For the purpose of proving our theorem, we provide several definitions and lemmas in this section. For convenience, the following notations are used throughout the paper:

- $H$  denotes a real Hilbert space with an inner product  $\langle \cdot, \cdot \rangle$  and an induced norm  $\| \cdot \|$ ;
- $C$  denotes a nonempty closed convex subset of  $H$ ;
- $\Gamma_0(H)$  denotes a class of convex, lower semicontinuous, and proper functions from a Hilbert space  $H$  to  $(-\infty, +\infty]$ ;
- $x_n \rightarrow q$  ( $x_n \rightharpoonup q$ ) denote the strong (weak) convergence of a sequence  $\{x_n\}$  to  $q$  in  $H$ , respectively;
- $Fix(S)$  denotes the set of all fixed points of  $S$ .

Recall that the (nearest point) projection  $P_C$  from  $H$  onto  $C$  assigns to each  $x \in H$  the unique point  $P_Cx \in C$  satisfying the property

$$\|x - P_Cx\| = \min_{y \in C} \|x - y\|.$$

**Lemma 2.1.** [18] *For given  $x \in H$  and let  $P_C : H \rightarrow C$  be a metric projection. Then*

- (a)  $w = P_Cx$  if and only if  $\langle x - w, y - w \rangle \leq 0, \quad \forall y \in C$ ;
- (b)  $w = P_Cx$  if and only if  $\|x - w\|^2 \leq \|x - y\|^2 - \|y - w\|^2, \quad \forall y \in C$ ;
- (c)  $\langle P_Cx - P_Cy, x - y \rangle \geq \|P_Cx - P_Cy\|^2, \quad \forall x, y \in H$ .

**Definition 2.1.** A mapping  $S : C \rightarrow C$  is called nonexpansive, if

$$\|Sx - Sy\| \leq \|x - y\| \quad \forall x, y \in C.$$

**Definition 2.2.** A mapping  $A : C \rightarrow H$  is called

- (i) Monotone if

$$\langle Ax - Ay, x - y \rangle \geq 0, \quad \forall x, y \in C;$$

- (ii)  $\eta$ -Strongly monotone if there exists a positive real number  $\eta$  such that

$$\langle Ax - Ay, x - y \rangle \geq \eta \|x - y\|^2, \quad \forall x, y \in C;$$

- (iii)  $L$ -Lipschitz continuous if there exists  $L > 0$  such that

$$\|Ax - Ay\| \leq L \|x - y\|, \quad \forall x, y \in C;$$

(iv)  $\alpha$ -inverse strongly monotone if there exists  $\alpha > 0$  such that

$$\langle x - y, Ax - Ay \rangle \geq \alpha \|Ax - Ay\|^2, \quad \forall x, y \in C.$$

Clearly, If  $A$  is  $\eta$ -Strongly monotone and  $L$ -Lipschitz continuous, then  $A$  is  $\frac{\eta}{L^2}$ -inverse strongly monotone. If  $A$  is an  $\alpha$ -inverse strongly monotone mapping, then  $\frac{1}{\alpha}$ -Lipschitz continuous.

**Lemma 2.2.** [12] *Let  $X$  be a real inner product space. Then*

(a)  $\|x + y\|^2 \leq \|x\|^2 + 2\langle y, x + y \rangle, \quad \forall x, y \in X;$

(b)  $\|px + qy\|^2 = p(p + q)\|x\|^2 + q(p + q)\|y\|^2 - pq\|x - y\|^2, \quad \forall x, y \in X, \forall p, q \in \mathbb{R}.$

The following Lemma, which comes from [17], [30], will be used to prove our strong convergence result.

**Lemma 2.3.** [17], [30] *Let  $\{\alpha_n\}$  be a sequence of nonnegative real numbers satisfying the following relation:*

$$a_{n+1} \leq (1 - \alpha_n)a_n + \delta_n + \mu_n, \quad \forall n \geq 1,$$

where  $\{\alpha_n\}$  is a sequence in  $(0, 1)$  and  $\{\delta_n\}$  is a real sequence. Assume  $\sum_{n=1}^{\infty} |\mu_n| < \infty$ . Then, the following results hold:

(i) *If  $\delta_n \leq \alpha_n M$  for some  $M \geq 0$  then  $\{a_n\}$  is a bounded sequence;*

(ii) *If  $\sum_{n=1}^{\infty} \alpha_n = \infty$ , and  $\limsup_{n \rightarrow \infty} \frac{\delta_n}{\alpha_n} \leq 0$ , then  $\lim_{n \rightarrow \infty} a_n = 0$ .*

Let the function  $f \in \Gamma_0(H)$ . The set

$$\partial f(x) = \{z \in H : \langle z, y - x \rangle + f(x) \leq f(y), \quad \forall y \in H\}$$

is called a *subdifferential* of  $f$  at  $x \in H$ . The function  $f$  is said to be *subdifferentiable* at  $x$  if  $\partial f(x) \neq \emptyset$ . The elements of  $\partial f(x)$  are called the *subgradients* of  $f$  at  $x$ . If the function  $f$  is continuously differentiable, then  $\partial f(x) = \{\nabla f(x)\}$ ; this is the gradient of  $f$ . It is well known that the subdifferential  $\partial f$  is a maximal monotone operator. It is notable that a point  $x^* \in H$  minimizes  $f$  if and only if  $0 \in \partial f(x^*)$ . Let  $x$  and  $p$  be in  $H$ . The proximity operator of  $f$  is characterized by the inclusion

$$p = \text{Prox}_{\gamma f} x \Leftrightarrow x - p \in \gamma \partial f(p).$$

In other words,

$$\text{Prox}_{\gamma f} = (I + \gamma \partial f)^{-1}.$$

Moreover, the proximity operator of  $f$  is firmly nonexpansive, namely,

$$(2.8) \quad \langle \text{Prox}_{\gamma f}(x) - \text{Prox}_{\gamma f}(y), x - y \rangle \geq \|\text{Prox}_{\gamma f}(x) - \text{Prox}_{\gamma f}(y)\|^2$$

for all  $x, y \in H$ , which is equivalent to

$$(2.9) \quad \|\text{Prox}_{\gamma f}(x) - \text{Prox}_{\gamma f}(y)\|^2 \leq \|x - y\|^2 - \|(I - \text{Prox}_{\gamma f})(x) - (I - \text{Prox}_{\gamma f})(y)\|^2$$

for all  $x, y \in H$ . For general information on proximal operator, see Combettes and Pesquet [3].

**Proposition 2.1.** [2] *Let the function  $f \in \Gamma_0(H)$  and let  $x, p \in H$ . Then*

$$p = \text{Prox}_f x \Leftrightarrow \langle y - p, x - p \rangle + f(p) \leq f(y),$$

for all  $y \in H$ .

**Lemma 2.4.** *Let the function  $f \in \Gamma_0(H)$ . Let  $A, B : C \rightarrow H$  be  $\delta^A$  and  $\delta^B$ -inverse strongly monotone operators, respectively, with  $\delta = \min\{\delta^A, \delta^B\}$  and  $\text{Fix}(\text{Prox}_{\gamma f}(I - \gamma A)) \cap \text{Fix}(\text{Prox}_{\gamma f}(I - \gamma B)) \neq \emptyset$ . Then*

$$(2.10) \quad \text{Fix}(\text{Prox}_{\gamma f}(I - \gamma A)) \cap \text{Fix}(\text{Prox}_{\gamma f}(I - \gamma B)) = \text{Fix}(\text{Prox}_{\gamma f}(I - \gamma(aA + (1-a)B))),$$

for all  $a \in (0, 1)$  and  $\gamma \in (0, 2\delta)$ .

*Proof.* From Proposition 2.1, it is easy to see that

$$(2.11) \quad \text{Fix}(\text{Prox}_{\gamma f}(I - \gamma A)) \cap \text{Fix}(\text{Prox}_{\gamma f}(I - \gamma B)) \subseteq \text{Fix}(\text{Prox}_{\gamma f}(I - \gamma(aA + (1-a)B))).$$

Let  $x_0 \in \text{Fix}(\text{Prox}_{\gamma f}(I - \gamma(aA + (1-a)B)))$  and  $x^* \in \text{Fix}(\text{Prox}_{\gamma f}(I - \gamma A)) \cap \text{Fix}(\text{Prox}_{\gamma f}(I - \gamma B))$ . So, we have

$$x^* \in \text{Fix}(\text{Prox}_{\gamma f}(I - \gamma(aA + (1-a)B))).$$

By the definitions of  $A, B$ , we have

$$\begin{aligned} \|x_0 - x^*\|^2 &= \|\text{Prox}_{\gamma f}(I - \gamma(aA + (1-a)B))x_0 - \text{Prox}_{\gamma f}(I - \gamma(aA + (1-a)B))x^*\|^2 \\ &\leq \|x_0 - x^* - \gamma(a(Ax_0 - Ax^*) + (1-a)(Bx_0 - Bx^*))\|^2 \\ &= \|x_0 - x^*\|^2 - 2\gamma\langle a(Ax_0 - Ax^*) + (1-a)(Bx_0 - Bx^*), x_0 - x^* \rangle \\ &\quad + \gamma^2\|a(Ax_0 - Ax^*) + (1-a)(Bx_0 - Bx^*)\|^2 \\ &\leq \|x_0 - x^*\|^2 - 2\gamma a\langle Ax_0 - Ax^*, x_0 - x^* \rangle - 2\gamma(1-a)\langle Bx_0 - Bx^*, x_0 - x^* \rangle \\ &\quad + \gamma^2(a\|Ax_0 - Ax^*\|^2 + (1-a)\|Bx_0 - Bx^*\|^2) \\ (2.12) \quad &\leq \|x_0 - x^*\|^2 - \gamma a(2\delta - \gamma)\|Ax_0 - Ax^*\|^2 - \gamma(1-a)(2\delta - \gamma)\|Bx_0 - Bx^*\|^2. \end{aligned}$$

It implies that

$$Ax_0 = Ax^*, Bx_0 = Bx^*.$$

Let  $y \in H$ . By applying Proposition 2.1 and  $x^* \in \text{Fix}(\text{Prox}_{\gamma f}(I - \gamma A))$ , we obtain

$$\langle y - x^*, (I - \gamma A)x^* - x^* \rangle + \gamma f(x^*) \leq \gamma f(y),$$

which implies that

$$(2.13) \quad f(y) - f(x^*) + \langle y - x^*, Ax^* \rangle \geq 0.$$

Since  $x^* \in \text{Fix}(\text{Prox}_{\gamma f}(I - \gamma B))$ , we also get

$$(2.14) \quad f(y) - f(x^*) + \langle y - x^*, Bx^* \rangle \geq 0.$$

Since  $x_0 \in \text{Fix}(\text{Prox}_{\gamma f}(I - \gamma(aA + (1-a)B)))$  and by Proposition 2.1, we get

$$\langle y - x_0, (I - \gamma(aA + (1-a)B))x_0 - x_0 \rangle + \gamma f(x_0) \leq \gamma f(y),$$

which implies that

$$(2.15) \quad f(y) - f(x_0) + \langle y - x_0, (aA + (1-a)B)x_0 \rangle \geq 0.$$

From (2.13) and  $Ax_0 = Ax^*$ , we obtain

$$\begin{aligned} \langle y - x_0, Ax_0 \rangle + f(y) - f(x_0) &= \langle y - x^*, Ax^* \rangle + \langle x^* - x_0, Ax_0 \rangle + f(y) - f(x^*) \\ &\quad + f(x^*) - f(x_0) \\ &= \langle y - x^*, Ax^* \rangle + f(y) - f(x^*) + \langle x^* - x_0, Ax_0 \rangle \\ &\quad + f(x^*) - f(x_0) \\ (2.16) \quad &\geq \langle x^* - x_0, Ax_0 \rangle + f(x^*) - f(x_0). \end{aligned}$$

From  $Bx_0 = Bx^*$ , (2.14), and (2.15), we get

$$\begin{aligned}
 & \langle x^* - x_0, aAx_0 \rangle + af(x^*) - af(x_0) \\
 &= \langle x^* - x_0, aAx_0 + (1-a)Bx_0 \rangle - \langle x^* - x_0, (1-a)Bx_0 \rangle \\
 & \quad + af(x^*) - af(x_0) \\
 &= \langle x^* - x_0, aAx_0 + (1-a)Bx_0 \rangle + f(x^*) - f(x_0) \\
 & \quad - f(x^*) + f(x_0) - \langle x^* - x_0, (1-a)Bx_0 \rangle \\
 & \quad + af(x^*) - af(x_0) \\
 & \geq \langle x_0 - x^*, (1-a)Bx^* \rangle + (1-a)f(x_0) - (1-a)f(x^*) \\
 &= (1-a)(\langle x_0 - x^*, Bx^* \rangle + f(x_0) - f(x^*)) \\
 & \geq 0.
 \end{aligned}$$

Since  $a \in (0, 1)$ , we have

$$(2.17) \quad \langle x^* - x_0, Ax_0 \rangle + f(x^*) - f(x_0) \geq 0.$$

From (2.16) and (2.17), we obtain

$$(2.18) \quad \langle y - x_0, Ax_0 \rangle + f(y) - f(x_0) \geq 0, \forall y \in H.$$

It follows from (2.18) and Proposition 2.1,

$$\langle y - x_0, x_0 - (I - \gamma A)x_0 \rangle + \gamma f(y) - \gamma f(x_0) \geq 0, \forall y \in H.$$

It implies that

$$(2.19) \quad x_0 \in \text{Fix}(\text{Prox}_{\gamma f}(I - \gamma A)).$$

Using the same method as (2.19), we also have

$$x_0 \in \text{Fix}(\text{Prox}_{\gamma f}(I - \gamma B)).$$

So, we can conclude that

$$(2.20) \quad \text{Fix}(\text{Prox}_{\gamma f}(I - \gamma(aA + (1-a)B))) \subseteq \text{Fix}(\text{Prox}_{\gamma f}(I - \gamma A)) \cap \text{Fix}(\text{Prox}_{\gamma f}(I - \gamma B)).$$

From (2.11) and (2.20), we deduce that

$$(2.21) \quad \text{Fix}(\text{Prox}_{\gamma f}(I - \gamma A)) \cap \text{Fix}(\text{Prox}_{\gamma f}(I - \gamma B)) = \text{Fix}(\text{Prox}_{\gamma f}(I - \gamma(aA + (1-a)B))).$$

□

**Lemma 2.5.** [31] *Let  $H$  be a Hilbert space,  $C$  a closed convex subset of  $H$ , and  $T : C \rightarrow C$  be a nonexpansive mapping with  $\text{Fix}(T) \neq \emptyset$ . If  $\{x_n\}$  is a sequence in  $C$  weakly converging to  $x$  and  $\{(I - T)x_n\}$  converges strongly to  $y$ , then  $(I - T)x = y$ .*

### 3. MAIN RESULTS

In this section, we introduce an intermixed algorithm and prove a strong convergence of the proposed algorithm to find the solution of fixed point problem of two proximal operators.

For every  $i = 1, 2$ , let the functions  $f_i \in \Gamma_0(H)$ , let  $A_i, B_i : C \rightarrow H$  be  $\delta_i^A$  and  $\delta_i^B$ -inverse strongly monotone operators, respectively, with  $\delta_i = \min\{\delta_i^A, \delta_i^B\}$ . Assume that  $\Omega_i = \text{Fix}(\text{Prox}_{\gamma f}^i(I - \gamma_i A_i)) \cap \text{Fix}(\text{Prox}_{\gamma f}^i(I - \gamma_i B_i)) \neq \emptyset$ , for all  $i = 1, 2$ . Let  $\xi_1, \xi_2 : H \rightarrow H$  be  $\sigma_1$  and  $\sigma_2$ -contraction mappings with  $\sigma_1, \sigma_2 \in (0, 1)$  and  $\sigma = \max\{\sigma_1, \sigma_2\}$ .

Now, we introduce an intermixed algorithm with viscosity technique for solving a common fixed point of proximal operators as follows:

**Algorithm 1:** An intermixed algorithm with viscosity technique for solving a common fixed point of two proximal operators.

**Initialization:** Given  $x_1, y_1 \in C$  be arbitrary.

**Iterative Steps:** Given the current iterate  $\{x_n\}, \{y_n\}$ , calculate  $\{x_{n+1}\}, \{y_{n+1}\}$  as follows:

**Step 1:** Compute

$$\begin{cases} v_n = \text{Prox}_{\gamma f}^2(y_n - \gamma_2(a_2A_2 + (1 - a_2)B_2)y_n) \\ u_n = \text{Prox}_{\gamma f}^1(x_n - \gamma_1(a_1A_1 + (1 - a_1)B_1)x_n) \end{cases}$$

**Step 2:** Compute

$$\begin{cases} y_{n+1} = \mu_n y_n + \beta_n P_C(\alpha_n \xi_2(x_n) + (1 - \alpha_n)v_n) \\ x_{n+1} = \mu_n x_n + \beta_n P_C(\alpha_n \xi_1(y_n) + (1 - \alpha_n)u_n), \end{cases}$$

where  $\{\mu_n\}, \{\beta_n\}, \{\alpha_n\} \subseteq [0, 1]$  with  $\mu_n + \beta_n \leq 1, \gamma_i \in (0, 2\delta_i), a_i \in (0, 1)$  and  $\text{Prox}_{\gamma f}^i : H \rightarrow H$  is the proximity operator, for all  $i = 1, 2$ .

Set  $n := n + 1$  and go to Step 1.

**Theorem 3.1.** For every  $i = 1, 2$ , let the functions  $f_i \in \Gamma_0(H)$ , let  $A_i, B_i : C \rightarrow H$  be  $\delta_i^A$  and  $\delta_i^B$ -inverse strongly monotone operators, respectively, with  $\delta_i = \min\{\delta_i^A, \delta_i^B\}$ . Assume that  $\Omega_i = \text{Fix}(\text{Prox}_{\gamma f}^i(I - \gamma_i A_i)) \cap \text{Fix}(\text{Prox}_{\gamma f}^i(I - \gamma_i B_i)) \neq \emptyset$ , for all  $i = 1, 2$ . Let  $\xi_1, \xi_2 : H \rightarrow H$  be  $\sigma_1$  and  $\sigma_2$ -contraction mappings with  $\sigma_1, \sigma_2 \in (0, 1)$  and  $\sigma = \max\{\sigma_1, \sigma_2\}$ . Let  $\{x_n\}$  and  $\{y_n\}$  be the sequences generated by Algorithm 1, satisfying the following conditions:

- (i)  $\lim_{n \rightarrow \infty} \alpha_n = 0$  and  $\sum_{n=1}^{\infty} \alpha_n = \infty$ ;
- (ii) there are  $\bar{\epsilon}, l > 0$  with  $0 < \bar{\epsilon} \leq \mu_n, \beta_n \leq l < 1$  for all  $n \in \mathbb{N}$ ;
- (iii)  $\sum_{n=1}^{\infty} |\alpha_{n+1} - \alpha_n| < \infty, \sum_{n=1}^{\infty} |\mu_{n+1} - \mu_n| < \infty, \sum_{n=1}^{\infty} |\beta_{n+1} - \beta_n| < \infty, \sum_{n=1}^{\infty} (1 - \mu_n - \beta_n) < \infty$ .

Then  $\{x_n\}$  and  $\{y_n\}$  converge strongly to  $x^* = P_{\Omega_1} \xi_1(y^*)$  and  $y^* = P_{\Omega_2} \xi_2(x^*)$ , respectively.

*Proof.* Putting  $K_i = \text{Prox}_{\gamma f}^i(I - \gamma_i(a_i A_i + (1 - a_i)B_i))$  for all  $i = 1, 2$ . First, we will show that  $K_i$  is nonexpansive mapping for all  $i = 1, 2$ . For every  $i = 1, 2$ , let  $x^*, x_0 \in C$ . Using the same method as (2.12), we have

$$\begin{aligned} \|K_i x^* - K_i x_0\| &= \|\text{Prox}_{\gamma f}^i(I - \gamma_i(a_i A_i + (1 - a_i)B_i))x^* \\ &\quad - \text{Prox}_{\gamma f}^i(I - \gamma_i(a_i A_i + (1 - a_i)B_i))x_0\|^2 \\ &\leq \|x^* - x_0\|^2 + a_i \gamma_i (\gamma_i - 2\delta_i) \|A_i x^* - A_i x_0\|^2 \\ &\quad + (1 - a_i) \gamma_i (\gamma_i - 2\delta_i) \|B_i x^* - B_i x_0\|^2 \\ (3.22) \qquad \qquad \qquad &\leq \|x^* - x_0\|^2. \end{aligned}$$

Thus,  $\text{Prox}_{\gamma f}^i(I - \gamma_i(a_i A_i + (1 - a_i)B_i))$  is nonexpansive mapping for all  $i = 1, 2$ . Assume that  $x^* \in \Omega_1$  and  $y^* \in \Omega_2$ .

From the definition of  $x_n$ ,  $u_n$  and the nonexpansiveness of  $K_i$ , we have

$$\begin{aligned}
\|x_{n+1} - x^*\| &= \|\mu_n x_n + \beta_n PC(\alpha_n \xi_1(y_n) + (1 - \alpha_n)u_n) - x^*\| \\
&= \|\mu_n(x_n - x^*) + \beta_n(PC(\alpha_n \xi_1(y_n) + (1 - \alpha_n)u_n) - x^*) \\
&\quad - (1 - \mu_n - \beta_n)x^*\| \\
&\leq \mu_n \|x_n - x^*\| + \beta_n \|\alpha_n \xi_1(y_n) + (1 - \alpha_n)u_n - x^*\| \\
&\quad + (1 - \mu_n - \beta_n)\|x^*\| \\
&\leq \mu_n \|x_n - x^*\| + \beta_n(\alpha_n \|\xi_1(y_n) - x^*\| + (1 - \alpha_n)\|u_n - x^*\|) \\
&\quad + (1 - \mu_n - \beta_n)\|x^*\| \\
&= \mu_n \|x_n - x^*\| + \beta_n(\alpha_n \|\xi_1(y_n) - x^*\| + (1 - \alpha_n)\|K_1 x_n - x^*\|) \\
&\quad + (1 - \mu_n - \beta_n)\|x^*\| \\
&\leq \mu_n \|x_n - x^*\| + \beta_n(\alpha_n \|\xi_1(y_n) - x^*\| + (1 - \alpha_n)\|x_n - x^*\|) \\
&\quad + (1 - \mu_n - \beta_n)\|x^*\| \\
&\leq (1 - \beta_n)\|x_n - x^*\| + \beta_n \alpha_n \|\xi_1(y_n) - x^*\| + \beta_n(1 - \alpha_n)\|x_n - x^*\| \\
&\quad + (1 - \mu_n - \beta_n)\|x^*\| \\
&= (1 - \alpha_n \beta_n)\|x_n - x^*\| + \alpha_n \beta_n \|\xi_1(y_n) - x^*\| \\
&\quad + (1 - \mu_n - \beta_n)\|x^*\| \\
&\leq (1 - \alpha_n \beta_n)\|x_n - x^*\| + \alpha_n \beta_n (\|\xi_1(y_n) - \xi_1(y^*)\| + \|\xi_1(y^*) - x^*\|) \\
&\quad + (1 - \mu_n - \beta_n)\|x^*\| \\
&\leq (1 - \alpha_n \beta_n)\|x_n - x^*\| + \alpha_n \beta_n \sigma_1 \|y_n - y^*\| + \alpha_n \beta_n \|\xi_1(y^*) - x^*\| \\
&\quad + (1 - \mu_n - \beta_n)\|x^*\| \\
&\leq (1 - \alpha_n \beta_n)\|x_n - x^*\| + \alpha_n \beta_n \sigma \|y_n - y^*\| + \alpha_n \beta_n \|\xi_1(y^*) - x^*\| \\
&\quad + (1 - \mu_n - \beta_n)\|x^*\|.
\end{aligned} \tag{3.23}$$

Similarly, we get

$$\begin{aligned}
\|y_{n+1} - y^*\| &\leq (1 - \alpha_n \beta_n)\|y_n - y^*\| + \alpha_n \beta_n \sigma \|x_n - x^*\| + \alpha_n \beta_n \|\xi_2(x^*) - y^*\| \\
&\quad + (1 - \mu_n - \beta_n)\|y^*\|.
\end{aligned} \tag{3.24}$$

Combining (3.23) and (3.24), we have

$$\begin{aligned}
\|x_{n+1} - x^*\| + \|y_{n+1} - y^*\| &\leq (1 - \alpha_n \beta_n)\|x_n - x^*\| + \alpha_n \beta_n \sigma \|y_n - y^*\| \\
&\quad + \alpha_n \beta_n \|\xi_1(y^*) - x^*\| + (1 - \mu_n - \beta_n)\|x^*\| \\
&\quad + (1 - \alpha_n \beta_n)\|y_n - y^*\| + \alpha_n \beta_n \sigma \|x_n - x^*\| \\
&\quad + \alpha_n \beta_n \|\xi_2(x^*) - y^*\| + (1 - \mu_n - \beta_n)\|y^*\| \\
&= (1 - \alpha_n \beta_n) (\|x_n - x^*\| + \|y_n - y^*\|) \\
&\quad + \alpha_n \beta_n \sigma (\|x_n - x^*\| + \|y_n - y^*\|) \\
&\quad + \alpha_n \beta_n (\|\xi_1(y^*) - x^*\| + \|\xi_2(x^*) - y^*\|) \\
&\quad + (1 - \mu_n - \beta_n) (\|x^*\| + \|y^*\|)
\end{aligned}$$



$$\begin{aligned}
 &= (1 - \alpha_n \beta_n (1 - \sigma)) (\|x_n - x^*\| + \|y_n - y^*\|) \\
 &\quad + \alpha_n \beta_n (\|\xi_1(y^*) - x^*\| + \|\xi_2(x^*) - y^*\|) \\
 &\quad + (1 - \mu_n - \beta_n) (\|x^*\| + \|y^*\|) \\
 &= (1 - \alpha_n \beta_n (1 - \sigma)) (\|x_n - x^*\| + \|y_n - y^*\|) \\
 &\quad + \alpha_n \beta_n (1 - \sigma) \left( \frac{\|\xi_1(y^*) - x^*\| + \|\xi_2(x^*) - y^*\|}{1 - \sigma} \right) \\
 &\quad + (1 - \mu_n - \beta_n) (\|x^*\| + \|y^*\|).
 \end{aligned}$$

By Lemma 2.3, we get that  $\{x_n\}$  and  $\{y_n\}$  are bounded. Next, we will show that  $\{u_n\}$ ,  $\{v_n\}$ ,  $\{\xi_1(y_n)\}$ , and  $\{\xi_2(x_n)\}$  are bounded. From the definition of  $u_n$  and the nonexpansiveness of  $K_1$ , we have

$$\begin{aligned}
 \|u_n - x^*\| &= \|K_1 x_n - x^*\| \\
 &\leq \|x_n - x^*\|.
 \end{aligned}$$

Since  $\{x_n\}$  is bounded, then  $\{u_n\}$  is bounded. Using the same method, we establish that the sequence  $v_n$  is bounded. Observe that

$$\begin{aligned}
 \|\xi_1(y_n) - x^*\| &\leq \|\xi_1(y_n) - \xi_1(x^*)\| + \|\xi_1(x^*) - x^*\| \\
 &\leq \sigma_1 \|x_n - x^*\| + \|\xi_1(x^*) - x^*\|.
 \end{aligned}$$

Since  $\{x_n\}$  is bounded, then  $\{\xi_1(y_n)\}$  is bounded. Using the same method, we show that the sequence  $\{\xi_2(x_n)\}$  is bounded.

Setting  $T_n = P_C(\alpha_n \xi_1(y_n) + (1 - \alpha_n)u_n)$  and  $T_n^* = P_C(\alpha_n \xi_2(x_n) + (1 - \alpha_n)v_n)$ . We will show that  $\{T_n\}$  and  $\{T_n^*\}$  are bounded. Observe that

$$\begin{aligned}
 \|T_n - x^*\| &= \|P_C(\alpha_n \xi_1(y_n) + (1 - \alpha_n)u_n) - x^*\| \\
 &\leq \|\alpha_n \xi_1(y_n) + (1 - \alpha_n)u_n - x^*\| \\
 &\leq \alpha_n \|\xi_1(y_n) - x^*\| + (1 - \alpha_n) \|u_n - x^*\| \\
 &\leq \alpha_n \|\xi_1(y_n) - \xi_1(x^*)\| + \alpha_n \|\xi_1(x^*) - x^*\| + (1 - \alpha_n) \|u_n - x^*\| \\
 &\leq \alpha_n \sigma_1 \|x_n - x^*\| + \alpha_n \|\xi_1(x^*) - x^*\| + (1 - \alpha_n) \|x_n - x^*\| \\
 &= (1 - \alpha_n (1 - \sigma_1)) \|x_n - x^*\| + \alpha_n \|\xi_1(x^*) - x^*\|.
 \end{aligned}$$

Since  $\{x_n\}$  is bounded, then  $\{T_n\}$  is bounded. Using the same method, we show that the sequence  $\{T_n^*\}$  is bounded.

Next, we show that  $\|x_{n+1} - x_n\| \rightarrow 0$  and  $\|y_{n+1} - y_n\| \rightarrow 0$  as  $n \rightarrow \infty$ .

By the nonexpansiveness of  $K_i$ , we have

$$\begin{aligned}
\|T_n - T_{n-1}\| &= \|P_C(\alpha_n \xi_1(y_n) + (1 - \alpha_n)u_n) - P_C(\alpha_{n-1} \xi_1(y_{n-1}) + (1 - \alpha_{n-1})u_{n-1})\| \\
&\leq \|(\alpha_n \xi_1(y_n) + (1 - \alpha_n)u_n) - (\alpha_{n-1} \xi_1(y_{n-1}) + (1 - \alpha_{n-1})u_{n-1})\| \\
&= \|\alpha_n \xi_1(y_n) - \alpha_n \xi_1(y_{n-1}) + \alpha_n \xi_1(y_{n-1}) + (1 - \alpha_n)u_n - (1 - \alpha_n)u_{n-1} \\
&\quad + (1 - \alpha_n)u_{n-1} - \alpha_{n-1} \xi_1(y_{n-1}) - (1 - \alpha_{n-1})u_{n-1}\| \\
&= \|\alpha_n(\xi_1(y_n) - \xi_1(y_{n-1})) + (\alpha_n - \alpha_{n-1})\xi_1(y_{n-1}) + (1 - \alpha_n)(u_n - u_{n-1}) \\
&\quad + (\alpha_{n-1} - \alpha_n)u_{n-1}\| \\
&\leq \alpha_n \|\xi_1(y_n) - \xi_1(y_{n-1})\| + |\alpha_n - \alpha_{n-1}| \|\xi_1(y_{n-1})\| \\
&\quad + (1 - \alpha_n) \|K_1 x_n - K_1 x_{n-1}\| + |\alpha_n - \alpha_{n-1}| \|u_{n-1}\| \\
&\leq \alpha_n \sigma_1 \|y_n - y_{n-1}\| + |\alpha_n - \alpha_{n-1}| \|\xi_1(y_{n-1})\| + (1 - \alpha_n) \|x_n - x_{n-1}\| \\
&\quad + |\alpha_n - \alpha_{n-1}| \|u_{n-1}\| \\
&\leq \alpha_n \sigma \|y_n - y_{n-1}\| + |\alpha_n - \alpha_{n-1}| \|\xi_1(y_{n-1})\| + (1 - \alpha_n) \|x_n - x_{n-1}\| \\
&\quad + |\alpha_n - \alpha_{n-1}| \|u_{n-1}\|.
\end{aligned}
\tag{3.25}$$

From the definition of  $x_n$  and (3.25), we have

$$\begin{aligned}
\|x_{n+1} - x_n\| &= \|\mu_n x_n + \beta_n T_n - (\mu_{n-1} x_{n-1} + \beta_{n-1} T_{n-1})\| \\
&\leq \mu_n \|x_n - x_{n-1}\| + |\mu_n - \mu_{n-1}| \|x_{n-1}\| \\
&\quad + \beta_n \|T_n - T_{n-1}\| + |\beta_n - \beta_{n-1}| \|T_{n-1}\| \\
&\leq \mu_n \|x_n - x_{n-1}\| + |\mu_n - \mu_{n-1}| \|x_{n-1}\| \\
&\quad + \beta_n \left( \alpha_n \sigma \|y_n - y_{n-1}\| + |\alpha_n - \alpha_{n-1}| \|\xi_1(y_{n-1})\| \right. \\
&\quad \left. + (1 - \alpha_n) \|x_n - x_{n-1}\| + |\alpha_n - \alpha_{n-1}| \|u_{n-1}\| \right) \\
&\quad + |\beta_n - \beta_{n-1}| \|T_{n-1}\| \\
&\leq (1 - \alpha_n \beta_n) \|x_n - x_{n-1}\| + |\mu_n - \mu_{n-1}| \|x_{n-1}\| \\
&\quad + \alpha_n \beta_n \sigma \|y_n - y_{n-1}\| + |\alpha_n - \alpha_{n-1}| \left( \|\xi_1(y_{n-1})\| + \|u_{n-1}\| \right) \\
&\quad + |\beta_n - \beta_{n-1}| \|T_{n-1}\|.
\end{aligned}
\tag{3.26}$$

Using the same method as derived in (3.26), we have

$$\begin{aligned}
\|y_{n+1} - y_n\| &\leq (1 - \alpha_n \beta_n) \|y_n - y_{n-1}\| + |\mu_n - \mu_{n-1}| \|y_{n-1}\| + \alpha_n \beta_n \sigma \|x_n - x_{n-1}\| \\
&\quad + |\alpha_n - \alpha_{n-1}| \left( \|\xi_2(x_{n-1})\| + \|v_{n-1}\| \right) + |\beta_n - \beta_{n-1}| \|T_{n-1}^*\|.
\end{aligned}
\tag{3.27}$$

From (3.26) and (3.27), we have

$$\begin{aligned}
\|x_{n+1} - x_n\| + \|y_{n+1} - y_n\| &\leq (1 - (1 - \sigma)\beta_n \alpha_n) (\|x_n - x_{n-1}\| + \|y_n - y_{n-1}\|) \\
&\quad + |\mu_n - \mu_{n-1}| (\|x_{n-1}\| + \|y_{n-1}\|) \\
&\quad + |\beta_n - \beta_{n-1}| (\|T_{n-1}\| + \|T_{n-1}^*\|) \\
&\quad + |\alpha_n - \alpha_{n-1}| (\|\xi_1(y_{n-1})\| + \|u_{n-1}\|) \\
&\quad + \|\xi_2(x_{n-1})\| + \|v_{n-1}\|.
\end{aligned}$$

Applying Lemma 2.3 and the condition (iii), we can conclude that

$$\lim_{n \rightarrow \infty} \|x_{n+1} - x_n\| = 0 \text{ and } \lim_{n \rightarrow \infty} \|y_{n+1} - y_n\| = 0.
\tag{3.28}$$

Next, we show that  $\|x_n - U_n\| \rightarrow 0$  as  $n \rightarrow \infty$  where  $U_n = \alpha_n \xi_1(y_n) + (1 - \alpha_n)u_n$ ,  $\|y_n - V_n\| \rightarrow 0$  where  $V_n = \alpha_n \xi_2(x_n) + (1 - \alpha_n)v_n$  as  $n \rightarrow \infty$ .

From the definition of  $x_n$ , we obtain

$$\begin{aligned}
 \|x_{n+1} - x^*\|^2 &= \|\mu_n x_n + \beta_n P_C U_n - x^*\|^2 \\
 &= \|\mu_n(x_n - x^*) + \beta_n(P_C U_n - x^*) - (1 - \mu_n - \beta_n)x^*\|^2 \\
 &\leq \|\mu_n(x_n - x^*) + \beta_n(P_C U_n - x^*)\|^2 \\
 &\quad - 2(1 - \mu_n - \beta_n)\langle x^*, x_{n+1} - x^* \rangle \\
 &\leq \|\mu_n(x_n - x^*) + \beta_n(P_C U_n - x^*)\|^2 \\
 &\quad + 2(1 - \mu_n - \beta_n)\|x^*\| \|x_{n+1} - x^*\| \\
 &= \mu_n(\mu_n + \beta_n)\|x_n - x^*\|^2 + \beta_n(\mu_n + \beta_n)\|P_C U_n - x^*\|^2 \\
 &\quad - \mu_n \beta_n \|x_n - P_C U_n\|^2 + 2(1 - \mu_n - \beta_n)\|x^*\| \|x_{n+1} - x^*\| \\
 &\leq \mu_n(\mu_n + \beta_n)\|x_n - x^*\|^2 + \beta_n(\mu_n + \beta_n)\|U_n - x^*\|^2 \\
 &\quad - \mu_n \beta_n \|x_n - P_C U_n\|^2 + 2(1 - \mu_n - \beta_n)\|x^*\| \|x_{n+1} - x^*\| \\
 &= \mu_n(\mu_n + \beta_n)\|x_n - x^*\|^2 \\
 &\quad + \beta_n(\mu_n + \beta_n)\|\alpha_n(\xi_1(y_n) - u_n) + (u_n - x^*)\|^2 \\
 &\quad - \mu_n \beta_n \|x_n - P_C U_n\|^2 + 2(1 - \mu_n - \beta_n)\|x^*\| \|x_{n+1} - x^*\| \\
 &\leq \mu_n(\mu_n + \beta_n)\|x_n - x^*\|^2 + \beta_n(\mu_n + \beta_n)\left(\|u_n - x^*\|^2 \right. \\
 &\quad \left. + 2\alpha_n \langle \xi_1(y_n) - u_n, \alpha_n \xi_1(y_n) + (1 - \alpha_n)u_n - x^* \rangle \right) \\
 &\quad - \mu_n \beta_n \|x_n - P_C U_n\|^2 + 2(1 - \mu_n - \beta_n)\|x^*\| \|x_{n+1} - x^*\| \\
 &\leq \mu_n(\mu_n + \beta_n)\|x_n - x^*\|^2 + \beta_n(\mu_n + \beta_n)\left(\|u_n - x^*\|^2 \right. \\
 &\quad \left. + 2\alpha_n \|\xi_1(y_n) - u_n\| \|\alpha_n \xi_1(y_n) + (1 - \alpha_n)u_n - x^*\| \right) \\
 &\quad - \mu_n \beta_n \|x_n - P_C U_n\|^2 + 2(1 - \mu_n - \beta_n)\|x^*\| \|x_{n+1} - x^*\| \\
 &\leq \|x_n - x^*\|^2 + 2\alpha_n \beta_n \|\xi_1(y_n) - u_n\| \|\alpha_n \xi_1(y_n) + (1 - \alpha_n)u_n - x^*\| \\
 &\quad - \mu_n \beta_n \|x_n - P_C U_n\|^2 + 2(1 - \mu_n - \beta_n)\|x^*\| \|x_{n+1} - x^*\|.
 \end{aligned}
 \tag{3.29}$$

It follows from (3.29) that

$$\begin{aligned}
 \mu_n \beta_n \|x_n - P_C U_n\|^2 &\leq \|x_n - x^*\|^2 - \|x_{n+1} - x^*\|^2 \\
 &\quad + 2\alpha_n \beta_n \|\xi_1(y_n) - u_n\| \|\alpha_n \xi_1(y_n) + (1 - \alpha_n)u_n - x^*\| \\
 &\quad + 2(1 - \mu_n - \beta_n)\|x^*\| \|x_{n+1} - x^*\| \\
 &\leq \|x_n - x_{n+1}\|(\|x_n - x^*\| + \|x_{n+1} - x^*\|) \\
 &\quad + 2\alpha_n \beta_n \|\xi_1(y_n) - u_n\| \|\alpha_n \xi_1(y_n) + (1 - \alpha_n)u_n - x^*\| \\
 &\quad + 2(1 - \mu_n - \beta_n)\|x^*\| \|x_{n+1} - x^*\|.
 \end{aligned}$$

By (3.28), the condition (i)- (iii), we get

$$\lim_{n \rightarrow \infty} \|P_C U_n - x_n\| = 0.
 \tag{3.30}$$

From definition of  $y_n$  and applying the same method as (3.30), we have

$$\lim_{n \rightarrow \infty} \|P_C V_n - y_n\| = 0.
 \tag{3.31}$$

From Lemma 2.1, we obtain

$$(3.32) \quad \|P_C U_n - x^*\|^2 \leq \|U_n - x^*\|^2 - \|U_n - P_C U_n\|^2.$$

From the definition of  $U_n$ , we get

$$(3.33) \quad \begin{aligned} \|U_n - x^*\|^2 &= \|\alpha_n(\xi_1(y_n) - x^*) + (1 - \alpha_n)(u_n - x^*)\|^2 \\ &\leq \alpha_n \|\xi_1(y_n) - x^*\|^2 + (1 - \alpha_n) \|u_n - x^*\|^2 \\ &\leq \alpha_n \|\xi_1(y_n) - x^*\|^2 + (1 - \alpha_n) \|x_n - x^*\|^2. \end{aligned}$$

From (3.32), (3.33), and Lemma 2.2, we obtain

$$\begin{aligned} \|x_{n+1} - x^*\|^2 &= \|\mu_n x_n + \beta_n P_C U_n - x^*\|^2 \\ &\leq \mu_n(\mu_n + \beta_n) \|x_n - x^*\|^2 + \beta_n(\mu_n + \beta_n) \|P_C U_n - x^*\|^2 \\ &\quad - \mu_n \beta_n \|x_n - P_C U_n\|^2 + 2(1 - \mu_n - \beta_n) \|x^*\| \|x_{n+1} - x^*\| \\ &\leq \mu_n(\mu_n + \beta_n) \|x_n - x^*\|^2 + \beta_n(\mu_n + \beta_n) (\|U_n - x^*\|^2 - \|U_n - P_C U_n\|^2) \\ &\quad - \mu_n \beta_n \|x_n - P_C U_n\|^2 + 2(1 - \mu_n - \beta_n) \|x^*\| \|x_{n+1} - x^*\| \\ &\leq \mu_n(\mu_n + \beta_n) \|x_n - x^*\|^2 + \beta_n(\mu_n + \beta_n) (\alpha_n \|\xi_1(y_n) - x^*\|^2 \\ &\quad + (1 - \alpha_n) \|x_n - x^*\|^2 - \|U_n - P_C U_n\|^2) - \mu_n \beta_n \|x_n - P_C U_n\|^2 \\ &\quad + 2(1 - \mu_n - \beta_n) \|x^*\| \|x_{n+1} - x^*\| \\ &= \mu_n \|x_n - x^*\|^2 + \beta_n \alpha_n \|\xi_1(y_n) - x^*\|^2 + \beta_n(1 - \alpha_n) \|x_n - x^*\|^2 \\ &\quad - \beta_n(\mu_n + \beta_n) \|U_n - P_C U_n\|^2 - \mu_n \beta_n \|x_n - P_C U_n\|^2 \\ &\quad + 2(1 - \mu_n - \beta_n) \|x^*\| \|x_{n+1} - x^*\| \\ &= (\mu_n + \beta_n(1 - \alpha_n)) \|x_n - x^*\|^2 + \beta_n \alpha_n \|\xi_1(y_n) - x^*\|^2 \\ &\quad - \beta_n(\mu_n + \beta_n) \|U_n - P_C U_n\|^2 - \mu_n \beta_n \|x_n - P_C U_n\|^2 \\ &\quad + 2(1 - \mu_n - \beta_n) \|x^*\| \|x_{n+1} - x^*\| \\ &\leq \|x_n - x^*\|^2 + \beta_n \alpha_n \|\xi_1(y_n) - x^*\|^2 - \beta_n(\mu_n + \beta_n) \|U_n - P_C U_n\|^2 \\ &\quad + 2(1 - \mu_n - \beta_n) \|x^*\| \|x_{n+1} - x^*\|, \end{aligned}$$

it follows that

$$\begin{aligned} \beta_n(\mu_n + \beta_n) \|U_n - P_C U_n\|^2 &\leq \|x_n - x^*\|^2 - \|x_{n+1} - x^*\|^2 + \alpha_n \beta_n \|\xi_1(y_n) - x^*\|^2 \\ &\quad + 2(1 - \mu_n - \beta_n) \|x^*\| \|x_{n+1} - x^*\| \\ &\leq \|x_n - x_{n+1}\| (\|x_n - x^*\| + \|x_{n+1} - x^*\|) \\ &\quad + \alpha_n \beta_n \|\xi_1(y_n) - x^*\|^2 \\ &\quad + 2(1 - \mu_n - \beta_n) \|x^*\| \|x_{n+1} - x^*\|. \end{aligned}$$

From  $\|x_{n+1} - x_n\| \rightarrow 0$  as  $n \rightarrow \infty$  and the condition (i), (ii), we have

$$(3.34) \quad \lim_{n \rightarrow \infty} \|U_n - P_C U_n\| = 0.$$

Applying the same argument as (3.34) to the definition of  $V_n$  also yields

$$(3.35) \quad \lim_{n \rightarrow \infty} \|V_n - P_C V_n\| = 0.$$

Consider

$$\begin{aligned} \|x_n - U_n\| &= \|x_n - P_C U_n + P_C U_n - U_n\| \\ &\leq \|x_n - P_C U_n\| + \|P_C U_n - U_n\|. \end{aligned}$$

From (3.30) and (3.34), we have

$$(3.36) \quad \lim_{n \rightarrow \infty} \|x_n - U_n\| = 0.$$

Using the same methodology as (3.36) and the definition of  $y_n$ , we also have

$$(3.37) \quad \lim_{n \rightarrow \infty} \|y_n - V_n\| = 0.$$

Next, we show that  $\|x_n - u_n\| \rightarrow 0$  as  $n \rightarrow \infty$  and  $\|y_n - v_n\| \rightarrow 0$  as  $n \rightarrow \infty$ . Observe that

$$U_n - x_n = \alpha_n(\xi_1(y_n) - x_n) + (1 - \alpha_n)(u_n - x_n),$$

this implies that

$$(3.38) \quad (1 - \alpha_n)\|u_n - x_n\| \leq \|U_n - x_n\| + \alpha_n\|\xi_1(y_n) - x_n\|.$$

From (3.36), (3.38), and the condition (i), we have

$$(3.39) \quad \lim_{n \rightarrow \infty} \|u_n - x_n\| = \lim_{n \rightarrow \infty} \|\text{Prox}_{\gamma f}^1(I - \gamma_1(a_1 A_1 + (1 - a_1)B_1))x_n - x_n\| = 0.$$

Applying the same argument as (3.39), we also obtain

$$(3.40) \quad \lim_{n \rightarrow \infty} \|v_n - y_n\| = \lim_{n \rightarrow \infty} \|\text{Prox}_{\gamma f}^2(I - \gamma_2(a_2 A_2 + (1 - a_2)B_2))y_n - y_n\| = 0.$$

Next, we show that  $\limsup_{n \rightarrow \infty} \langle \xi_1(y^*) - x^*, U_n - x^* \rangle \leq 0$ , where  $x^* = P_{\Omega_1} \xi_1(y^*)$  and  $\limsup_{n \rightarrow \infty} \langle \xi_2(x^*) - y^*, V_n - y^* \rangle \leq 0$ , where  $y^* = P_{\Omega_2} \xi_2(x^*)$ . Indeed, take a subsequence  $\{U_{n_k}\}$  of  $\{U_n\}$  such that

$$\limsup_{n \rightarrow \infty} \langle \xi_1(y^*) - x^*, U_n - x^* \rangle = \lim_{k \rightarrow \infty} \langle \xi_1(y^*) - x^*, U_{n_k} - x^* \rangle.$$

Since  $\{x_n\}, \{y_n\}$  are bounded, without loss of generality, we may assume that  $x_{n_k} \rightharpoonup \bar{x}$  and  $y_{n_k} \rightharpoonup \bar{y}$  as  $k \rightarrow \infty$ , respectively. Since  $C$  is closed and convex,  $C$  is weakly closed. So, we obtain  $\bar{x}, \bar{y} \in C$ .

Since  $\text{Prox}_{\gamma f}^i(I - \gamma_i(a_i A_i + (1 - a_i)B_i))$  is nonexpansive, for all  $i = 1, 2$ , (3.39), and (3.40), it follows from Lemma 2.5 that  $\bar{x} \in \text{Fix}(\text{Prox}_{\gamma f}^1(I - \gamma_1(a_1 A_1 + (1 - a_1)B_1)))$  and  $\bar{y} \in \text{Fix}(\text{Prox}_{\gamma f}^2(I - \gamma_2(a_2 A_2 + (1 - a_2)B_2)))$ .

By Lemma 2.4, we have

$$(3.41) \quad \bar{x} \in \text{Fix}(\text{Prox}_{\gamma f}^1(I - \gamma_1 A_1)) \cap \text{Fix}(\text{Prox}_{\gamma f}^1(I - \gamma_1 B_1)) = \Omega_1.$$

and

$$(3.42) \quad \bar{y} \in \text{Fix}(\text{Prox}_{\gamma f}^2(I - \gamma_2 A_2)) \cap \text{Fix}(\text{Prox}_{\gamma f}^2(I - \gamma_2 B_2)) = \Omega_2.$$

From (3.36), we obtain  $U_{n_k} \rightharpoonup \bar{x}$  as  $k \rightarrow \infty$ . Since  $U_{n_k} \rightharpoonup \bar{x}$  as  $k \rightarrow \infty$ ,  $\bar{x} \in \Omega_1$  and Lemma 2.1, we can derive that

$$(3.43) \quad \begin{aligned} \limsup_{n \rightarrow \infty} \langle \xi_1(y^*) - x^*, U_n - x^* \rangle &= \lim_{k \rightarrow \infty} \langle \xi_1(y^*) - x^*, U_{n_k} - x^* \rangle \\ &= \langle \xi_1(y^*) - x^*, \bar{x} - x^* \rangle \\ &\leq 0. \end{aligned}$$

Similarly, indeed, take a subsequence  $\{V_{n_k}\}$  of  $\{V_n\}$  such that

$$\limsup_{n \rightarrow \infty} \langle \xi_2(x^*) - y^*, V_n - y^* \rangle = \lim_{k \rightarrow \infty} \langle \xi_2(x^*) - y^*, V_{n_k} - y^* \rangle.$$

From (3.37), we obtain  $V_{n_k} \rightarrow \bar{y}$  as  $k \rightarrow \infty$ .

Following the same method as (3.43), we easily obtain that

$$(3.44) \quad \limsup_{n \rightarrow \infty} \langle \xi_2(x^*) - y^*, V_n - y^* \rangle \leq 0.$$

Finally, we show that  $\{x_n\}$  converges strongly to  $x^*$ , where  $x^* = P_{\Omega_1} \xi_1(y^*)$  and  $\{y_n\}$  converges strongly to  $y^*$ , where  $y^* = P_{\Omega_2} \xi_2(x^*)$ .

Since  $U_n = \alpha_n \xi_1(y_n) + (1 - \alpha_n)u_n$  and  $V_n = \alpha_n \xi_2(x_n) + (1 - \alpha_n)v_n$  and the definition of  $x_n$ , we get

$$\begin{aligned} \|x_{n+1} - x^*\|^2 &= \|\mu_n x_n + \beta_n P_C U_n - x^*\|^2 \\ &\leq \mu_n (\mu_n + \beta_n) \|x_n - x^*\|^2 + \beta_n (\mu_n + \beta_n) \|\alpha_n (\xi_1(y_n) - x^*) \\ &\quad + (1 - \alpha_n)(u_n - x^*)\|^2 + 2(1 - \mu_n - \beta_n) \|x^*\| \|x_{n+1} - x^*\| \\ &\leq \mu_n (\mu_n + \beta_n) \|x_n - x^*\|^2 + \beta_n (\mu_n + \beta_n) \left( (1 - \alpha_n) \|u_n - x^*\|^2 \right. \\ &\quad \left. + 2\alpha_n \langle \xi_1(y_n) - x^*, U_n - x^* \rangle \right) \\ &\quad + 2(1 - \mu_n - \beta_n) \|x^*\| \|x_{n+1} - x^*\| \\ &\leq \mu_n (\mu_n + \beta_n) \|x_n - x^*\|^2 + \beta_n (\mu_n + \beta_n) \left( (1 - \alpha_n) \|x_n - x^*\|^2 \right. \\ &\quad \left. + 2\alpha_n \langle \xi_1(y_n) - x^*, U_n - x^* \rangle \right) \\ &\quad + 2(1 - \mu_n - \beta_n) \|x^*\| \|x_{n+1} - x^*\| \\ &\leq \mu_n \|x_n - x^*\|^2 + \beta_n (1 - \alpha_n) \|x_n - x^*\|^2 \\ &\quad + 2\alpha_n \beta_n (\mu_n + \beta_n) \langle \xi_1(y_n) - x^*, U_n - x^* \rangle \\ &\quad + 2(1 - \mu_n - \beta_n) \|x^*\| \|x_{n+1} - x^*\| \\ &= (\mu_n + \beta_n (1 - \alpha_n)) \|x_n - x^*\|^2 + 2\alpha_n \beta_n (\mu_n + \beta_n) \langle \xi_1(y_n) - x^*, U_n - x^* \rangle \\ &\quad + 2(1 - \mu_n - \beta_n) \|x^*\| \|x_{n+1} - x^*\| \\ &= ((\mu_n + \beta_n) - \alpha_n \beta_n) \|x_n - x^*\|^2 \\ &\quad + 2\alpha_n \beta_n (\mu_n + \beta_n) \left( \langle \xi_1(y_n) - \xi_1(y^*), U_n - x^* \rangle + \langle \xi_1(y^*) - x^*, U_n - x^* \rangle \right) \\ &\quad + 2(1 - \mu_n - \beta_n) \|x^*\| \|x_{n+1} - x^*\| \\ &\leq (1 - \alpha_n \beta_n) \|x_n - x^*\|^2 \\ &\quad + 2\alpha_n \beta_n (\mu_n + \beta_n) (\|\xi_1(y_n) - \xi_1(y^*)\| \|U_n - x^*\| + \langle \xi_1(y^*) - x^*, U_n - x^* \rangle) \\ &\quad + 2(1 - \mu_n - \beta_n) \|x^*\| \|x_{n+1} - x^*\| \\ &\leq (1 - \alpha_n \beta_n) \|x_n - x^*\|^2 \\ &\quad + 2\alpha_n \beta_n \|\xi_1(y_n) - \xi_1(y^*)\| (\|U_n - x_{n+1}\| + \|x_{n+1} - x^*\|) \\ &\quad + 2\alpha_n \beta_n (\mu_n + \beta_n) \langle \xi_1(y^*) - x^*, U_n - x^* \rangle \\ &\quad + 2(1 - \mu_n - \beta_n) \|x^*\| \|x_{n+1} - x^*\| \end{aligned}$$

$$\begin{aligned}
 &\leq (1 - \alpha_n \beta_n) \|x_n - x^*\|^2 \\
 &\quad + 2\alpha_n \beta_n \sigma \|y_n - y^*\| \|U_n - x_{n+1}\| + 2\alpha_n \beta_n \sigma \|y_n - y^*\| \|x_{n+1} - x^*\| \\
 &\quad + 2\alpha_n \beta_n (\mu_n + \beta_n) \langle \xi_1(y^*) - x^*, U_n - x^* \rangle \\
 &\quad + 2(1 - \mu_n - \beta_n) \|x^*\| \|x_{n+1} - x^*\| \\
 &\leq (1 - \alpha_n \beta_n) \|x_n - x^*\|^2 \\
 &\quad + 2\alpha_n \beta_n \sigma \|y_n - y^*\| \|U_n - x_{n+1}\| + \alpha_n \beta_n \sigma (\|y_n - y^*\|^2 + \|x_{n+1} - x^*\|^2) \\
 &\quad + 2\alpha_n \beta_n (\mu_n + \beta_n) \langle \xi_1(y^*) - x^*, U_n - x^* \rangle \\
 &\quad + 2(1 - \mu_n - \beta_n) \|x^*\| \|x_{n+1} - x^*\|,
 \end{aligned}$$

which yields that

$$\begin{aligned}
 \|x_{n+1} - x^*\|^2 &\leq \frac{1 - \alpha_n \beta_n}{1 - \alpha_n \beta_n \sigma} \|x_n - x^*\|^2 + \frac{2\alpha_n \beta_n \sigma}{1 - \alpha_n \beta_n \sigma} \|y_n - y^*\| \|U_n - x_{n+1}\| \\
 &\quad + \frac{\alpha_n \beta_n \sigma}{1 - \alpha_n \beta_n \sigma} \|y_n - y^*\|^2 + \frac{2\alpha_n \beta_n (\mu_n + \beta_n)}{1 - \alpha_n \beta_n \sigma} \langle \xi_1(y^*) - x^*, U_n - x^* \rangle \\
 &\quad + \frac{2(1 - \mu_n - \beta_n)}{1 - \alpha_n \beta_n \sigma} \|x^*\| \|x_{n+1} - x^*\| \\
 &= \left(1 - \frac{\alpha_n \beta_n - \alpha_n \beta_n \sigma}{1 - \alpha_n \beta_n \sigma}\right) \|x_n - x^*\|^2 + \frac{2\alpha_n \beta_n \sigma}{1 - \alpha_n \beta_n \sigma} \|y_n - y^*\| \|U_n - x_{n+1}\| \\
 &\quad + \frac{\alpha_n \beta_n \sigma}{1 - \alpha_n \beta_n \sigma} \|y_n - y^*\|^2 + \frac{2\alpha_n \beta_n (\mu_n + \beta_n)}{1 - \alpha_n \beta_n \sigma} \langle \xi_1(y^*) - x^*, U_n - x^* \rangle \\
 &\quad + \frac{2(1 - \mu_n - \beta_n)}{1 - \alpha_n \beta_n \sigma} \|x^*\| \|x_{n+1} - x^*\| \\
 &= \left(1 - \frac{\alpha_n \beta_n (1 - \sigma)}{1 - \alpha_n \beta_n \sigma}\right) \|x_n - x^*\|^2 + \frac{2\alpha_n \beta_n \sigma}{1 - \alpha_n \beta_n \sigma} \|y_n - y^*\| \|U_n - x_{n+1}\| \\
 &\quad + \frac{\alpha_n \beta_n \sigma}{1 - \alpha_n \beta_n \sigma} \|y_n - y^*\|^2 + \frac{2\alpha_n \beta_n (\mu_n + \beta_n)}{1 - \alpha_n \beta_n \sigma} \langle \xi_1(y^*) - x^*, U_n - x^* \rangle \\
 &\quad + \frac{2(1 - \mu_n - \beta_n)}{1 - \alpha_n \beta_n \sigma} \|x^*\| \|x_{n+1} - x^*\|,
 \end{aligned}$$

there exists  $\hat{M} > 0$ , such that

$$\begin{aligned}
 \|x_{n+1} - x^*\|^2 &\leq \left(1 - \frac{\alpha_n \beta_n (1 - \sigma)}{1 - \alpha_n \beta_n \sigma}\right) \|x_n - x^*\|^2 + \frac{2\alpha_n \beta_n \sigma}{1 - \alpha_n \beta_n \sigma} \|y_n - y^*\| \|U_n - x_{n+1}\| \\
 &\quad + \frac{\alpha_n \beta_n \sigma}{1 - \alpha_n \beta_n \sigma} \|y_n - y^*\|^2 + \frac{2\alpha_n \beta_n (\mu_n + \beta_n)}{1 - \alpha_n \beta_n \sigma} \langle \xi_1(y^*) - x^*, U_n - x^* \rangle \\
 (3.45) \quad &\quad + (1 - \mu_n - \beta_n) \hat{M} \|x^*\| \|x_{n+1} - x^*\|.
 \end{aligned}$$

Similarly, as previously stated, there exists  $\bar{M} > 0$ , such that

$$\begin{aligned}
 \|y_{n+1} - y^*\|^2 &\leq \left(1 - \frac{\alpha_n \beta_n (1 - \sigma)}{1 - \alpha_n \beta_n \sigma}\right) \|y_n - y^*\|^2 + \frac{2\alpha_n \beta_n \sigma}{1 - \alpha_n \beta_n \sigma} \|x_n - x^*\| \|V_n - y_{n+1}\| \\
 &\quad + \frac{\alpha_n \beta_n \sigma}{1 - \alpha_n \beta_n \sigma} \|x_n - x^*\|^2 + \frac{2\alpha_n \beta_n (\mu_n + \beta_n)}{1 - \alpha_n \beta_n \sigma} \langle \xi_2(x^*) - y^*, V_n - y^* \rangle \\
 (3.46) \quad &\quad + (1 - \mu_n - \beta_n) \bar{M} \|y^*\| \|y_{n+1} - y^*\|.
 \end{aligned}$$

From (3.45), (3.46), and choose  $M = \max\{\hat{M}, \bar{M}\}$ , we get

$$\begin{aligned}
 & \|x_{n+1} - x^*\|^2 + \|y_{n+1} - y^*\|^2 \\
 & \leq \left(1 - \frac{\alpha_n \beta_n (1 - \sigma)}{1 - \alpha_n \beta_n \sigma}\right) (\|x_n - x^*\|^2 + \|y_n - y^*\|^2) \\
 & \quad + \frac{2\alpha_n \beta_n \sigma}{1 - \alpha_n \beta_n \sigma} (\|y_n - y^*\| \|U_n - x_{n+1}\| + \|x_n - x^*\| \|V_n - y_{n+1}\|) \\
 & \quad + \frac{\alpha_n \beta_n \sigma}{1 - \alpha_n \beta_n \sigma} (\|x_n - x^*\|^2 + \|y_n - y^*\|^2) \\
 & \quad + \frac{2\alpha_n \beta_n (\mu_n + \beta_n)}{1 - \alpha_n \beta_n \sigma} (\langle \xi_1(y^*) - x^*, U_n - x^* \rangle + \langle \xi_2(x^*) - y^*, V_n - y^* \rangle) \\
 & \quad + (1 - \mu_n - \beta_n) M (\|x^*\| \|x_{n+1} - x^*\| + \|y^*\| \|y_{n+1} - y^*\|) \\
 & = \left(1 - \frac{\alpha_n \beta_n (1 - 2\sigma)}{1 - \alpha_n \beta_n \sigma}\right) (\|x_n - x^*\|^2 + \|y_n - y^*\|^2) \\
 & \quad + \frac{2\alpha_n \beta_n \sigma}{1 - \alpha_n \beta_n \sigma} (\|y_n - y^*\| \|U_n - x_{n+1}\| + \|x_n - x^*\| \|V_n - y_{n+1}\|) \\
 & \quad + \frac{2\alpha_n \beta_n (\mu_n + \beta_n)}{1 - \alpha_n \beta_n \sigma} (\langle \xi_1(y^*) - x^*, U_n - x^* \rangle + \langle \xi_2(x^*) - y^*, V_n - y^* \rangle) \\
 (3.47) \quad & \quad + (1 - \mu_n - \beta_n) M (\|x^*\| \|x_{n+1} - x^*\| + \|y^*\| \|y_{n+1} - y^*\|).
 \end{aligned}$$

By (3.28), (3.36), (3.37), (3.43), (3.44), the condition (i), (iii) and Lemma 2.3, we have  $\lim_{n \rightarrow \infty} (\|x_n - x^*\| + \|y_n - y^*\|) = 0$ . It implies that the sequences  $\{x_n\}, \{y_n\}$  converge to  $x^* = P_{\Omega_1} \xi_1(y^*), y^* = P_{\Omega_2} \xi_2(x^*)$ , respectively. This completes the proof.  $\square$

**Remark 3.1.** We have the following observations for the offered Algorithms 1.

- (1) It should be noted that we use a new mathematical tool (Lemma 2.4) related to two proximal operators that exploits the information of  $v_n$  and  $u_n$ , which actually draws inspiration from Xu [29] and Guo and Cui [8].
- (2) By combining the proximal-gradient algorithm with viscosity technique in Guo and Cui [8], the intermixed algorithm in Yao et al.[32] and the Krasnoselskii–Mann algorithm in Kanzow and Shehu [12], the algorithm presented in this paper provide a strong convergence theorem in real Hilbert spaces.

#### 4. APPLICATIONS

In this section, we reduce our main problem to the following the split feasibility problems.

**4.1. The Split Feasibility Problem.** Let  $C$  and  $Q$  be nonempty closed convex subsets of Hilbert spaces  $H_1$  and  $H_2$ , respectively. The *split feasibility problem* is to find a point

$$(4.48) \quad x \in C \text{ such that } Ax \in Q,$$

where  $A : H_1 \rightarrow H_2$  is a bounded linear operator. The set of all solution (SFP) is denoted by  $\Gamma = \{x \in C; Ax \in Q\}$ . The split feasibility problem is the first example of the split inverse problem, which was first introduced by Censor and Elfving [5] in Euclidean spaces.

**Proposition 4.2.** ([6]) *Given  $x^* \in \mathcal{H}_1$ , the following statements are equivalent.*

- (i)  $x^*$  solves the  $\Gamma$ ;
- (ii)  $P_C(I - \lambda A^*(I - P_Q)A)x^* = x^*$ , where  $A^*$  is the adjoint of  $A$ ;



(iii)  $x^*$  solves the variational inequality problem of finding  $x^* \in C$  such that

$$(4.49) \quad \langle \nabla Q(x^*), x - x^* \rangle \geq 0, \quad \forall x \in C,$$

where  $\nabla Q = A^*(I - P_Q)A$ .

If  $C$  is a closed convex subset of  $H$  and the function  $f$  is the indicator function of  $C$  then it is well known that  $\text{Prox}_{\gamma f} = P_C$ , the projection operator of  $H$ , onto the closed convex set  $C$  and putting  $A_i = B_i$  for all  $i = 1, 2$  in Theorem 3.1. Consequently, the following result can be obtain from Theorem 3.1.

**Algorithm 2:** An intermixed algorithm with viscosity technique for solving the split feasibility problems.

Initialization: Given  $x_1, y_1 \in C$  be arbitrary.

Iterative Steps: Given the current iterate  $\{x_n\}, \{y_n\}$ , calculate  $\{x_{n+1}\}, \{y_{n+1}\}$  as follows:

Step 1: Compute

$$\begin{cases} v_n = P_C(I - \gamma_2 \nabla Q_2)y_n \\ u_n = P_C(I - \gamma_1 \nabla Q_1)x_n \end{cases}$$

Step 2: Compute

$$\begin{cases} y_{n+1} = \mu_n y_n + \beta_n P_C(\alpha_n \xi_2(x_n) + (1 - \alpha_n)v_n) \\ x_{n+1} = \mu_n x_n + \beta_n P_C(\alpha_n \xi_1(y_n) + (1 - \alpha_n)u_n), \end{cases}$$

where  $\nabla Q_i = A_i^*(I - P_Q)A_i$ ,  $\gamma_i \in (0, \frac{2}{\|A_i\|^2})$ ,  $\{\mu_n\}, \{\beta_n\}, \{\alpha_n\} \subseteq [0, 1]$ , with  $\mu_n + \beta_n \leq 1$ .

Set  $n := n + 1$  and go to Step 1.

From Proposition 4.2, it is clear that the solution of the problem (4.49) is the same as the problem (4.48). By applying the aforementioned technique, it is possible to find the solution to the two-split feasibility problem, as demonstrated in the following theorem.

**Theorem 4.2.** Let  $H_1$  and  $H_2$  be real Hilbert spaces and let  $C, Q$  be two nonempty closed convex subsets of real Hilbert spaces  $H_1$  and  $H_2$ , respectively. Let  $A_1, A_2 : H_1 \rightarrow H_2$  be bounded linear operators with  $A_1^*, A_2^*$  are adjoint of  $A_1$  and  $A_2$ , respectively. Assume that  $\Gamma_1 = \{x^* \in C; A_1 x^* \in Q\} \neq \emptyset$  and  $\Gamma_2 = \{y^* \in C; A_1 y^* \in Q\} \neq \emptyset$ . Let  $\xi_1, \xi_2 : H \rightarrow H$  be  $\sigma_1$  and  $\sigma_2$ -contraction mappings with  $\sigma_1, \sigma_2 \in (0, 1)$  and  $\sigma = \max\{\sigma_1, \sigma_2\}$ . Let  $\{x_n\}$  and  $\{y_n\}$  be the sequences generated by Algorithm 2, satisfying the following conditions:

- (i)  $\lim_{n \rightarrow \infty} \alpha_n = 0$  and  $\sum_{n=1}^{\infty} \alpha_n = \infty$ ;
- (ii) there are  $\bar{\epsilon}, l > 0$  with  $0 < \bar{\epsilon} \leq \mu_n, \beta_n \leq l < 1$  for all  $n \in \mathbb{N}_+$ ;
- (iii)  $\sum_{n=1}^{\infty} |\alpha_{n+1} - \alpha_n| < \infty, \sum_{n=1}^{\infty} |\mu_{n+1} - \mu_n| < \infty, \sum_{n=1}^{\infty} |\beta_{n+1} - \beta_n| < \infty, \sum_{n=1}^{\infty} (1 - \mu_n - \beta_n) < \infty$ .

Then  $\{x_n\}$  and  $\{y_n\}$  converge strongly to  $x^* = P_{\Gamma_1} \xi_1(y^*)$  and  $y^* = P_{\Gamma_2} \xi_2(x^*)$ , respectively.

*Proof.* Let  $x^*, x_0 \in C$  and  $\nabla Q_i = A_i^*(I - P_Q)A_i$ , for all  $i = 1, 2$ . First, we show that  $\nabla Q_i$  is  $\frac{1}{\|A_i\|^2}$ -inverse strongly monotone for all  $i = 1, 2$ . Since  $P_Q$  is firmly nonexpansive, then

$P_Q$  is  $\frac{1}{2}$ -averaged mapping, thus  $I - P_Q$  is 1-inverse strongly monotone. Observe that

$$\begin{aligned} \langle \nabla \mathcal{Q}_i(x^*) - \nabla \mathcal{Q}_i(x_0), x^* - x_0 \rangle &= \langle A_i^*(I - P_Q)A_i x^* - A_i^*(I - P_Q)A_i x_0, x^* - x_0 \rangle \\ &= \langle (I - P_Q)A_i x^* - (I - P_Q)A_i x_0, A_i x^* - A_i x_0 \rangle \\ &\geq \|(I - P_Q)A_i x^* - (I - P_Q)A_i x_0\|^2 \\ &\geq \frac{1}{\|A_i\|^2} \cdot \|A_i^*(I - P_Q)A_i x^* - A_i^*(I - P_Q)A_i x_0\|^2 \\ &= \frac{1}{\|A_i\|^2} \cdot \|\nabla \mathcal{Q}_i(x^*) - \nabla \mathcal{Q}_i(x_0)\|^2. \end{aligned}$$

Then  $\nabla \mathcal{Q}_i$  is  $\frac{1}{\|A_i\|^2}$ -inverse strongly monotone, for all  $i = 1, 2$ . So, we can conclude of Theorem 4.2 from Proposition 4.2 and Theorem 3.1.  $\square$

## 5. NUMERICAL EXAMPLES

In this section, we give some numerical examples to support our main theorem. All the numerical results are completed on Apple MacBook Pro with 2 GHz Quad-Core Intel Core i5. The program is implemented in Python 3.10.4.

**Example 5.1.** We consider our problem in the infinite-dimensional Hilbert space  $H = L_2([0, 1])$  with the inner product defined by

$$\langle x, y \rangle := \int_0^1 x(t)y(t)dt, \quad \forall x, y \in H$$

and the induced norm by

$$\|x\|_2 := \left( \int_0^1 |x(t)|^2 dt \right)^{\frac{1}{2}}, \quad \forall x \in H.$$

Let  $C := \{x \in L_2([0, 1]) : \|x\| \leq 1\}$  be the unit ball. Then, we have

$$(5.50) \quad P_C(x(t)) = \begin{cases} x(t), & \text{if } \|x(t)\|_2 \leq 1, \\ \frac{x(t)}{\|x(t)\|_2}, & \text{if } \|x(t)\|_2 > 1. \end{cases}$$

Now take  $f = \|\cdot\|_2$ , the norm in  $L_2([0, 1])$ . Then, the proximal operator is given by

$$(5.51) \quad \text{Prox}_{\gamma f}(x(t)) = \begin{cases} \left(1 - \frac{\gamma}{\|x(t)\|_2}\right) x(t), & \text{if } \|x(t)\|_2 \geq \gamma, \\ 0, & \text{if } \|x(t)\|_2 < \gamma. \end{cases}$$

This proximal operator is also known as the block soft thresholding operator.

For every  $i = 1, 2$ , let  $A_i, B_i : C \rightarrow H$  defined by

$$A_1(x(t)) = x(t), A_2(x(t)) = \frac{x(t)}{3}, B_1(x(t)) = 5x(t) \text{ and } B_2(x(t)) = \frac{22x(t)}{7},$$

for all  $t \in [0, 1]$ ,  $x \in C$ . For every  $i = 1, 2$ , we take the operator  $\xi_i : H \rightarrow H$  to be defined as  $\xi_1(x(t)) = \frac{x(t)}{25}$  and  $\xi_2(x(t)) = \frac{x(t)}{36}$ , for all  $t \in [0, 1]$ ,  $x \in H$ . In Algorithm 1, choose  $\alpha_n = \frac{1}{5n}$ ,  $\mu_n = \frac{1}{(n+1)^2} - \frac{1}{(n+1)^4}$ ,  $\beta_n = 1 - \frac{1}{(n+1)^2}$ ,  $a_1 = 0.70$  and  $a_2 = 0.20$ , for all

$n \in \mathbb{N}$ . So our Algorithm 1 has the following form:

(5.52)

$$\begin{cases} v_n = \text{Prox}_{\gamma f}^2(y_n - \gamma_2(0.2A_2 + 0.8B_2)y_n) \\ u_n = \text{Prox}_{\gamma f}^1(x_n - \gamma_1(0.7A_1 + 0.3B_1)x_n) \\ y_{n+1} = \left(\frac{1}{(n+1)^2} - \frac{1}{(n+1)^4}\right)y_n + \left(1 - \frac{1}{(n+1)^2}\right)P_C\left(\frac{1}{5n}\xi_2(x_n) + \left(1 - \frac{1}{5n}\right)v_n\right) \\ x_{n+1} = \left(\frac{1}{(n+1)^2} - \frac{1}{(n+1)^4}\right)x_n + \left(1 - \frac{1}{(n+1)^2}\right)P_C\left(\frac{1}{5n}\xi_1(y_n) + \left(1 - \frac{1}{5n}\right)u_n\right). \end{cases}$$

We test the Algorithm 1 for three different starting points and use  $\|x_{n+1} - x_n\|_2 < 10^{-10}$  and  $\|y_{n+1} - y_n\|_2 < 10^{-10}$  as stopping criterion.

**Case 1:**  $x_1 = \frac{t}{5}$  and  $y_1 = \frac{t}{7}$ ;

**Case 2:**  $x_1 = e^{-5t}$  and  $y_1 = \frac{t^2}{2}$ ;

**Case 3:**  $x_1 = \sin(2t)$  and  $y_1 = \cos(2t)$ .

According to the definition of  $A_i, B_i, f_i$ , for all  $i = 1, 2$ , then the solution of the problem is  $x^*(t) = \{0\}$ . The computational experiments, using our Algorithm 1, for each case are reported in Tables 1, 2, 3, and Figures 1, 2, 3. The convergence behavior of the error  $\|x_n - x_{n-1}\|_2$  and  $\|y_n - y_{n-1}\|_2$  for each case is shown in Figure 4.

TABLE 1. Computational result of **Case 1** for Example 5.1.

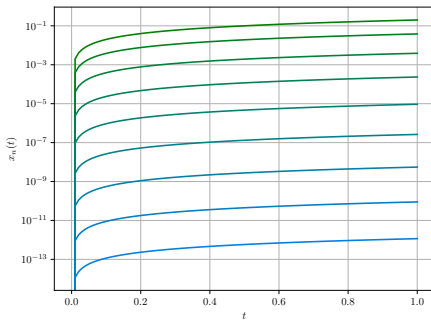
$n$	$x_n(t)$	$y_n(t)$	$\ x_{n+1} - x_n\ _2$	$\ y_n - y_{n-1}\ _2$
1	$0.2t$	$0.14286t$	-	-
2	$0.038357t$	$0.027619t$	$0.093325$	$0.066533$
3	$0.0038866t$	$0.0028225t$	$0.019902$	$0.014316$
4	$0.00023478t$	$0.00017213t$	$0.0021084$	$0.0015302$
5	$9.3462 \cdot 10^{-6}t$	$6.9228 \cdot 10^{-6}t$	$0.00013016$	$9.5382 \cdot 10^{-5}$
6	$2.6317 \cdot 10^{-7}t$	$1.9705 \cdot 10^{-7}t$	$5.2441 \cdot 10^{-6}$	$3.8831 \cdot 10^{-6}$
7	$5.5187 \cdot 10^{-9}t$	$4.1782 \cdot 10^{-9}t$	$1.4876 \cdot 10^{-7}$	$1.1136 \cdot 10^{-7}$
8	$8.9582 \cdot 10^{-11}t$	$6.8575 \cdot 10^{-11}t$	$3.1345 \cdot 10^{-9}$	$2.3727 \cdot 10^{-9}$
9	$1.16 \cdot 10^{-12}t$	$8.976 \cdot 10^{-13}t$	$5.1051 \cdot 10^{-11}$	$3.9074 \cdot 10^{-11}$

TABLE 2. Computational result of **Case 2** for Example 5.1.

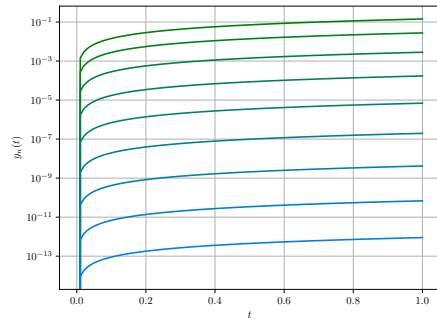
$n$	$x_n(t)$	$y_n(t)$	$\ x_n - x_{n-1}\ _2$	$\ y_n - y_{n-1}\ _2$
1	$e^{-5t}$	$0.2t^2$	-	-
2	$0.0012t^2 + 0.1875e^{-5t}$	$0.0375t^2 + 0.0041667e^{-5t}$	$0.25688$	$0.072554$
3	$0.00025185t^2 + 0.018533e^{-5t}$	$0.0037067t^2 + 0.00087449e^{-5t}$	$0.053474$	$0.015251$
4	$2.4024 \cdot 10^{-5}t^2 + 0.0010881e^{-5t}$	$0.00021762t^2 + 8.3415 \cdot 10^{-5}e^{-5t}$	$0.0055276$	$0.0016045$
5	$1.3403 \cdot 10^{-6}t^2 + 4.1944 \cdot 10^{-5}e^{-5t}$	$8.3888 \cdot 10^{-6}t^2 + 4.654 \cdot 10^{-6}e^{-5t}$	$0.00033198$	$9.9186 \cdot 10^{-5}$
6	$4.9247 \cdot 10^{-8}t^2 + 1.14 \cdot 10^{-6}e^{-5t}$	$2.28 \cdot 10^{-7}t^2 + 1.71 \cdot 10^{-7}e^{-5t}$	$1.2973 \cdot 10^{-5}$	$4.044 \cdot 10^{-6}$
7	$1.2823 \cdot 10^{-9}t^2 + 2.3014 \cdot 10^{-8}e^{-5t}$	$4.6027 \cdot 10^{-9}t^2 + 4.4525 \cdot 10^{-9}e^{-5t}$	$3.5598 \cdot 10^{-7}$	$1.1746 \cdot 10^{-7}$
8	$2.4901 \cdot 10^{-11}t^2 + 3.5898 \cdot 10^{-10}e^{-5t}$	$7.1796 \cdot 10^{-11}t^2 + 8.6463 \cdot 10^{-11}e^{-5t}$	$7.2412 \cdot 10^{-9}$	$2.5624 \cdot 10^{-9}$
9	$3.7454 \cdot 10^{-13}t^2 + 4.4625 \cdot 10^{-12}e^{-5t}$	$8.925 \cdot 10^{-13}t^2 + 1.3005 \cdot 10^{-12}e^{-5t}$	$1.1372 \cdot 10^{-10}$	$4.3587 \cdot 10^{-11}$
10	$4.4933 \cdot 10^{-15}t^2 + 4.5323 \cdot 10^{-14}e^{-5t}$	$9.0647 \cdot 10^{-15}t^2 + 1.5602 \cdot 10^{-14}e^{-5t}$	$1.4228 \cdot 10^{-12}$	$5.9411 \cdot 10^{-13}$

TABLE 3. Computational result of **Case 3** for Example 5.1.

$n$	$x_n(t)$	$y_n(t)$	$\ x_n - x_{n-1}\ _2$	$\ y_n - y_{n-1}\ _2$
1	$\sin(2t)$	$\cos(2t)$	-	-
2	$0.1875 \sin(2t) + 0.006 \cos(2t)$	$0.0041667 \sin(2t) + 0.4676 \cos(2t)$	0.62492	0.33764
3	$0.018533 \sin(2t) + 0.0022552 \cos(2t)$	$0.0012487 \sin(2t) + 0.088194 \cos(2t)$	0.13131	0.24253
4	$0.0010891 \sin(2t) + 0.00035263 \cos(2t)$	$0.00010534 \sin(2t) + 0.0051715 \cos(2t)$	0.014005	0.053239
5	$4.2022 \cdot 10^{-5} \sin(2t) + 2.347 \cdot 10^{-5} \cos(2t)$	$5.4972 \cdot 10^{-6} \sin(2t) + 0.00019906 \cos(2t)$	0.00091556	0.0031992
6	$1.1434 \cdot 10^{-6} \sin(2t) + 9.4349 \cdot 10^{-7} \cos(2t)$	$1.9385 \cdot 10^{-7} \sin(2t) + 5.4012 \cdot 10^{-6} \cos(2t)$	$3.975 \cdot 10^{-5}$	0.00012508
7	$2.3112 \cdot 10^{-8} \sin(2t) + 2.5917 \cdot 10^{-8} \cos(2t)$	$4.9126 \cdot 10^{-9} \sin(2t) + 1.0883 \cdot 10^{-7} \cos(2t)$	$1.2299 \cdot 10^{-6}$	$3.4336 \cdot 10^{-6}$
8	$3.6101 \cdot 10^{-10} \sin(2t) + 5.2106 \cdot 10^{-10} \cos(2t)$	$9.3615 \cdot 10^{-11} \sin(2t) + 1.6942 \cdot 10^{-9} \cos(2t)$	$2.8427 \cdot 10^{-8}$	$6.9863 \cdot 10^{-8}$
9	$4.4943 \cdot 10^{-12} \sin(2t) + 8.0267 \cdot 10^{-12} \cos(2t)$	$1.3891 \cdot 10^{-12} \sin(2t) + 2.1015 \cdot 10^{-11} \cos(2t)$	$5.0783 \cdot 10^{-10}$	$1.0972 \cdot 10^{-9}$
10	$4.5716 \cdot 10^{-14} \sin(2t) + 9.7958 \cdot 10^{-14} \cos(2t)$	$1.6498 \cdot 10^{-14} \sin(2t) + 2.1296 \cdot 10^{-13} \cos(2t)$	$7.1996 \cdot 10^{-12}$	$1.3724 \cdot 10^{-11}$

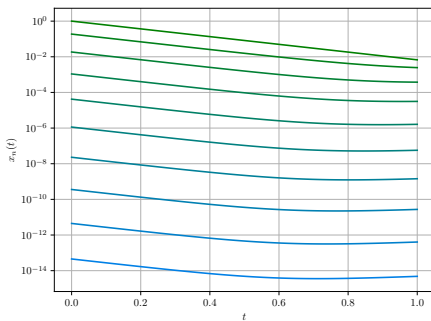


(A) **Case 1** :  $x_1 = \frac{t}{5}$  for  $n = 1, 2, 3, \dots, 8$ .  
and

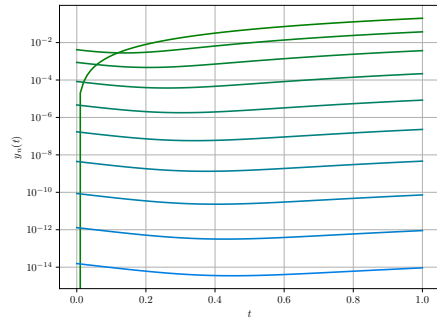


(B) **Case 1** :  $y_1 = \frac{t}{7}$  for  $n = 1, 2, 3, \dots, 8$ .

FIGURE 1. The convergence behavior of  $\{x_n(t)\}$  and  $\{y_n(t)\}$  with **Case 1** in Example 5.1 and  $y$ -axis is illustrated in Log scale.

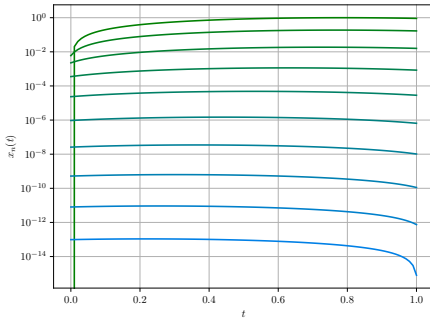


(A) **Case 2** :  $x_1 = e^{-5t}$  for  $n = 1, 2, 3, \dots, 9$ .

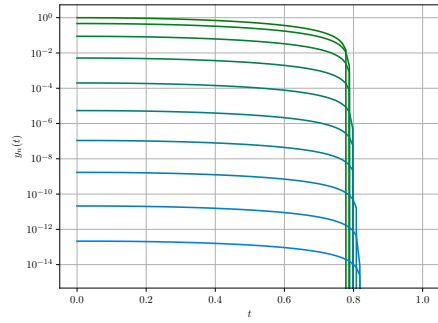


(B) **Case 2** :  $y_1 = \frac{t^2}{2}$  for  $n = 1, 2, 3, \dots, 9$ .

FIGURE 2. The convergence behavior of  $\{x_n(t)\}$  and  $\{y_n(t)\}$  with **Case 2** in Example 5.1 and  $y$ -axis is illustrated in logscale.

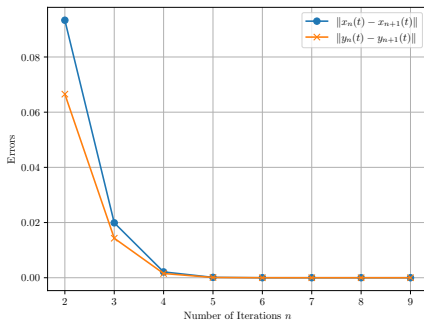


(A) **Case 3** :  $x_1 = \sin(2t)$  for  $n = 1, 2, 3, \dots, 9$ .

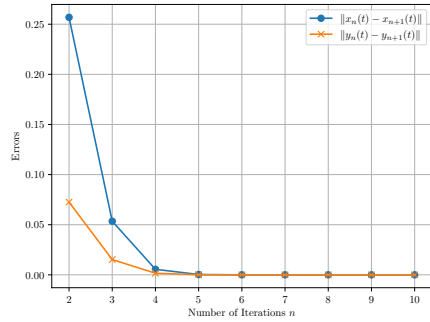


(B) **Case 3** :  $y_1 = \cos(2t)$  for  $n = 1, 2, 3, \dots, 9$ .

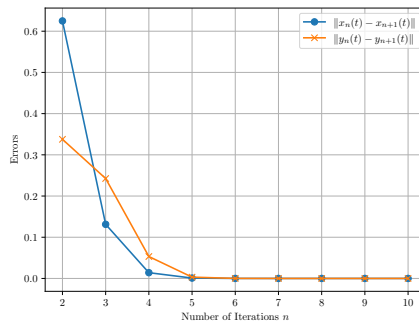
FIGURE 3. The convergence behavior of  $\{x_n(t)\}$  and  $\{y_n(t)\}$  with **Case 3** in Example 5.1 and  $y$ -axis is illustrated in logscale.



(A) **Case 1** :  $x_1 = 0.2t$  and  $y_1 = 0.8t$ .



(B) **Case 2** :  $x_1 = e^{-2t}$  and  $y_1 = \frac{t^2}{2}$ .



(C) **Case 3** :  $x_1 = \sin(2t)$  and  $y_1 = \cos(2t)$

FIGURE 4. Error plotting of  $\|x_n - x_{n-1}\|_2$  and  $\|y_n - y_{n-1}\|_2$  in Example 5.1.

Moreover, we also provide the comparison (in terms of convergence and the CPU time) of the sequences  $\mu_n$  and  $\beta_n$  on Algorithm 1 by choosing different  $\mu_n$  and  $\beta_n$  with  $\mu_n + \beta_n \leq$

1 satisfying the conditions (ii), (iii) in the following choices.

**Choice 1:**  $\mu_n = \frac{1}{(n+1)^2} - \frac{1}{(n+1)^4}$  and  $\beta_n = 1 - \frac{1}{(n+1)^2}$ ;

**Choice 2:**  $\mu_n = \frac{n}{(8n+9)} - \frac{1}{(n^2+1)}$  and  $\beta_n = 1 - \frac{1}{(n^2+1)}$ ;

**Choice 3:**  $\mu_n = \frac{1}{n+1} - \frac{1}{(n+1)^{20}}$  and  $\beta_n = 1 - \frac{1}{n+1}$ ;

**Choice 4:**  $\mu_n = \frac{1}{n^2+1}$  and  $\beta_n = 1 - \frac{1}{n^2+1}$ .

It is emphasized that all these sequences of  $\mu_n$  and  $\beta_n$  are to satisfy conditions (ii) and (iii). The results are reported in Table 4.

TABLE 4. Comparison of Algorithm 1 for Example 5.1 with different cases of  $\mu_n$  and  $\beta_n$ .

Starting point		Choice 1	Choice 2	Choice 3	Choice 4
$x_1 = \frac{t}{5}$	No. of Iter.	9	10	14	16
$y_1 = \frac{t}{7}$	CPU Time (s)	0.56213975	0.69141006	0.92488122	1.04418993

**Remark 5.2.** By testing the convergence behavior of Algorithm 1, we see in Example 5.1 that

- (1) Tables 1, 2, 3 and Figures 1, 2, 3, 4 show that  $\{x_n\}$  and  $\{y_n\}$  converge to  $x(t) = \mathbf{0}$ , where  $\mathbf{0} \in \text{Fix}(\text{Prox}_{\gamma f}(I - \gamma A)) \cap \text{Fix}(\text{Prox}_{\gamma g}(I - \gamma B))$ , for all  $i = 1, 2$ . The convergence of  $\{x_n\}$  and  $\{y_n\}$  of Example 5.1 can be guaranteed by Theorem 3.1.
- (2) From the discussion of Tables 1, 2, and 3, we see that the sequences  $\{x_n\}$  and  $\{y_n\}$  in **Case 1** on algorithm 1 converge the fastest.
- (3) The sequences  $\mu_n = \frac{1}{(n+1)^2} - \frac{1}{(n+1)^4}$  and  $\beta_n = 1 - \frac{1}{(n+1)^2}$  with  $\mu_n + \beta_n \leq 1$  satisfy the conditions (ii), (iii) in Theorem 3.1.
- (4) From the discussion of Table 4, we see that the sequences  $\{x_n\}$  and  $\{y_n\}$  in **Choice 1** on algorithm 1 converge the fastest and the least time.

Next, we use the Algorithm 2 in Theorem 4.2 to solve a system of linear equations. Systems of linear equations are used in a wide range of fields, including traffic analysis, economics, and electrical engineering.

**Example 5.2.** We assume that  $H_1 = H_2 = \mathbb{R}^4$ . Solving a system of linear equations  $A_i x = b_i$  for all  $i = 1, 2$ . In the following, we take:

$$A_1 = \begin{pmatrix} 2 & -1 & 3 & -1 \\ 1 & -2 & 1 & -3 \\ 2 & -1 & -1 & 1 \\ 2 & 0 & -2 & 3 \end{pmatrix}, b_1 = \begin{pmatrix} 1 \\ -15 \\ 7 \\ 10 \end{pmatrix}$$

and

$$A_2 = \begin{pmatrix} -1 & -3 & 0 & -3 \\ 1 & -1 & 2 & -2 \\ 1 & 2 & 1 & 0 \\ 2 & -2 & 8 & 6 \end{pmatrix}, b_2 = \begin{pmatrix} -22 \\ -6 \\ 9 \\ 36 \end{pmatrix}.$$

Then the split feasibility problem can be formulated as the problem of finding a point  $x^*$  with the property  $x^* \in C$  and  $A_i x^* \in Q$ , where  $C = \mathbb{R}^4$ ,  $Q = \{b_i\}$ , for all  $i = 1, 2$ . That is,

$\mathbf{x}^*$  is the solution of the system of linear equations  $A_i\mathbf{x} = b_i$ , and

$$\mathbf{x}^* = \begin{pmatrix} 1 \\ 3 \\ 2 \\ 4 \end{pmatrix}.$$

For every  $i = 1, 2$ , we take the operator  $\xi_i : \mathbb{R}^4 \rightarrow \mathbb{R}^4$  to be defined as  $\xi_1(\mathbf{x}) = \frac{\mathbf{x}}{49}$  and  $\xi_2(\mathbf{x}) = \frac{\mathbf{x}}{64}$ . In Algorithm 2, choose  $\alpha_n = \frac{1}{5n}$ ,  $\mu_n = \frac{1}{(n+1)^2} - \frac{1}{(n+1)^4}$  and  $\beta_n = 1 - \frac{1}{(n+1)^2}$  for all  $n \in \mathbb{N}$ . So our Algorithm 2 becomes

$$(5.53) \quad \begin{cases} \mathbf{v}_n = \mathbf{y}_n - \frac{1}{100} A_2^*(I - P_Q) A_2 \mathbf{y}_n \\ \mathbf{u}_n = \mathbf{x}_n - \frac{2}{100} A_1^*(I - P_Q) A_1 \mathbf{x}_n \\ \mathbf{y}_{n+1} = \left( \frac{1}{(n+1)^2} - \frac{1}{(n+1)^4} \right) \mathbf{y}_n + \left( 1 - \frac{1}{(n+1)^2} \right) \left( \frac{1}{5n} \xi_2(\mathbf{x}_n) + \left( 1 - \frac{1}{5n} \right) \mathbf{v}_n \right) \\ \mathbf{x}_{n+1} = \left( \frac{1}{(n+1)^2} - \frac{1}{(n+1)^4} \right) \mathbf{x}_n + \left( 1 - \frac{1}{(n+1)^2} \right) \left( \frac{1}{5n} \xi_1(\mathbf{y}_n) + \left( 1 - \frac{1}{5n} \right) \mathbf{u}_n \right). \end{cases}$$

According to the definition of  $A_i$ , for all  $i = 1, 2$ , then the solution of the problem is  $\mathbf{x}^* = (1, 3, 2, 4)^T$ . From Theorem 4.2, we can conclude that the sequences  $x_n$  and  $y_n$  converge strongly to  $\mathbf{x}^*$ . The numerical results, using our Algorithm 2, for the sequences  $\{\mathbf{x}_n\}$  and  $\{\mathbf{y}_n\}$  are reported in Tables 5 and 6.

TABLE 5. The numerical results for the sequence  $\{\mathbf{x}_n\}$  of Example 5.2.

$n$	$\mathbf{x}_n = (x_n^1, x_n^2, x_n^3, x_n^4)^T$	$\ \mathbf{x}_n - \mathbf{x}_{n-1}\ _2$
1	(10, 10, 10, 10)	-
100	(1.01101939, 2.96006399, 1.9079274, 3.93186252)	2.0827e-03
500	(0.99900056, 2.98427758, 1.98454128, 3.9924486)	4.7872e-05
1000	(0.99952084, 2.99227651, 1.99233583, 3.99621442)	1.1675e-05
5000	(0.99990674, 2.99847538, 1.99847759, 3.9992422)	4.5827e-07
10000	(0.99995351, 2.99923891, 1.99923946, 3.99962108)	1.1430e-07

TABLE 6. The numerical results for the sequence  $\{\mathbf{y}_n\}$  of Example 5.2.

$n$	$\mathbf{y}_n = (y_n^1, y_n^2, y_n^3, y_n^4)^T$	$\ \mathbf{y}_n - \mathbf{y}_{n-1}\ _2$
1	(-10, -10, -10, -10)	-
100	(0.74657296, 3.05961817, 2.10596020, 3.95701678)	1.9015e-03
500	(0.97220178, 3.00338976, 2.01114426, 3.99416767)	2.3602e-04
1000	(1.02507278, 2.98613767, 1.98783547, 4.00236647)	5.3877e-05
5000	(1.01697453, 2.99245005, 1.99212248, 4.00209563)	4.7330e-06
10000	(1.00763210, 2.99656705, 1.99645073, 4.00093167)	1.0058e-06

**Remark 5.3.** By testing the convergence behavior of Algorithm 2, we see in Example 5.2 that

- (1) Tables 5 and 6 show that  $\{\mathbf{x}_n\}$  and  $\{\mathbf{y}_n\}$  converge to  $\mathbf{x}^* = (1, 3, 2, 4)^T$ . The convergence of  $\{\mathbf{x}_n\}$  and  $\{\mathbf{y}_n\}$  of Example 5.2 can be guaranteed by Theorem 4.2.
- (2) Tables 5 and 6, we see that  $\mathbf{x}_{10000} = (0.99995351, 2.99923891, 1.99923946, 3.99962108)^T$  is an approximation of the system of linear equations with an error  $1.1430e - 07$  and  $\mathbf{y}_{10000} = (1.00763210, 2.99656705, 1.99645073, 4.00093167)^T$  is an approximation of the system of linear equations with an error  $1.0058e - 06$ , respectively.

## 6. CONCLUSION

In this paper, we introduce an intermixed algorithm with viscosity technique for solving a common fixed point of two proximal operators in a real Hilbert space. The strong convergence theorem of our proposed algorithm, Theorem 3.1, has been established and proven under some mild conditions. However, we should like remark the following:

- (1) We modify the results of Yao et al.[32] from strict pseudo-contraction mappings to proximal operators of in Hilbert spaces. Further, we also give the new mathematical tool related to proximal operators by using the concept of the convex minimization problem and the fixed point equation (1.2) (see Lemma 2.4).
- (2) Our result is proved with a new assumption on the control conditions  $\{\mu_n\}$  and  $\{\beta_n\}$  such that  $\mu_n + \beta_n \leq 1$ .
- (3) We apply our theorem to solve the split feasibility problem by using an intermixed algorithm with viscosity technique.
- (4) We give a numerical example that shows the efficiency and implementation of our main result in the space  $L_2$  as shown in Example 5.1. Moreover, we present a numerical example of the algorithm 2 for solving the system of linear equations in Example 5.2.

**Acknowledgments.** W. Khuangsatung would like to The first author would like to thank Rajamangala University of Technology Thanyaburi (RMUTT) under The Science, Research and Innovation Promotion Funding (TSRI) (Contract No. FRB660012/0168 and under project number FRB66E0635) for financial support.

## REFERENCES

- [1] Abbas, M.; AlShahrani, M.; Ansari, Q. H. et al.: Iterative methods for solving proximal split minimization problems. *Numer Algor* **78** (2018), 193–215.
- [2] Bauschke, H. H.; Combettes, P. L. *Convex Analysis and Monotone Operators Theory in Hilbert Spaces*. CMS Books in Mathematics. Springer-Verlag, second edition (2017).
- [3] Combettes, P. L.; Pesquet, J. C. *Proximal splitting methods in signal processing*. In: Fixed-Point Algorithms for Inverse Problems in Science and Engineering, 185–212. Springer, Berlin (2011).
- [4] Combettes, L.; Wajs, V. R. Signal recovery by proximal forward-backward splitting. *Multiscale Model. Simul.* **4** (2005), 1168–1200.
- [5] Censor, Y.; Elfving, T. A multiprojection algorithm using Bregman projections in a product space. *Numer. Algorith.* **8** (1994), 221–239.
- [6] Ceng, L. C.; Ansari, Q. H.; Yao, J. C. An extragradient method for solving split feasibility and fixed point problems. *Comput. Math. Appl.* **64** (2012), 633–642.
- [7] Dong, Y. New inertial factors of the Krasnoselskii-Mann iteration. *Set-Valued Var. Anal.* **29** (2021), 145–161.
- [8] Guo, Y.; Cui, W. Strong convergence and bounded perturbation resilience of a modified proximal gradient algorithm. *J Inequal Appl.* **2018** (2018), 103.
- [9] Iyiola, O. S.; Shehu, Y. New Convergence Results for Inertial Krasnoselskii–Mann Iterations in Hilbert Spaces with Applications. *Results Math.* **76** (2021), 75.
- [10] Jolaoso, L. O.; Abass, H. A. A viscosity-proximal gradient method with inertial extrapolation for solving certain minimization problems in Hilbert space. *Arch Math.* **55** (2019), no. 3, 167–194.



- [11] Jolaoso, L. O.; Ogbuisi, F.; Mewomo, O. An intermixed algorithm for two strict pseudocontractions in  $q$ -uniformly smooth Banach space. *Nonlinear Studies*. **26** (2019), no. 1, 27–41.
- [12] Kanzow, C.; Shehu, Y. Generalized Krasnoselskii-Mann-type iterations for nonexpansive mappings in Hilbert spaces. *Comput. Optim. Appl.* **67** (2017), 595–620.
- [13] Khuangsatung, W.; Jailoka, P.; Suantai, S. An iterative method for solving proximal split feasibility problems and fixed point problems. *Comp. Appl. Math.* **38** (2019), 177.
- [14] Kesornprom, S.; Cholamjiak, P. A modified inertial proximal gradient method for minimization problems and applications. *AIMS Mathematics*. **7** (2022), no. 5, 8147–8161.
- [15] Krasnoselskii, M. A. Two remarks on the method of successive approximations. *Uspekhi Mat. Nauk.* **10** (1955), 123–127.
- [16] Mann, W. R. Mean value methods in iteration. *Bull. Amer. Math. Soc.* **4** (1953), 506–510.
- [17] Maingé, P.E. Approximation methods for common fixed points of nonexpansive mappings in Hilbert spaces. *J. Math. Anal. Appl.* **325** (2007), no. 1, 469–479.
- [18] Ming, T.; Liu, L. General iterative methods for equilibrium and constrained convex minimization problem. *J. Optim. Theory Appl.* **63** (2014), 1367–1385.
- [19] Moudafi, A.; Thakur, B. S. Solving proximal split feasibility problems without prior knowledge of operator norms. *Optim Lett.* **8** (2014), 2099–2110.
- [20] Pakkaranang, N.; Kumam, P.; Berinde, V.; Suleiman, Y. I. Superiorization methodology and perturbation resilience of inertial proximal gradient algorithm with application to signal recovery. *J Supercomput.* **76** (2020), 9456–9477.
- [21] Reich, S. Weak convergence theorems for nonexpansive mappings in Banach spaces. *J. Math. Anal. Appl.* **67** (1979), 274–276.
- [22] Sahu, D. R.; Yao, J. C.; Verma, M.; Shukla, K. K. Convergence rate analysis of proximal gradient methods with applications to composite minimization problems. *Optimization*. **70** (2021), no. 1, 75–100.
- [23] Saechou, K.; Kangtunyakarn, A. Modified intermixed iteration for solving the split general system of variational inequality problems and applications. *Comp. Appl. Math.* **40** (2021), 264.
- [24] Shehu, Y. Convergence rate analysis of inertial Krasnoselskii-mann type iteration with applications. *Numer. Funct. Anal. Optim.* **39** (2018), no. 10, 1077–1091.
- [25] Suantai, S.; Jailoka, P.; Hanjing, A. An accelerated viscosity forward-backward splitting algorithm with helinesearch process for convex minimization problems. *J Inequal Appl.* **2021** (2021), 42.
- [26] Sripattanet, A.; Kangtunyakarn, A. Convergence theorem for solving a new concept of the split variational inequality problems and application. *RACSAM*. **114** (2020), 177.
- [27] Thongpaen P.; Wattanataweekul R. A fast fixed-point algorithm for convex minimization problems and its application in image restoration problems. *Mathematics*. **9** (2021), no. 20, 2619.
- [28] Wairojana, N.; Pakkaranang, N.; Uddin, I.; Kumam, P.; Awwal A. M. Modified proximal point algorithms involving convex combination technique for solving minimization problems with convergence analysis. *Optimization*. **69**:(7-8) (2020), 1655–1680.
- [29] Xu, H. K. Properties and iterative methods for the lasso and its variants. *Chin. Ann. Math. Ser.* **B35** (2014), no. 3, 501–518.
- [30] Xu, H. K. Iterative algorithms for nonlinear operators. *J. Lond. Math. Soc.* **66** (2002), no. 1, 240–256.
- [31] Xu, H. K. Viscosity approximation methods for non-expansive mappings. *J. Math. Anal. Appl.* **298** (2004), 279–291.
- [32] Yao, Z.; Kang, S. M.; Li, H. J. An intermixed algorithm for strict pseudo-contractions in Hilbert spaces. *Fixed Point Theory and Appl.* **2015**, 206 (2015).
- [33] Zhang, Y. C.; Guo, K.; Wang, T. Generalized Krasnoselskii-Mann-Type Iteration for Nonexpansive Mappings in Banach Spaces. *J. Oper. Res. Soc. China*. **9** (2021), 195–206.

<sup>1</sup>DEPARTMENT OF MATHEMATICS AND COMPUTER SCIENCE  
FACULTY OF SCIENCE AND TECHNOLOGY  
RAJAMANGALA UNIVERSITY OF TECHNOLOGY THANYABURI  
PATHUMTHANI 12110, THAILAND  
Email address: wongvisarut\_k@rmutt.ac.th

<sup>2</sup>DEPARTMENT OF MATHEMATICS, SCHOOL OF SCIENCE  
KING MONGKUT'S INSTITUTE OF TECHNOLOGY LADKRABANG  
BANGKOK 10520, THAILAND  
Email address: beawrock@hotmail.com